## CHORD and HIRAX Instrumentation & Calibration

H. Cynthia Chiang McGill University

Swiss SKA Days 6 September 2023 Big bang, inflation

Formation of CMB

Dark ages

Cosmic dawn

Reionization

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Structure growth

Dark energy domination



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N.F.POO

50

×Z,

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**CHORD** 300-1500 MHz III FIOO

50

S.

**HIRAX** 400-800 MHz

## Baryon acoustic oscillations

Galaxy positions "remember" acoustic waves from the early universe

Sound horizon sets ~150 Mpc scale: use as a ruler for charting expansion rate and catching dark energy in the act

We need lots of volume for cosmology: use intensity mapping to measure aggregate line emission





## Required specs for BAO intensity mapping



- Maximize sensitivity on scales of interest → Use compact array geometry
- Redshift range of interest: 0.8 < z < 2.5 to capture dark energy domination at  $z \sim 2$  $\rightarrow$  Required frequencies: 400 – 800 MHz
- BAO 150 Mpc angular scale: 3 1.3 degrees at 0.8 < z < 2.5→ Required baseline lengths: 15 – 60 meters
- BAO scale along line of sight: 20 12 MHz at 0.8 < z < 2.5→ Required freq resolution: minimum ~100 channels, more for foregrounds and higher order peaks
- BAO signal level: ~0.1 mK → Low system temperature, large collecting area

## CHORD and HIRAX



CHORD Site: DRAO, Canada Dishes: 512 core + 128 outriggers Frequencies: 300 – 1500 MHz

#### HIRAX

Site: Karoo desert, South Africa

Dishes: 256 core + TBD outriggers

Frequencies: 400 – 800 MHz



## The need for "redundancy"



Milky Way is 1000 x brighter than BAO signal, and we don't have a model that's good to 1 part in 1000





Calibration depends on identical baselines seeing the same signal

Within a few days, need to average visibilities, otherwise we have 50-100 Tb/day data

Gain calibration: more instrumental imperfections mean solving/saving a more complicated sky model. Non-redundancies bleed foregrounds into visibility averages, corrupting data.

#### Post-calibration isn't good enough: we need up-front control

1) Define specifications using cosmology forecasts and instrument sims

2) Build instrumentation that meets the required tolerances

3) Verify that the instrumentation meets the required tolerances

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- Sliding scale in trading degraded redundancy for increased computation/data storage
- Complex dependencies between top-level and downstream requirements
- Mechanical realities may push back on top-level requirements
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- Precision matters much more than accuracy
- Keeping costs down is important for large arrays

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4) Rejoice in your experimental victory Lose sleep while repeating all the above

## Defining specifications: HIRAX example

Cosmological forecasts: dark energy FOM target ~270–335, Bull et al. 2015 Fisher formalism + Shaw et al. 2015 foreground model, with Planck 2018 priors

- Range of k<sub>⊥</sub>: 0.05–0.16 Mpc<sup>-1</sup>
- Range of k<sub>1</sub>: 0.03–0.2 Mpc<sup>-1</sup>
- 21-cm power spectrum relative sensitivity, median across scales: <0.8%
- Array level calibration target: <0.3%</p>

#### Define system requirements

- Primary beam: consistent to a few parts in 1000 relative to the average integrated beam
- Pointing and positioning:
  - Beam centroid pointing vectors must be parallel within 5 arcmin RMS
  - Foci of all dishes must lie in a plane with 5 mm RMS deviation orthogonal to plane
  - Foci must form a regularly spaced grid with separation distances precise to 2.5 mm RMS

#### **Telescope requirements**

- Over 60 separate requirements for receiver support, dish, mount, foundation, etc.
- Pointing/positioning error analyzed with geometric model to compute error stackup
- Beam errors: CST simulations

## Defining specifications: HIRAX example

Fiducial beam with no systematics



Analysis: D. Crichton, K. Gerodias, E. Pieters, B. Saliwanchik

## Defining specifications: HIRAX example

HIRAX feed position spec: 0.5 mm RMS



Analysis: D. Crichton, K. Gerodias, E. Pieters, B. Saliwanchik

## Defining specifications: CHORD example



## Building the hardware



Monolithic composite dishes Laser-cut wideband feeds (CHORD) Feed assembly jigs (HIRAX) ...etc.







#### Laser tracker:

- High precision, ~tens of microns
- Measurement density limited only by patience
- Slow, and significant overhead

#### **Photogrammetry:**

- Precision somewhat worse than laser tracker
- Measurement density set by # of targets
- Comparatively fast and easy



#### RMS error: 0.825 mm

#### Laser tracker:

- High precision, ~tens of microns
- Measurement density limited only by patience
- Slow, and significant overhead

#### Photogrammetry:

RMS error: 0.949 mm

- Precision somewhat worse than laser tracker
- Measurement density set by # of targets
- Comparatively fast and easy

#### Analysis: A. Karigiri, M. Islam



Analysis: A. Karigiri, M. Islam



Analysis: A. Karigiri, M. Islam

ar surrace measurements



RMS of difference: 0.210 mm!

Analysis: A. Karigiri, M. Islam



Model discretized dish surface in CST and apply surface variations



Analysis: K. Gerodias

#### Beam difference between perturbed and perfect (but discretized) dish surface



- We see some systematics from discretization, but they're mostly subdominant
- Some of the structure comes from defocusing
- Next steps: pushing simulated beams through cosmological simulations

Analysis: A. Karigiri, K. Gerodias



Reflective surface lies underneath and differs from optical surface measurements









Reflectometer: open cylinder plus test surface forms a resonant cavity

Use TE011 mode

~0.1mm depth precision Qualitative sensitivity to resistivity

> Analysis: E. Pieters, A. Di Nitto, L. Gonzalez Escudero

## Instrument characterization and verification Beam holography



DRAO Galt telescope: our 26-m diameter friend

Track transiting sources and xcorr with CHORD to get 1D

Analysis: D. Wulf, K. Gerodias

800

-1.0

0.8

0.6

0.4

0.2



K. Gerodias, L. Herman



Analysis: E. Kuhn Simulations: B. Saliwanchik

	Laser tracker	Photogrammetry	Reflectometer	Holography	Drone
Distance from dish	0m*	0m*	0m*	Far field	~100m
Meas. time	~Hrs/dish	<hr dish<="" th=""/> <th>~Hrs/dish</th> <th>~Hrs/array</th> <th>~Hrs/array</th>	~Hrs/dish	~Hrs/array	~Hrs/array
Cost	\$\$\$\$	\$\$\$	\$	\$\$ / \$\$\$\$\$	\$\$
1D or 2D	2D	2D	2D	1D (-ish)	2D
Density of points	High	Medium	Low	High (1D)	High
Measurement systematics				•••	•••

\* Need to combine with EM sims

(This table is of course incomplete, and the fun is just starting...)