

Netherlands Institute for Radio Astronomy

# LOFAR: Imaging Pipeline and MSSS

## George Heald CALIM2011, Manchester 26 July 2011

ASTRON is part of the Netherlands Organisation for Scientific Research (NWO)



### Outline



- Recap of the LOFAR Imaging Pipeline flow
  - Practical look at the current status of the components and pipeline, with illustrative examples
  - Plans for short-term improvements
- MSSS the LOFAR Commissioning (LOCo) Survey
  - Review of capabilities
  - Needs and constraints
  - Overview of plans for MSSS



# LOFAR standard imaging pipeline **Vertice AST** (RON



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- Flagging with AOFlagger is now standard, and included in the NDPPP step
- Flag results and statistics seem satisfactory, e.g.:



Processing speed with the new cluster for a 6hr observation:

- 15 minutes LBA (flagging, no averaging)
- 22 minutes HBA (flagging and averaging)

# NDPPP (example 6hr LOFAR HBA) **VOFAR AST**(RON



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### Demixing

 $\mathbf{V}$ 

- Described by van der Tol et al. (2007) IEEE TSP, 55, 4497
- Used as an alternative to direction-dependent gain solutions
- Measured visibility (where an contains phase shift etc):

$$egin{aligned} & \mathbf{\hat{v}} = \mathbf{a}_1 v_1 + \mathbf{a}_2 v_2 + \mathbf{a}_3 v_3 = \left[egin{aligned} & \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 \end{array}
ight] \left[egin{aligned} & v_1 \\ & v_2 \\ & v_3 \end{array}
ight] = \mathbf{Av} \ & \mathbf{v} = \mathbf{A}^{\dagger} \mathbf{\hat{v}} = (\mathbf{A}^{\mathrm{H}} \mathbf{A})^{-1} \mathbf{A}^{\mathrm{H}} \mathbf{\hat{v}} & \overline{v}_i = rac{1}{N_t N_f} \sum_{i=1}^{N_t} \sum_{k=1}^{N_t} a_{ijk}^* \hat{v}_{jk} \end{aligned}$$

Introducing "mixing matrix" M:

$$\mathbf{M} = \left(\frac{1}{N_t N_f} \mathbf{A}^{\mathrm{H}} \mathbf{A}\right)^{-1}$$

Estimated visibility function of source 1, "demixing" 2 and 3:  $v_1 = \overline{v}_1 - M_{1,2} \tilde{v}_2 - M_{1,3} \tilde{v}_3$ 

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### Demixing

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- Demixing algorithm developed by Bas van der Tol is working well
  - Now ~standard for LBA datasets
  - Not typically used (but may be important later?) for HBA
- Speed is a problem:
  - good models of the offaxis sources (though NOT of the target field) are required
  - a significant runtime factor is the time to produce model visibilities [FFT-based model prediction in BBS now a high priority]
- Results are good, when bright offaxis sources are >20 degrees from target field (at ~60 MHz) - more test beams available
- Now implemented as a demonstrator python script, but will soon be added as part of DPPP/BBS for speed

### Demixing: 3C196 LBA\_INNER



#### Demixed CygA, CasA, VirA (latter not necessary in hindsight)



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### 3C196 LBA\_INNER: visibilities





### 3C196 LBA\_INNER: visibilities













#### no demixing

averaged to - one channel - 10 seconds

post-demixing calibration applied before imaging

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with demixing

averaged to - one channel - 10 seconds

post-demixing calibration applied before imaging

no cleaning





#### with demixing

averaged to - one channel - 10 seconds

post-demixing calibration applied before imaging

with cleaning

~100 SQ DEG





no demixing (but using gains obtained postdemixing)

no cleaning

image rms 122 mJy



with demixing (using gains obtained postdemixing)

no cleaning

image rms 66 mJy



with demixing (using gains obtained postdemixing)

(unguided) cleaning

image rms 40 mJy

## Demixing: imaging off-axis sources LOFAR AST (RON

- Hydra A Cas A distance ~ 127 degrees
- Post-demixing images (target = Hydra A):



### Averaging



- After demixing, averaging has been done and the data volume is managable
  - each subband typically reduces to about Δt=10sec, N<sub>ch</sub>=1 (note that such frequency compression will not be suitable for polarization work ...)
  - the compression factor is up to 640 (LBA data compressed to 1ch/SB), but extra columns are added for calibration etc
  - yielding (LBA) data volume decrease from ca. 28 GB to ~214 MB - note HBA\_DUAL is ~4x bigger (both the raw data and the processed data)
  - (for 244 subbands, this means currently ~ 52 GB/6 hr LBA observation, or ~200 GB/6 hr HBA\_DUAL observation)

### Calibration: models



- To begin calibration, either a good field model, or a calibrator gain transfer, is required: correct for clock delays, flux scale
- Currently, catalog extractions (WENSS, VLSS, NVSS) are used to kickstart data calibration. High-resolution images from e.g. VLA (at higher frequencies) are used when available
  - Low resolution models are insufficient to calibrate remote stations in the first pass
    - clean components work better than shapelets or gaussians for extended sources
  - Self-calibration does not work (properly) at this stage due to lack of beam correction in the imaging stage
- Matching resolution is crucial to jumpstarting the calibration cycle on remote baselines



- Example: test transfer from 3C286 to NGC 4631
  - Calibrator-source angular separation ~15 degrees
  - Observation at 150 MHz
  - Bandwidth evenly divided between calibrator and target field
    - same frequencies observed in two directions simultaneously



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#### Gain solutions from 3C286:



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#### Image of NGC 4631 field after applying gains (and nothing else)



### Removing the brightest sources







- Instrumental polarization in the calibrator field reduced from several percent (strongest in Stokes U) to ~noise level
- Application of these gains to target field did *not* eliminate the instrumental polarization
  - found to be due to incorrect HBA tile beam prediction in beam module (used in BBS and awimager)
- Tile beam prediction has been updated, new test planned to check that instrumental polarization can be calibrated out...

### Calibration: LOFAR beams

- LOFAR AST(RON
- For the most part, the beam predictions seem decent but not on all stations - (related to polarization swaps?)



van Zwieten

### Calibration: timing



- Runtimes (on *old* cluster) typically ~30 min / 6hr dataset (after averaging to 10s/1ch; doing (predict), solve, subtract, correct)
- The runtimes increase strongly with extra features
  - Complexity of models: reiterates need for FFT-based predict step!
  - Direction-dependent gain solutions
  - Beam prediction
- Note the need for benchmarks relevant to MSSS-type observations and major cycle characteristics: one reason for MSSS-Test1,2,3 as described later

### Calibration: results

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- After demixing and calibration, clipping and flagging are usually required to eliminate bad corrected visibilities
  - S/N flagging as in casa or AIPS is probably needed
  - Solver statistics are being investigated
- Output images post-calibration are getting closer to thermal noise estimates, but in many fields we are limited to ca. 10-20 times the theoretical thermal limit: (better with awimager??)

### Imaging



- Current development is in the casa suite working on 'awimager'.
  - this is an updated version of the lwimager, taking LOFAR beams into account and doing A-projection
  - development still concluding, with initial test program already in place and being analyzed with simulated data
  - time required for imaging should not much exceed 'normal' widefield imaging in casa, since the calculation of the convolution functions needed for A-projection is not a dominant additional time

### Major cycle

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- To close the major cycle we need a trusted version of the imager that will provide us with confident source positions and fluxes (pre- and post-deconvolution)
- Other basic tools are in place:
  - source finding routines (pybdsm and pyse)
  - database I/O in place and being tested

## Pipeline times (and unknowns...) **Vertices (Section 2017**)

Pipeline overview, and timings of components (example 6hr LBA)



### People working on the SIP



- Many students and postdocs are taking active roles in commissioning the imaging through Busy Weeks and Busy Wednesdays (which are *very* useful...)
- The KSPs have many students and postdocs available now working on imaging developments
- LOFAR Imaging Cookbook in good shape and available online: http://www.astron.nl/radio-observatory/lofar/lofar-imaging-cookbook



### Next (major) steps



- Understand limits of calibrator gain solution transfer
- Continue work on understanding, and speed up, demixing
- Speed up model prediction in BBS
- Commission new imager
  - Give feedback to Beam Team, update beam models, iterate
- Exercise source finders, and test GSM/LSM I/O
- Define major cycle stopping criteria (for abitrary fields...)
- Practice with early MSSS-like observations

### MSSS, AKA LOCo



- MSSS: the LOFAR Commissioning Survey
- Key roles:
  - Fill the initial GSM for calibration of arbitrary fields at arbitrary frequency in LOFAR bands
  - Guide development of & exercise:
    - observatory operations
    - processing software
    - imaging pipeline
    - piggyback applications
- Input from KSPs is being folded into the planning
- Expected survey time ~2-3 months depending on efficiency



Stappers

## Motivations for "core-only" MSSS **W**LOFAR AST(RON

- This really means 3km in HBA; 10km in LBA, which would yield similar characteristic beamsizes in both bands, of ~1.5-2 arcmin (@ 60,150 MHz)
- It also refers more to the (initial) *processing* than to the observations - the plan is to use all (at least all Dutch) available stations
- Key reasons (more on next slide):
  - Beam information is not available (yet) in the imager, so differing HBA station sizes could not be taken into account (this may be a moot point in the near future...)
  - Processing time increases with baseline length, so using a compact array makes real-time processing more realistic

### Benefits of a core-only MSSS



Band & setup	Pros	Cons
MSSS-LBA (CS+RS; baselines ≤ 10km, with multiple snapshots; LBA_INNER)	<ul> <li>Same angular resolution as MSSS-HBA</li> <li>Within a snapshot, the beam variation is minimal</li> <li>No station size (RS-CS) difference</li> <li>Ionosphere minimized</li> </ul>	<ul> <li>Requires multiple snapshots for <i>uv</i> coverage</li> <li>LBA_INNER needs testing</li> </ul>
MSSS-HBA (CS only; single snapshot; HBA_DUAL)	<ul> <li>Obviates need for beam- corrections in imager</li> <li>Good snapshot uv coverage</li> <li>Relatively rapid pipeline processing (<i>needs</i> <i>benchmarking</i>)</li> <li>Within a snapshot, the beam variation is minimal</li> </ul>	<ul> <li>Resolution and sensitivity not competitive for scientific use?</li> </ul>

### **MSSS** Pipeline





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- MSSS-LBA
  - Array configuration: 24 CS + 11 RS (LBA\_INNER)
  - Bandwidth: 16 MHz over 30-78 MHz [coverage uncertain]
  - Number of independent beams: 3
  - Time per field: 90 minutes (9x10 minutes; δHA~0.5h)
  - Resulting sensitivity (approximate): ~15 mJy
  - Required number of fields: 619 (covering 2n sr)
  - Required on-source observing time for full survey:
     619/3x90min = 309.5 hr



- MSSS-HBA
  - Array configuration: 24 CS (HBA\_DUAL?)
  - Bandwidth: 16 MHz over 120-168 MHz [coverage uncertain]
  - Number of independent beams: 3
  - Time per field: 15 minutes
  - Resulting sensitivity (approximate): ~5 mJy
  - Required number of fields: 3522 (covering 2n sr; see above)
  - Required on-source observing time for full survey: 3522/3x15min = 293.5 hr

### Comparison of relevant surveys



Survey	Frequency	Sensitivity	Resolution	Sky coverage
MSSS-LBA (core only)	~30-78 MHz	≲ 15 mJy/beam <sup>1,2</sup>	≲ 100" <sup>1</sup>	20,000 square deg (dec > 0)
VLSS	74 MHz	100 mJy/beam	80"	30,000 square deg (dec > -30)
MSSS-HBA (core only)	~120-170 MHz	≲ 5 mJy/beam <sup>1,2</sup>	≲ 120" <mark>1</mark>	20,000 square deg (dec > 0)
TGSS	140-156 MHz	7-9 mJy/beam	20"	(2100 of) 32,000 square deg (dec > -30)
WENSS	330 MHz	3.6 mJy/beam	54"	10,000 square deg (dec > 30)
NVSS	1400 MHz	0.45 mJy/beam	45"	35,000 square deg (dec > -40)

<sup>1</sup> Conservatively based on short-baseline-only processing; longer baselines will be available <sup>2</sup> MSSS sensitivities to be verified during test observations .... !

### Proposed test pointings

- Each set of pointings covers approx 200 square degrees
- Key is to make these as realistic as possible
  - test, understand, and optimize: data taking, handling, processing, major cycle algorithm, pipeline runtime, catalog creation, etc etc etc



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### Proposed test pointings



Test data processing and output catalogs in three regimes:

- Test1: near bright, simple source (3C196)
  - field already well understood
  - it won't get any easier than this ....
  - also contains another mid-complicated 3C source (3C219) about 10 deg away, so leads to Test2
- Test2: near bright, complicated source (3C465)
  - bright in-field calibrator, but not as simple
  - intermediate case for closing the major cycle
- Test3: blank field (where??)
  - no bright in-field calibrator
  - must understand (blindly) closing the major cycle

### Piggybacking

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- Piggybacking welcomed for at least part of the MSSS area
- Assessment of impact on observing and processing strategy required to ensure that the core MSSS goals are not affected...
- As much as possible, aim to include piggybacking applications in MSSS test observations



### Constraints and output

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- Constraint: minimize survey time (on-telescope and processing)
  - allow maximal amount of other project time
  - avoid tying up resources (cpu, storage) on cluster
  - provide MSSS skymodels for later observations of same area
- Output
  - key deliverable is a wideband catalog of the brightest sources in the LOFAR sky
  - positions, fluxes, source extent and orientation

### Summary



- Calibration of individual LOFAR fields is well in hand
  - Individual components of standard imaging pipeline being commissioned and integrated into automated version
  - New imager is the next big step for us ... it allows proper imaging and to close the (calibration) major cycle
- Major effort now on preparing for MSSS/LOCo
  - Test observations starting
  - Automated pipeline (and kickoff at observatory level) now in active development
  - LOCo will be the first LOFAR survey, and will provide a 20,000 square degree catalog of the 30-180 MHz sky