

# Fringe Fitting in Casa

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# Overview

Introduction to Fringe Fitting

Existing Implementation

Casa Implementation Progress

# Fringe Fitting

- Calibration of variable delay
- Due to atmosphere, geometry, clocks, frequency offsets
- Correlator corrects for predictable effects
- Residual delays require treatment

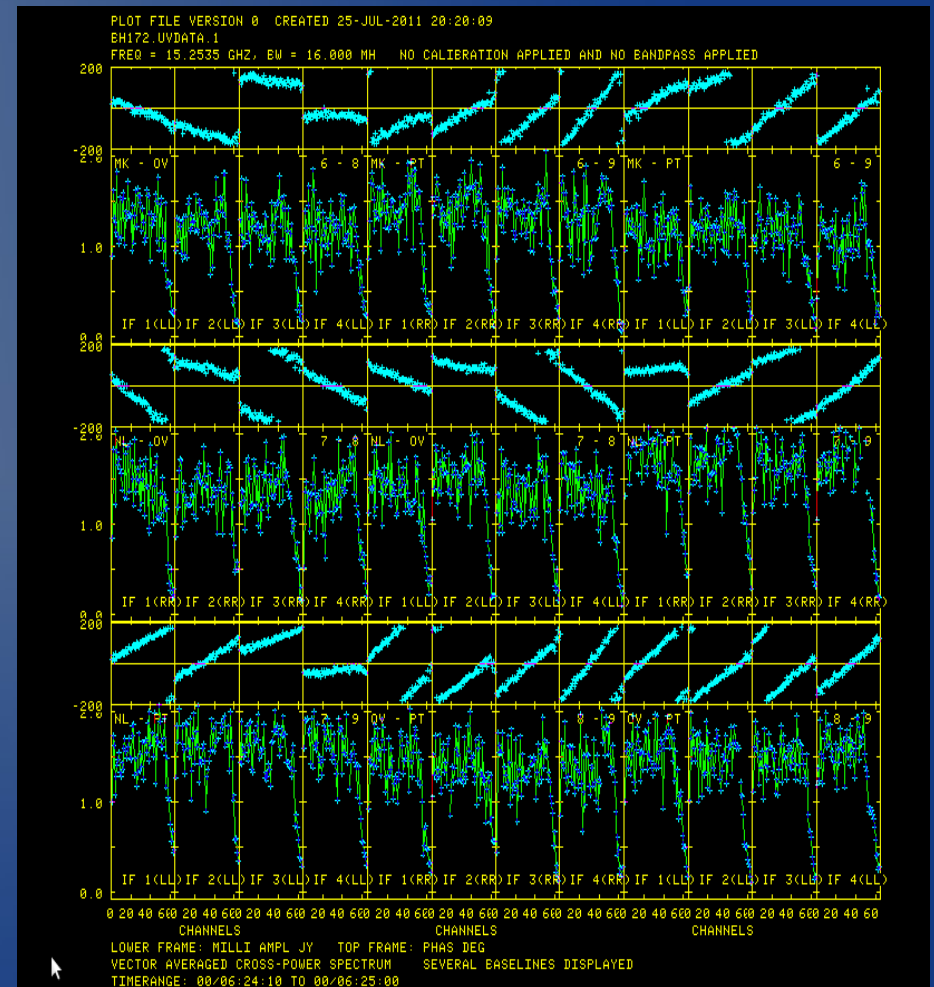
# Delay

- Visibility phase:

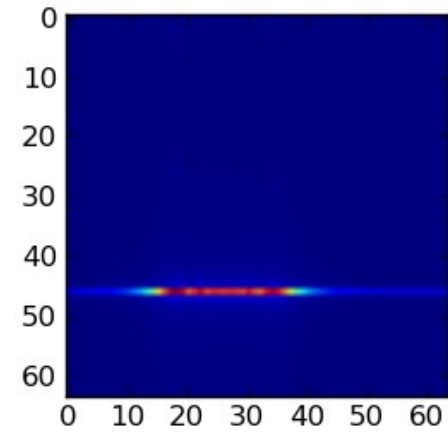
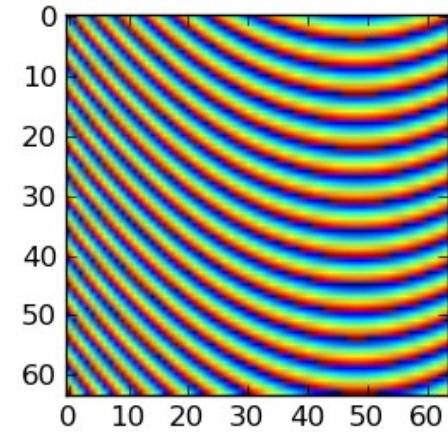
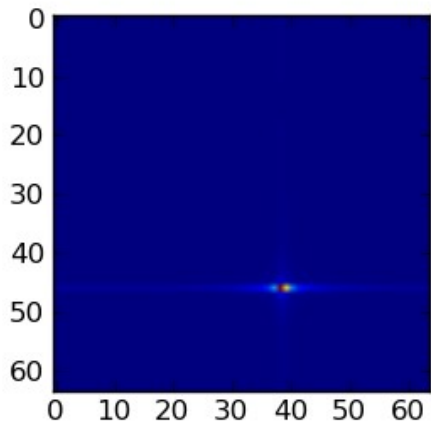
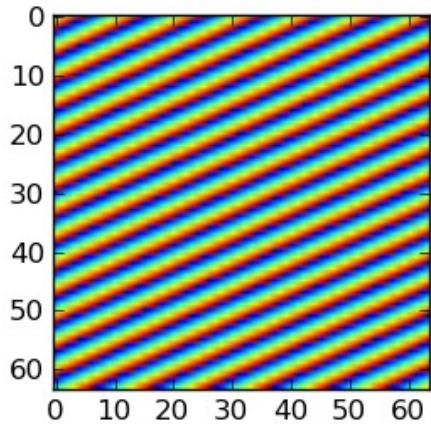
$$\phi_{t,\nu} = 2\pi\nu\tau_t;$$

- First Order Expansion:

$$\Delta\phi_{t,\nu} = \phi_0 + \left( \frac{\partial\phi}{\partial\nu}\Delta\nu + \frac{\partial\phi}{\partial t}\Delta t \right);$$



# Effect on phase



# Standard FF Techniques

- Baseline Based
  - FFT the visibility data
  - Locate peak in delay, fringe rate space
  - Correct phases
  - Advantages:
    - Simple
  - Disadvantages:
    - Need high S/N
    - Does not preserve closure (although it can in some cases)

# Alef, Porcas Method

- Baseline with closure constraints
  - Similar to Baseline based
  - Delay, rate parameters are decomposed to antenna based quantities by a least squares fit
  - Baseline Solutions recalculated from antenna solutions and applied

# Schwab, Cotton Method

- Global Fringe Fitting
  - All data is used in calculating solutions
  - FFT with baseline stacking
    - N-1 stacked baselines
  - Then LSQ fit to parameterisation:

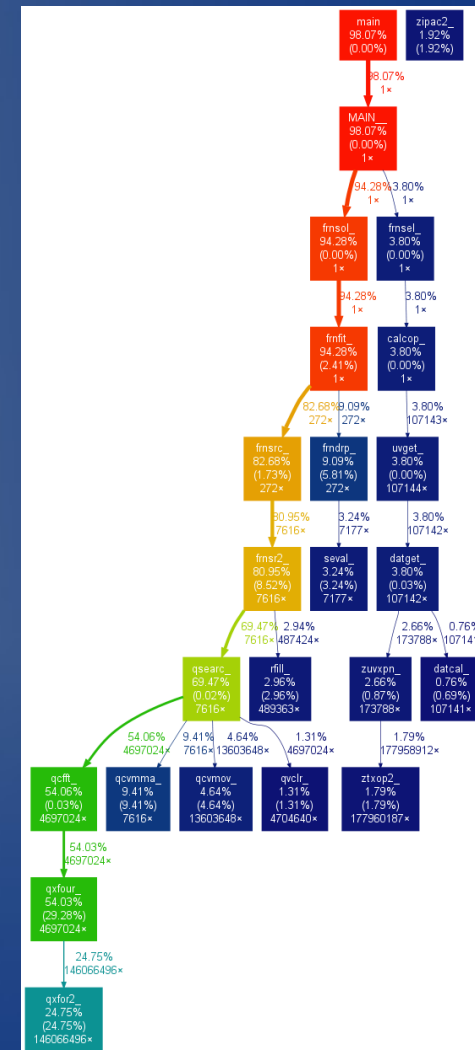
$$S_3(\mathbf{x}) = \sum_{k,l} \sum_{i < j} w_{ijkl} \times | \exp\{i[\tilde{\phi}_{ij}(t_k, \nu_l) - \phi_{ij}(t_k, \nu_l)]\} - E_{ijkl} |^2$$

- Advantages:
  - Most sensitive method
  - Copes well with homogenous arrays
  - Not much slower than other methods
  - Source model is used



# AIPS Implementation

- Read Data
- Divide out model
- Optionally stack baselines
- Zero pad & FFT
- Find delay, rate peaks to reference or all antennas
- Use results to do least squares solution
- Optionally apply to data



# Casa Implementation

- Calibration system is based on ME
- Highly object orientated
- Calibrator tool creates appropriate cal object
- GJones, BJones, **KJones**
- Extend existing calibration class (GJones) and modify selfSolve and applyCal
- Not entirely modular, eg. interpolation

# KJones Implementation

- Initially, delay only
  - Average in time
  - Pad & FFT
  - All baselines to single reference antenna
- Currently working in the KTest class
  - Calculates Delays & Rates
  - Initial baseline stacking code
  - Very early stage of development

# Design

- Abstract FringeEngine class
  - Virtual solveDelay method
  - Can be used in sequence
- Subclasses exist for delay only, delay & rate, by FFT method. LSQ planned.
- KTest object can be setup with a vector of FringeEngines and iterate over them to converge on a solution (at least that's the idea)

# Summary

- Early stages of the implementation
- Casa / Casacore learning curve to overcome
- Framework in place
- Steady progress
- Hope to include a beta or alpha version in next Casa release