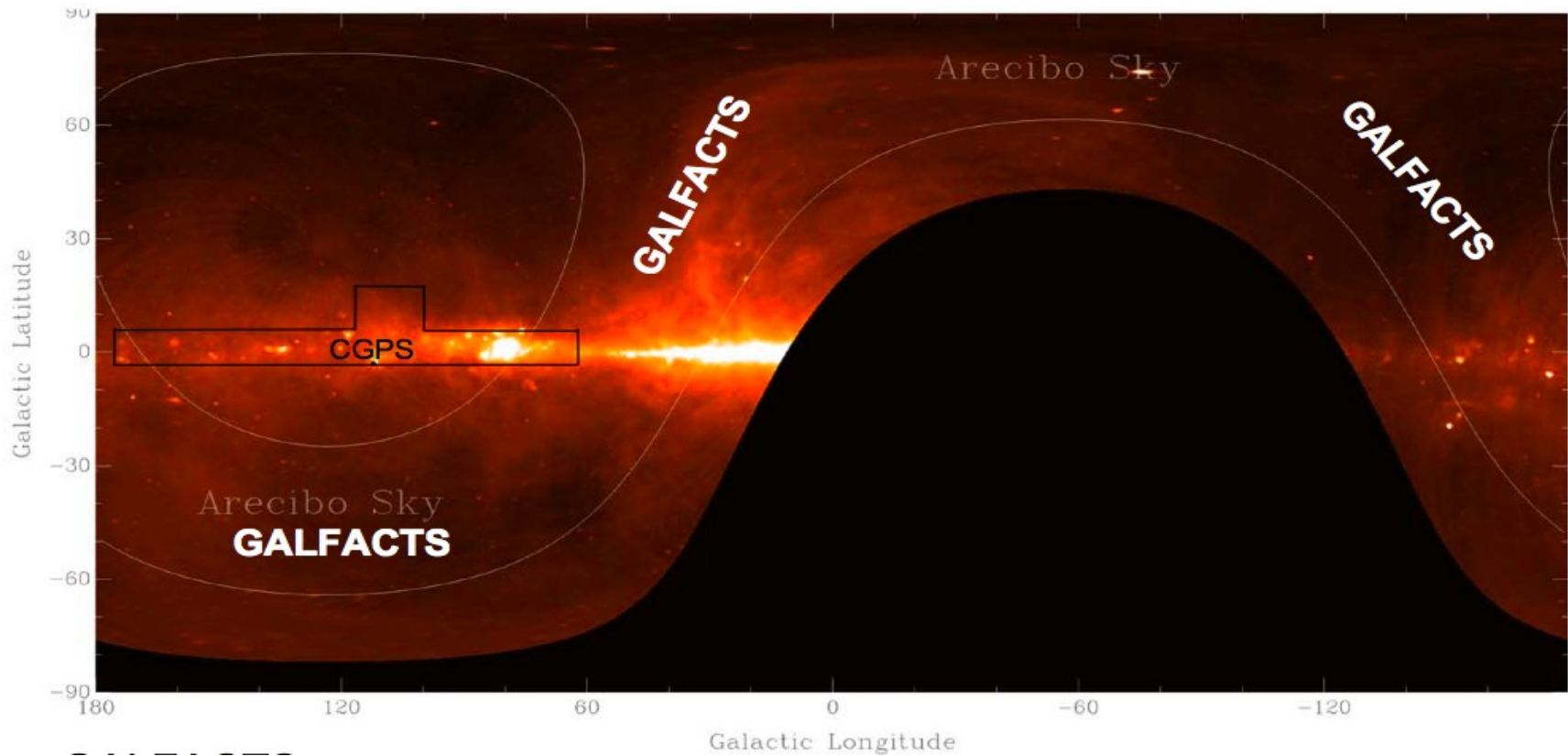


GALFACTS

a large-area spectro-polarimetric survey on Arecibo



Samuel George
University of Cambridge

Galactic **ALFA** Continuum Transit Survey

Taylor & Salter 2011, arxiv.org:1008.4944



www.ras.ucalgary.ca/GALFACTS

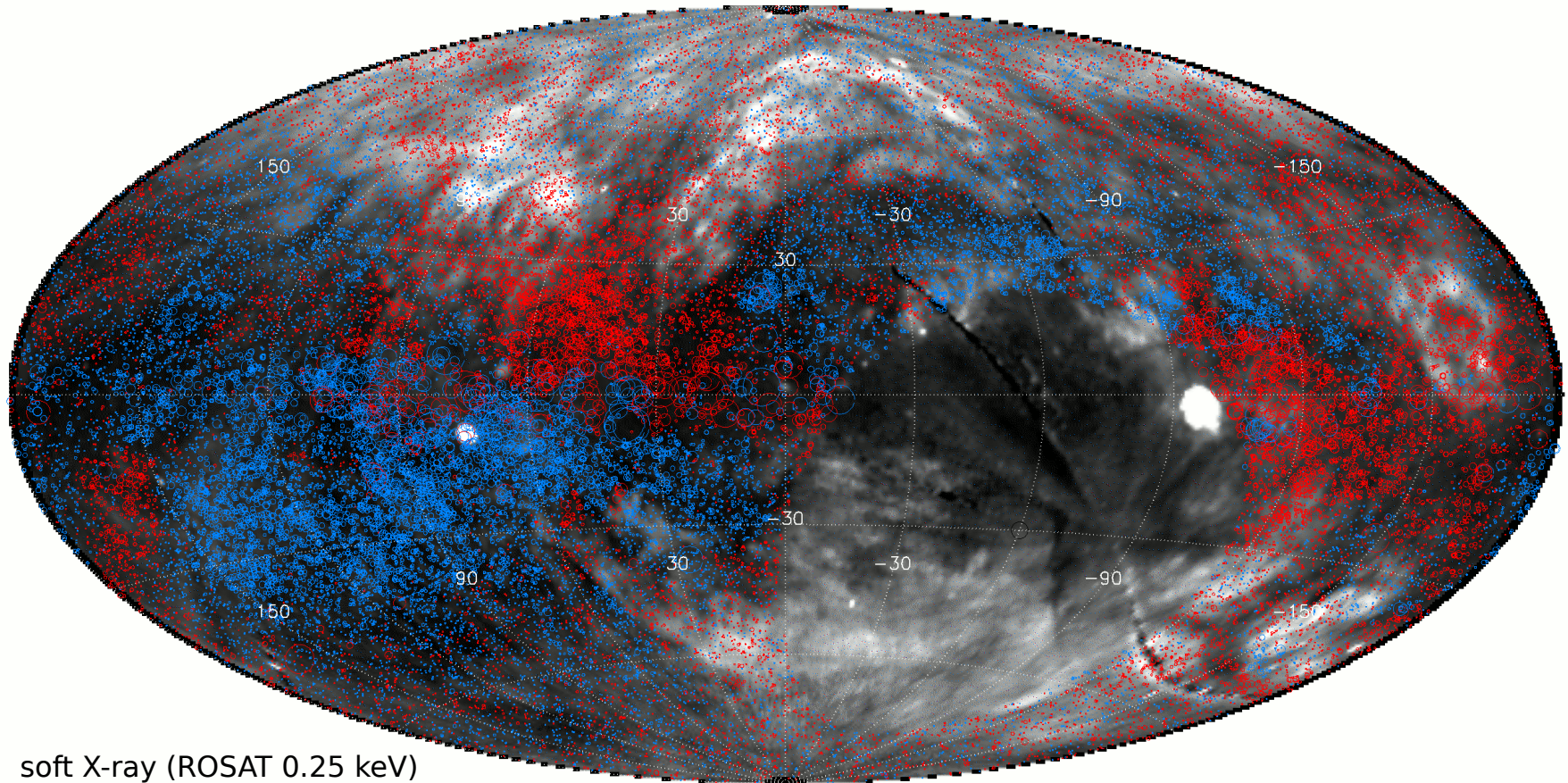
Measuring the Galactic magnetic field and its role in the Galaxy

Image the diffuse polarization in the Galaxy & effects of the Faraday Screen

Polarization properties of the extragalactic source and evolution of magnetism

Scientific pathfinder to SKA Cosmic Magnetism Key Science

Background source RMs trace ISM

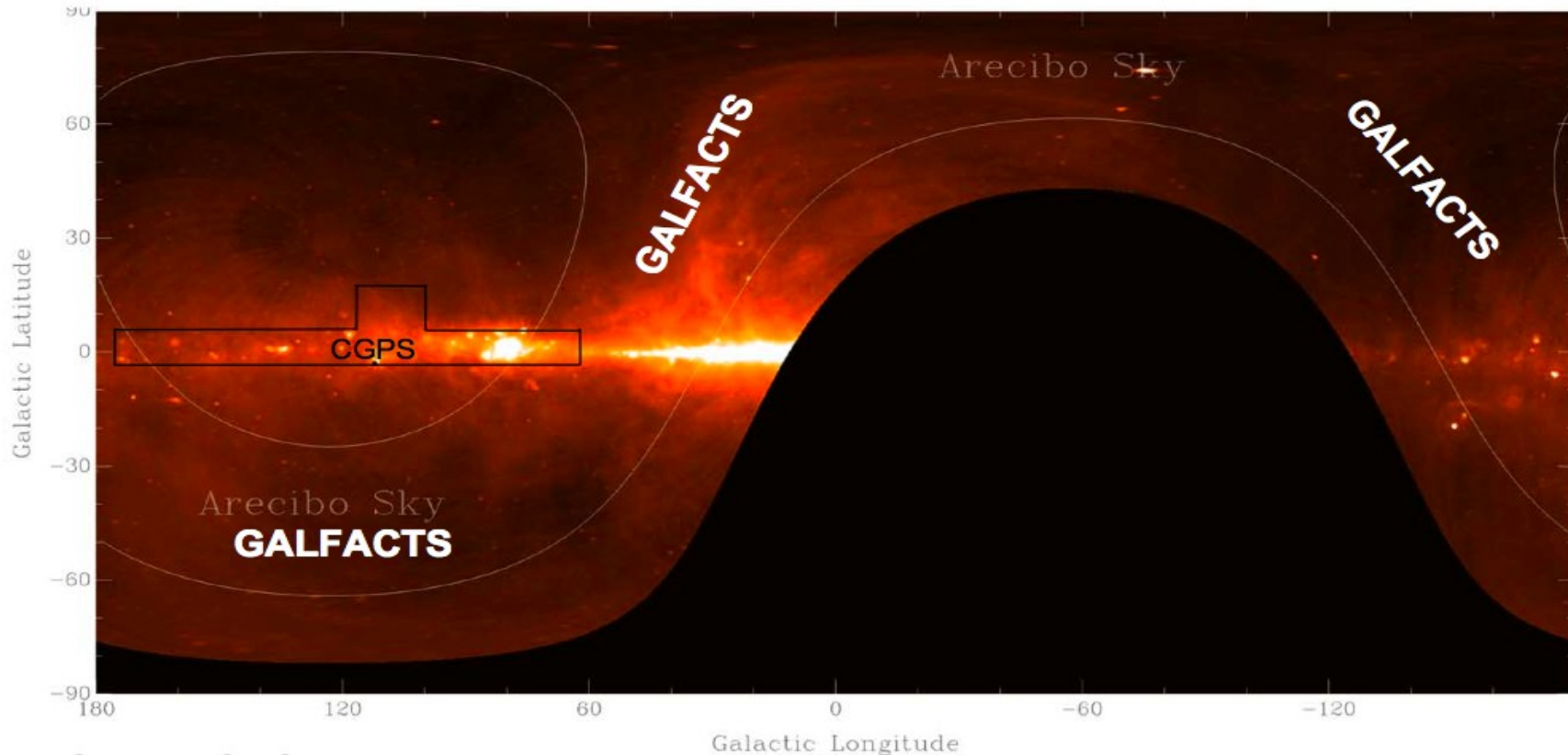


soft X-ray (ROSAT 0.25 keV)

Stil, Taylor & Sunstrum (2011) *ApJ*, 726, 4

GALFACTS

Declination range -0.8-37.8 degrees; 32% sky



8000 channels/300 MHz

3.5' beam; centre 1375MHz; 1ms time sampling

Total observation time ~ 1600 hours.

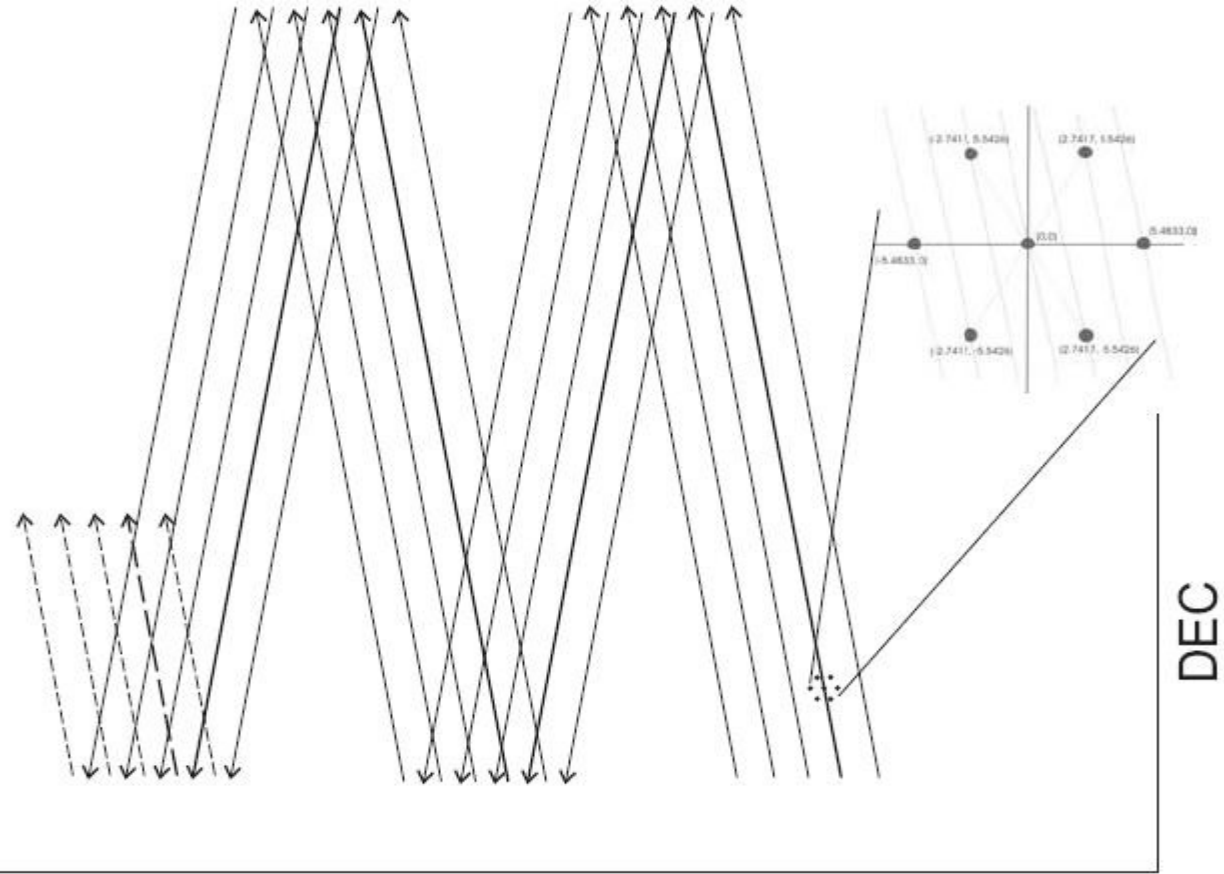
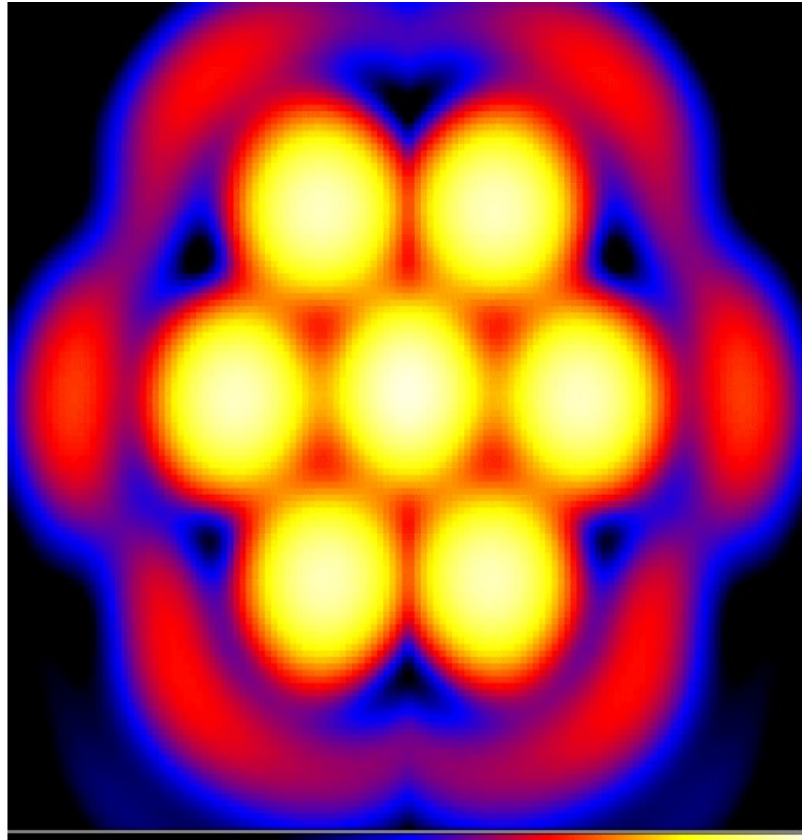
1 sigma Stokes I (all band) 90 microJy

8 runs of 29 day x 6.25 hours (4 North of zenith, 4 South of zenith)

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Observations

Declination range -0.8-37.8 degrees; 32% sky



Scan rate = 1.53 degrees/minute
Track separation = 1.83'

GALFACTS

Data Challenges

Andrecut, Guram, George, Taylor, ADASS 2011

ALFA spectrometer raw data
 ~460MB/s
 ~ 3 Petabytes for full project

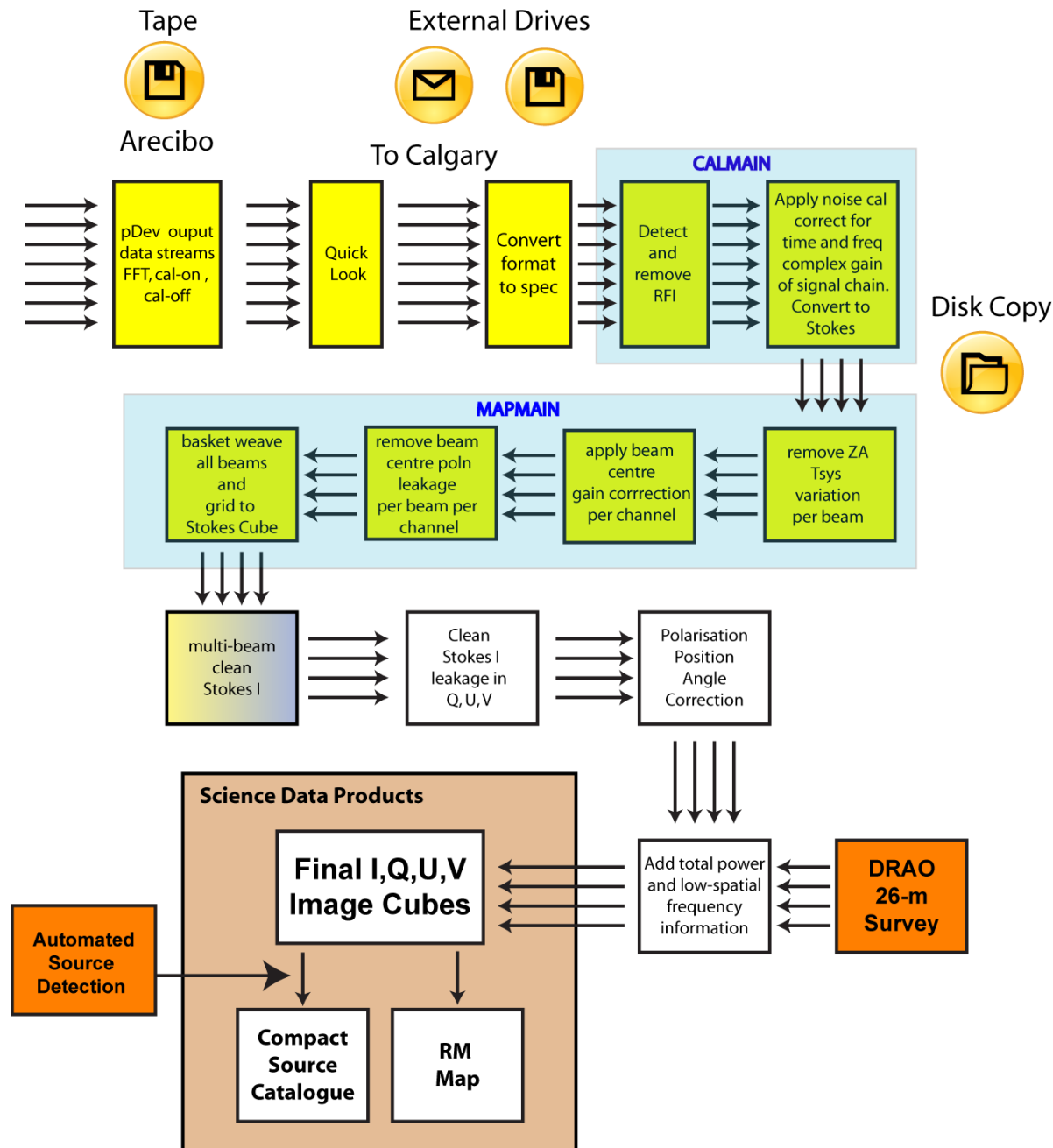
9.9 TB/day reduced to 800 GB/day
 after time/freq decimation at Arecibo

Data is compressed into 2 streams:

- 140TB total frequency averaged
- 40TB total time averaged, 0.2s (5 TB per run)

How do you transport 200TB of data, 25TB at a time, from Puerto Rico to Calgary?

25TB at 1MB/s would take 303 days.

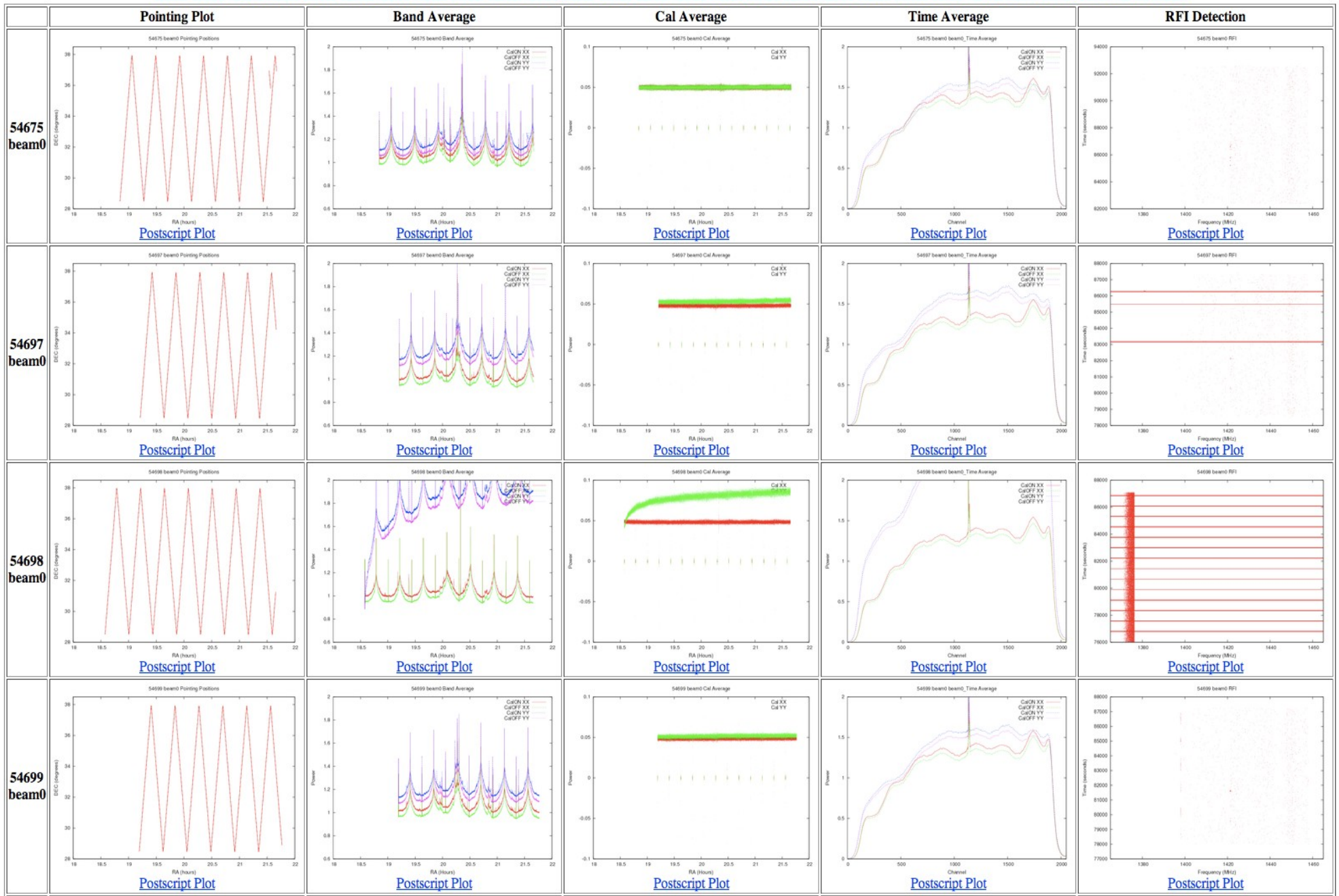


A2186.igalfa_d beam0 WAPPS Data Quality Heuristics

[main](#)

[beam0](#) [beam1](#) [beam2](#) [beam3](#) [beam4](#) [beam5](#) [beam6](#)

[54675](#) [54697](#) [54698](#) [54699](#) [54700](#) [54702](#) [54703](#) [54704](#) [54705](#) [54706](#) [54712](#) [54714](#) [54716](#) [54717](#) [54720](#) [54721](#) [54732](#) [54733](#) [54734](#) [54742](#) [54743](#) [54745](#) [54746](#) [54747](#) [54748](#) [54749](#) [54750](#)



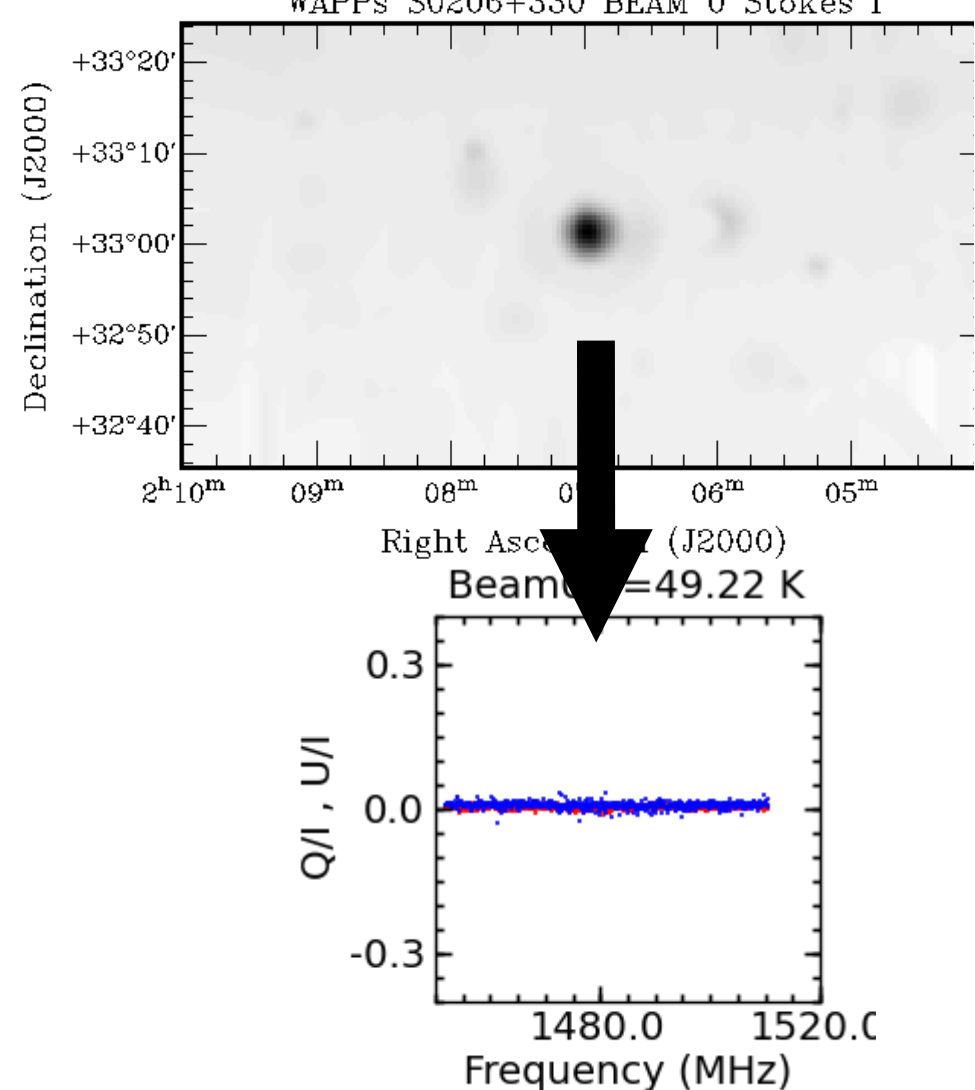
Calibration

High flux density ($S > 500\text{mJy}$)

Small angular size (unresolved with NVSS)

Isolated (6' from nearest NVSS source)

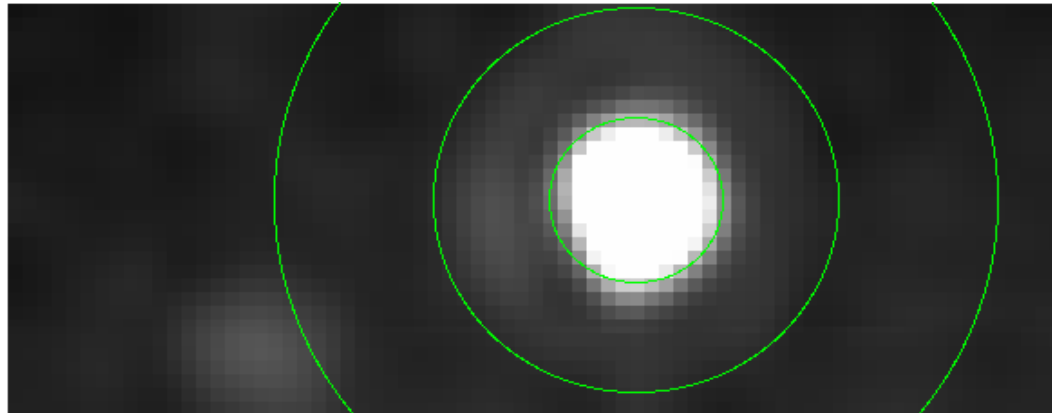
Cover varying declinations



RA	DEC	I_{int} mJy	I_{interr} mJy	P_{int} mJy	P_{interr} mJy	I_{peak} mJy/beam	P_{peak} mJy/beam	% Polar.	Pol. angle deg
02 06 56.65	+33 01 27.7	808.0	24.2	0.38	0.42	791.4	0.48	0.40	81.7
02 17 01.84	+28 04 58.2	1023.5	35.0	11.31	0.50	896.4	9.89	1.10	88.6
02 26 10.34	+34 21 30.4	2894.4	86.8	7.39	0.44	2825.5	7.05	0.25	62.8
02 38 12.44	+27 25 27.1	636.9	19.1	6.63	0.43	624.4	6.39	1.04	11.4
02 50 56.59	+21 21 20.0	819.4	24.6	0.90	0.41	805.5	0.91	0.11	77.9
03 11 35.17	+30 43 20.9	965.6	29.0	4.68	0.42	955.9	4.56	0.48	52.6
03 30 34.79	+36 39 41.2	579.1	17.4	0.70	0.48	564.7	0.74	0.12	-79.2
03 40 08.54	+32 09 01.3	1611.6	50.5	34.31	1.29	935.7	19.59	2.12	-71.1
03 52 33.43	+22 20 20.1	576.6	17.3	18.09	0.43	558.8	17.00	3.14	35.2

Calibration

- For each source/beam and channel fit a Gaussian to the source – embarrassingly parallel
- Three regions used: within beam, 1st side-lobe and some background region
- Background NVSS sources removed
- Return parameters of source



Stokes I image of a typical calibration source.
Shown are the regions used for extraction.

Calibration Output

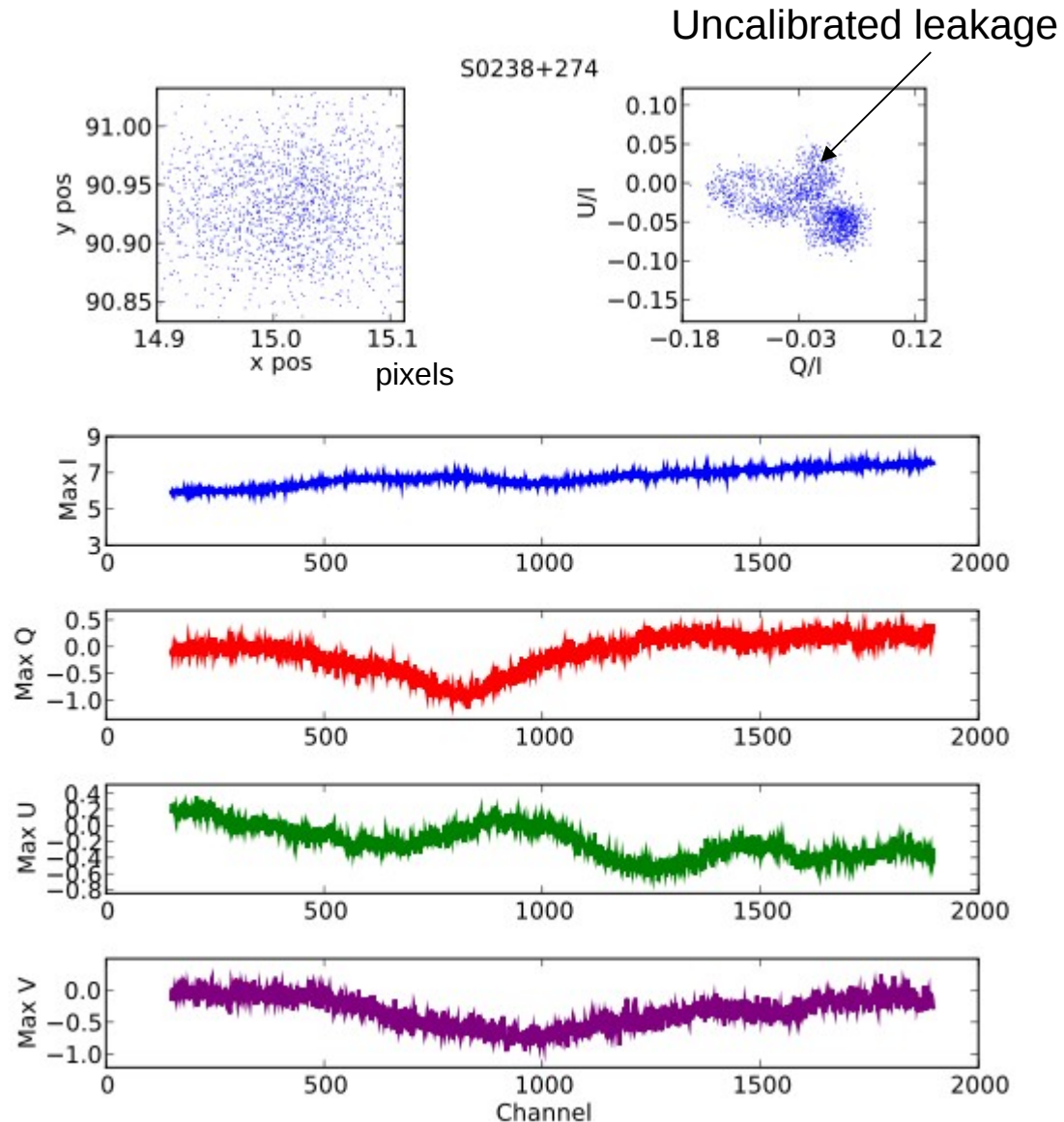
Example of diagnostic plots produced.

Typical of the run 1 MOCK observations and are for S0238+274 (PI =1%) .

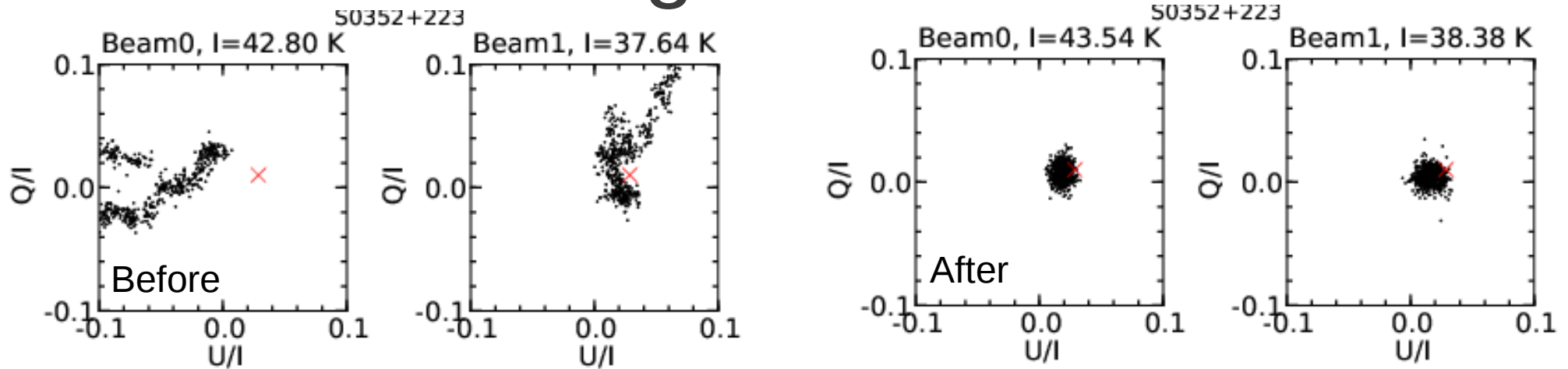
The polarization pattern seen in the U/I vs Q/I plot is due to leakage

Use S0226+343 as a reference source (small P in NVSS) for leakage – remove pattern

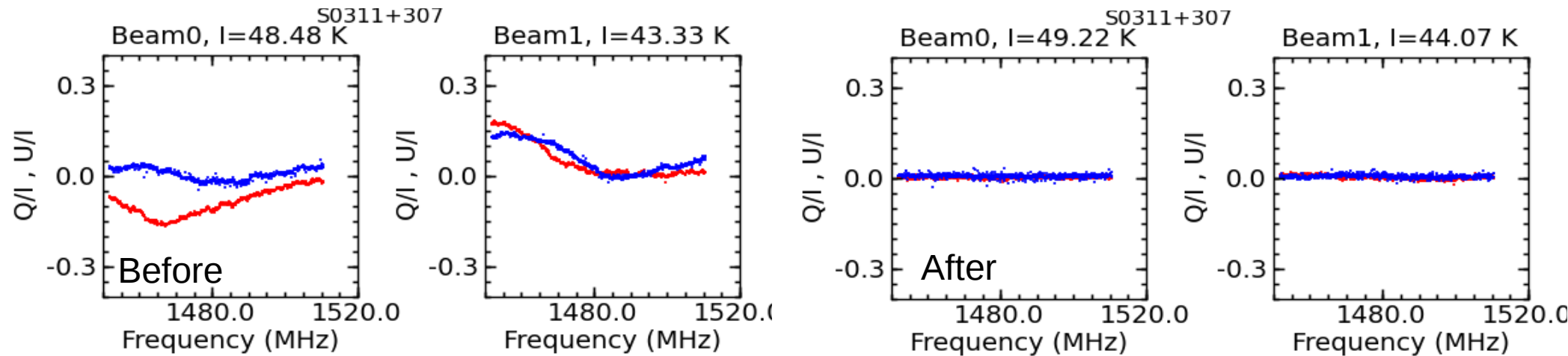
For V perform fit of the V vs I data to derive the leakage



Leakage Correction

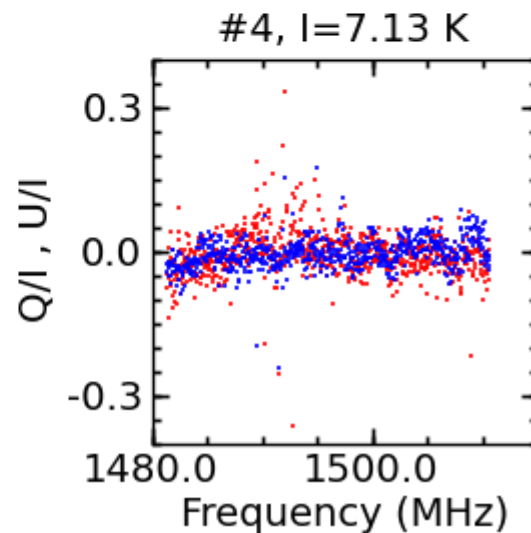
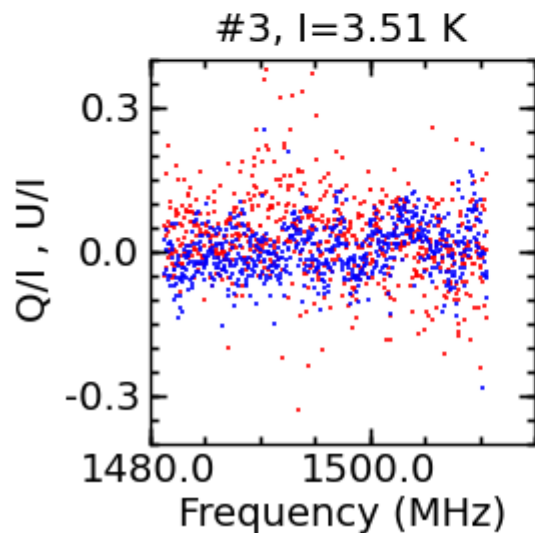
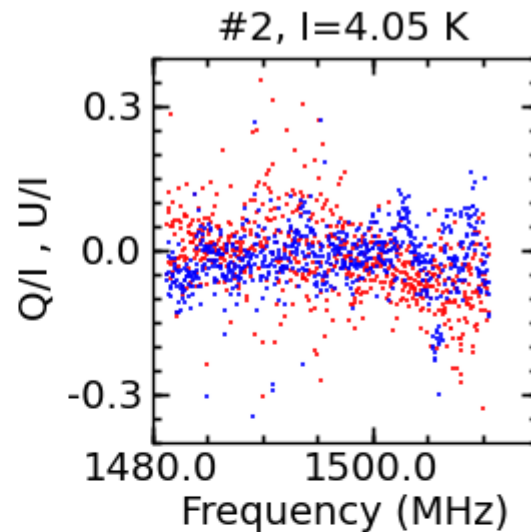
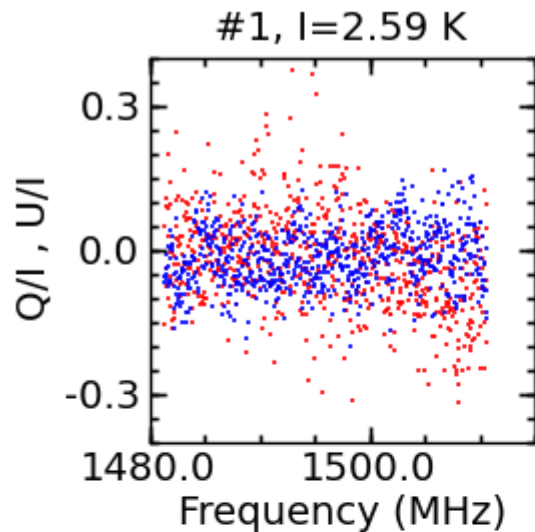


Red cross corresponds to the polarization value determined from the NVSS (PI NVSS = **3.14%**)
Mean distribution over all beams (after cal): PI = **2.41**



red curve U/I blue curve is Q/I

Un-polarized NVSS Sources

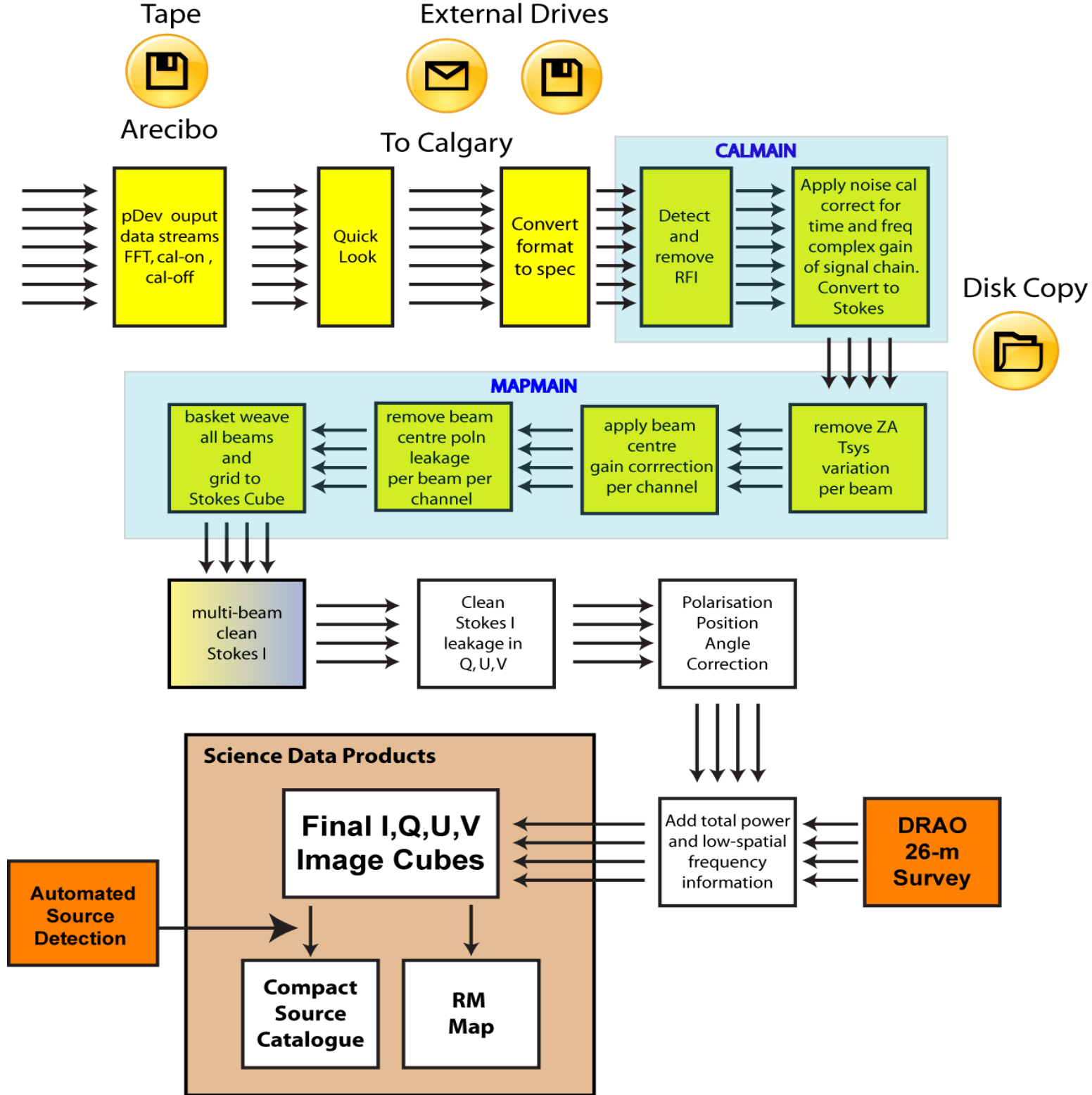


19 unpolarized
Sources in the NVSS
that cover range that
have:

Stokes $I > 200$ mJy
 P (bias cor) < 0.3 mJy

Median $\Pi = 4.46\%$

**Simple leakage
correction not good
enough**



RFI rejection

Frequency Domain

- ▶ Since the goal is to detect channels with large power values, comparing to their neighbors, an obvious strategy is to use first order differences (or equivalently the first derivative) in the frequency domain.
- ▶ At each time t the data is transformed as following:

$$\delta_{n,t} = s_{n+1,t} - s_{n,t}, \quad n = 0, 2, \dots, N - 2.$$

- ▶ The detection method is based on a Gaussian model for the amplitude of the new variable $\delta_{n,t}$.
- ▶ In such a model, one establishes a threshold to distinguish the RFI-contaminated state from the RFI-free state, and the data exceeding some threshold is rejected.
- ▶ The threshold is calculated using an adaptive method.
- ▶ We assume that $f_{n,t}$ is a binary rejection flag, such that $f_{n,t} = \text{TRUE}$ if the data in channel n at time t is bad (RFI-contaminated), and respectively $f_{n,t} = \text{FALSE}$ if the data is good (RFI-free).

RFI rejection

Time Domain

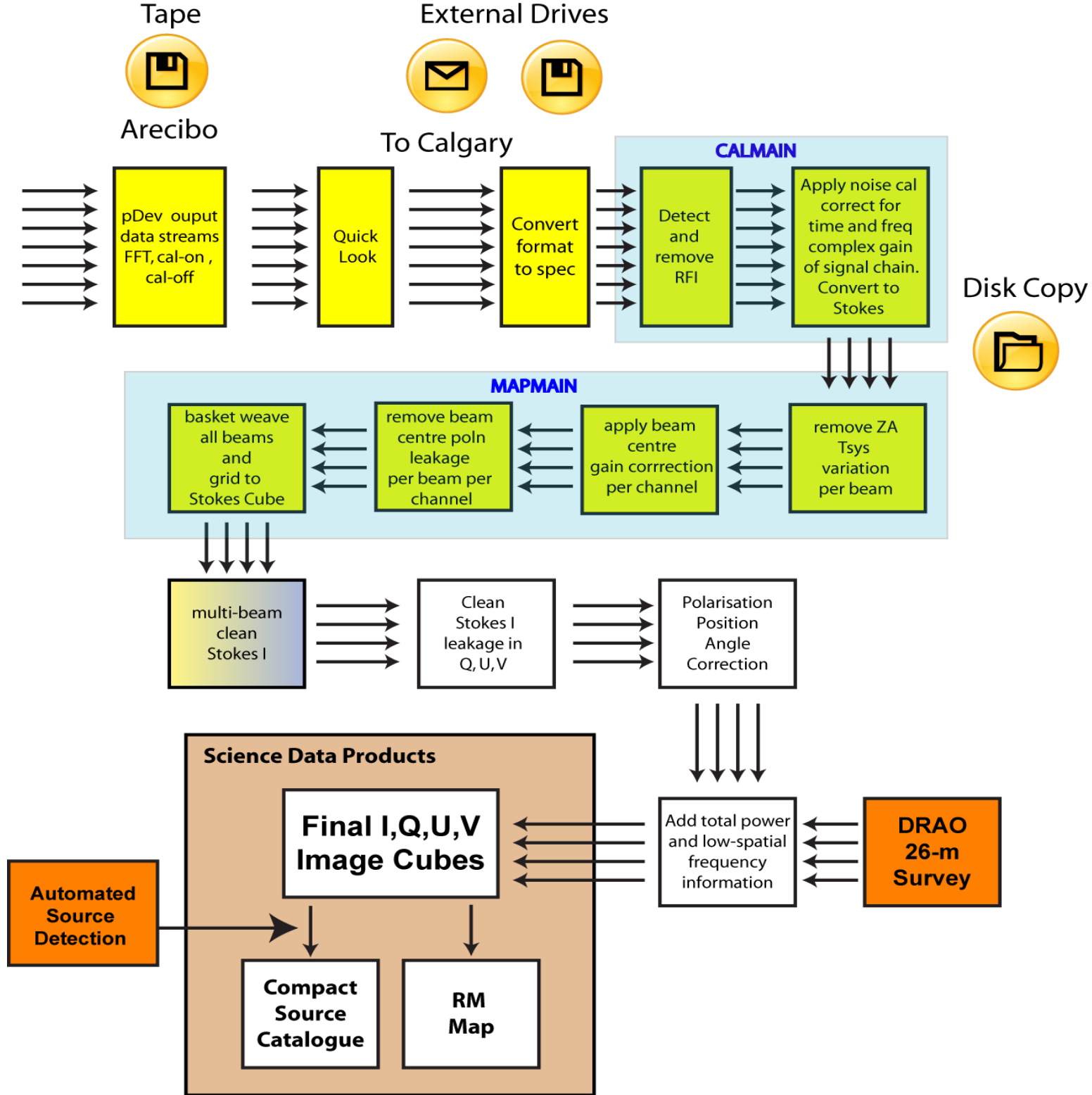
- ▶ The first method uses the standard deviation of the difference signal in frequency domain:

$$\sigma_t = \sqrt{\frac{1}{N-2} \sum_{n=0}^{N-2} (\delta_{n,t} - \mu_t)^2}, \quad t = 0, 1, \dots, T-1.$$

- ▶ The second method works with the band average signal:

$$\mu_t = \frac{1}{N} \sum_{n=0}^{N-1} s_{n,t}, \quad t = 0, 1, \dots, T-1.$$

- ▶ We use the second order differences (or the second derivative), instead of the first order differences.
- ▶ As for the frequency domain, the method assumes a Gaussian model for the new difference variables, and the data exceeding some threshold is rejected.
- ▶ We assume that g_t is a binary rejection flag, such that $g_t = TRUE$ if the data at time t is bad (RFI contaminated), and respectively $g_t = FALSE$ if the data is good.



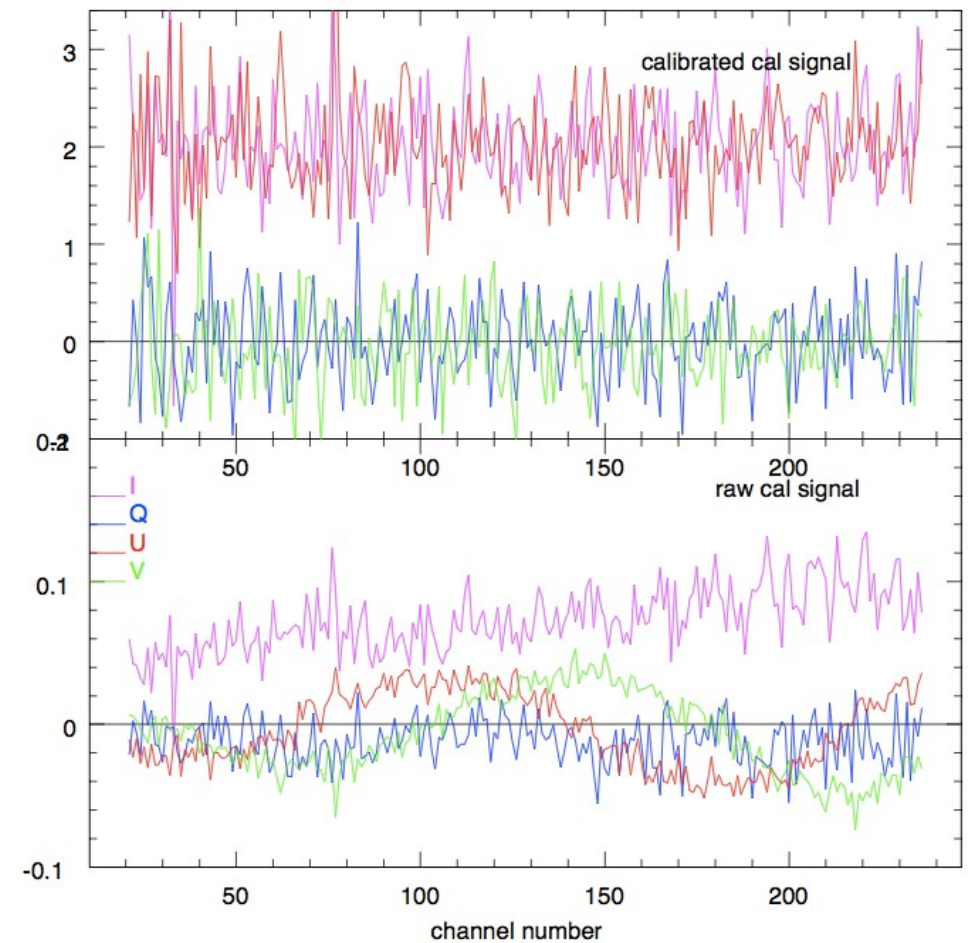
Gain Cal

$$A_I(\nu) = A_{xx} + A_{yy} = \left(G_x(\nu)^2 + G_y(\nu)^2 \right) T_{cal}$$

$$A_Q(\nu) = A_{xx} - A_{yy} = \left(G_x(\nu)^2 - G_y(\nu)^2 \right) T_{cal}$$

$$A_U(\nu) = A_{xy} + A_{yx} = G_x(\nu)G_y(\nu)2T_{cal} \cos \phi(\nu)$$

$$A_V(\nu) = i(A_{xy} - A_{yx}) = G_x(\nu)G_y(\nu)2T_{cal} \sin \phi(\nu)$$



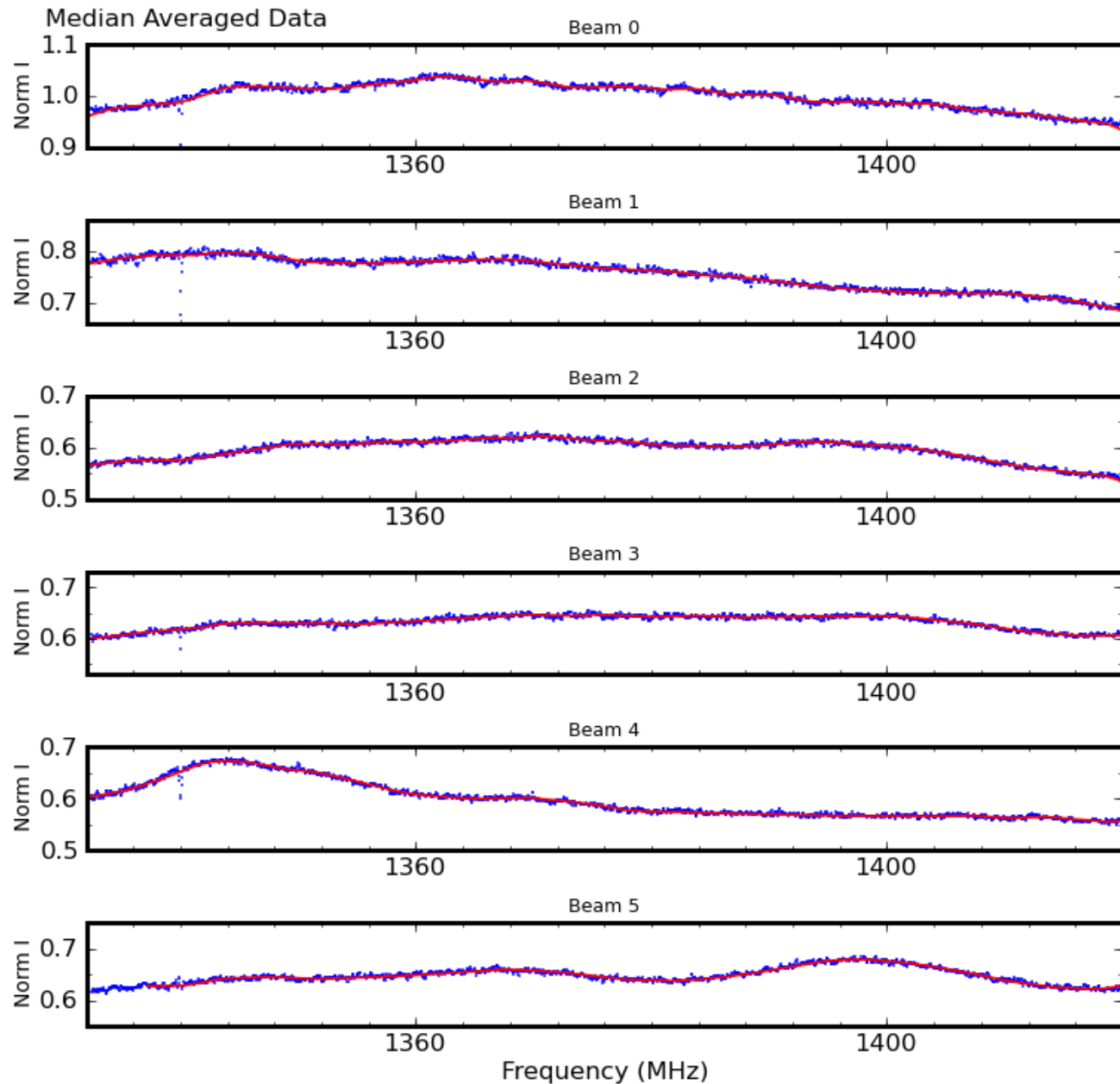
$$[I' \quad Q' \quad U' \quad V'] \begin{bmatrix} \frac{(g_x^2 + g_y^2)}{2} & \frac{(g_x^2 - g_y^2)}{2} & 0 & 0 \\ \frac{(g_x^2 - g_y^2)}{2} & \frac{(g_x^2 + g_y^2)}{2} & 0 & 0 \\ 0 & 0 & 2g_x g_y \cos \phi & -2g_x g_y \sin \phi \\ 0 & 0 & 2g_x g_y \sin \phi & 2g_x g_y \cos \phi \end{bmatrix} = [I \quad Q \quad U \quad V]$$

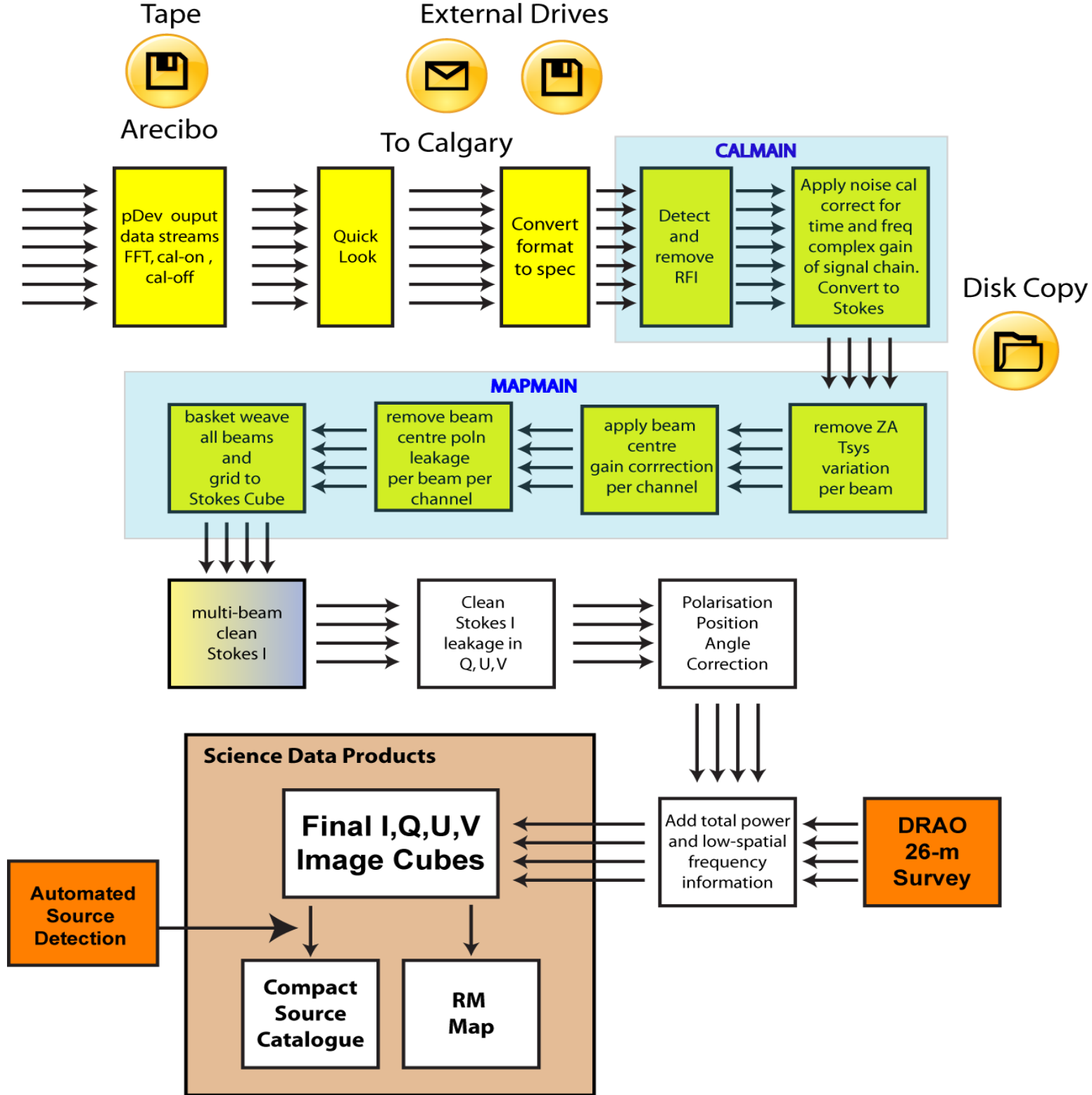
Beam Gain Correction

Use (completely sampled in each beam) calibrator observations

Normalize all the beam responses with respect to the central beam from individual beam maps of calibrator source

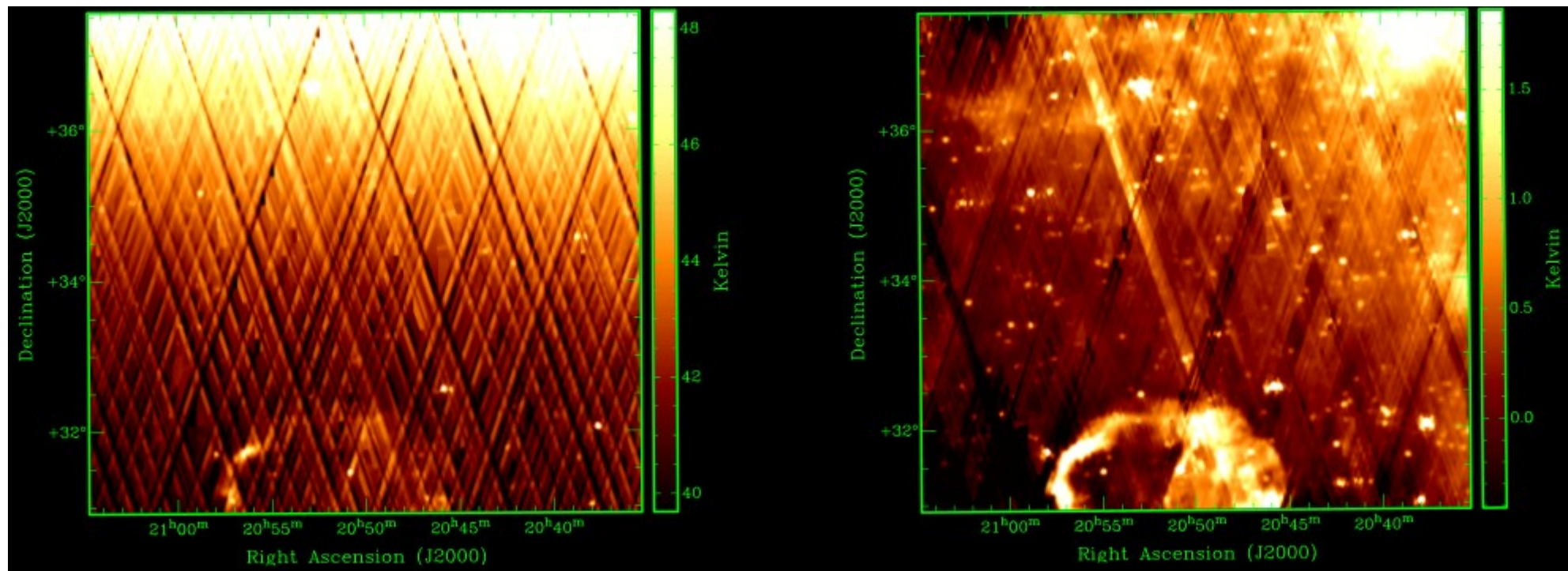
Use these values to normalize the main GALFACTS data

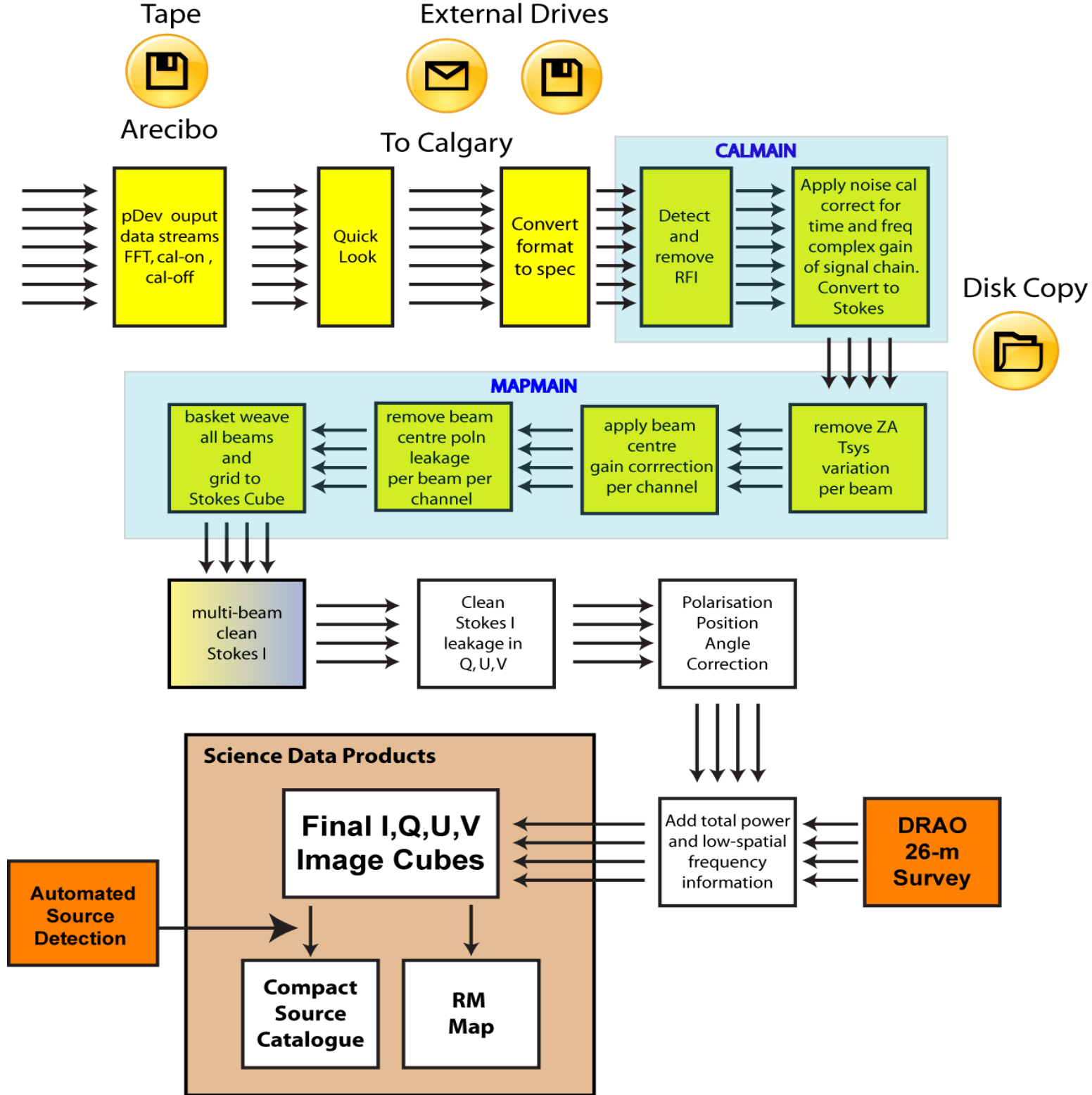




Declination Dependent Background Removal

- System temperature increases with declination (spillover effect)
- Bin per day per beam data into small declination bins
- Reject on source points from the bins
- Fit a polynomial to the binned data and subtract the fit from the original data

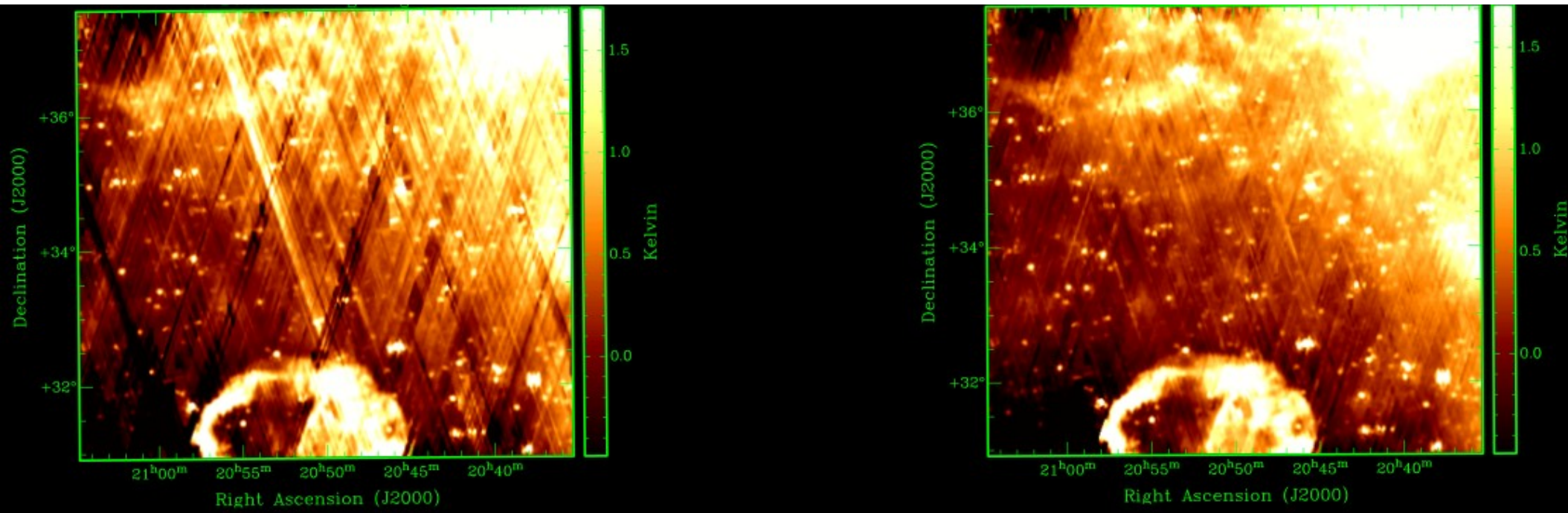


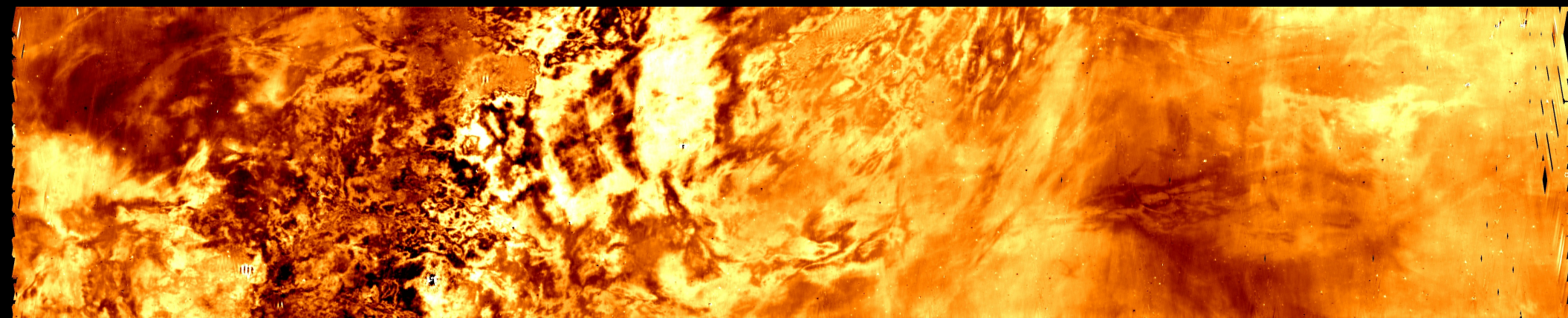
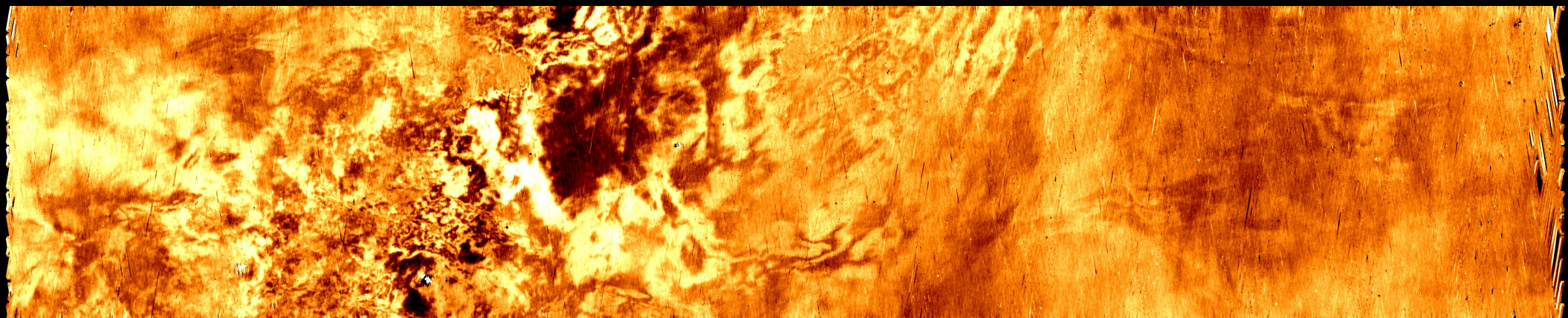


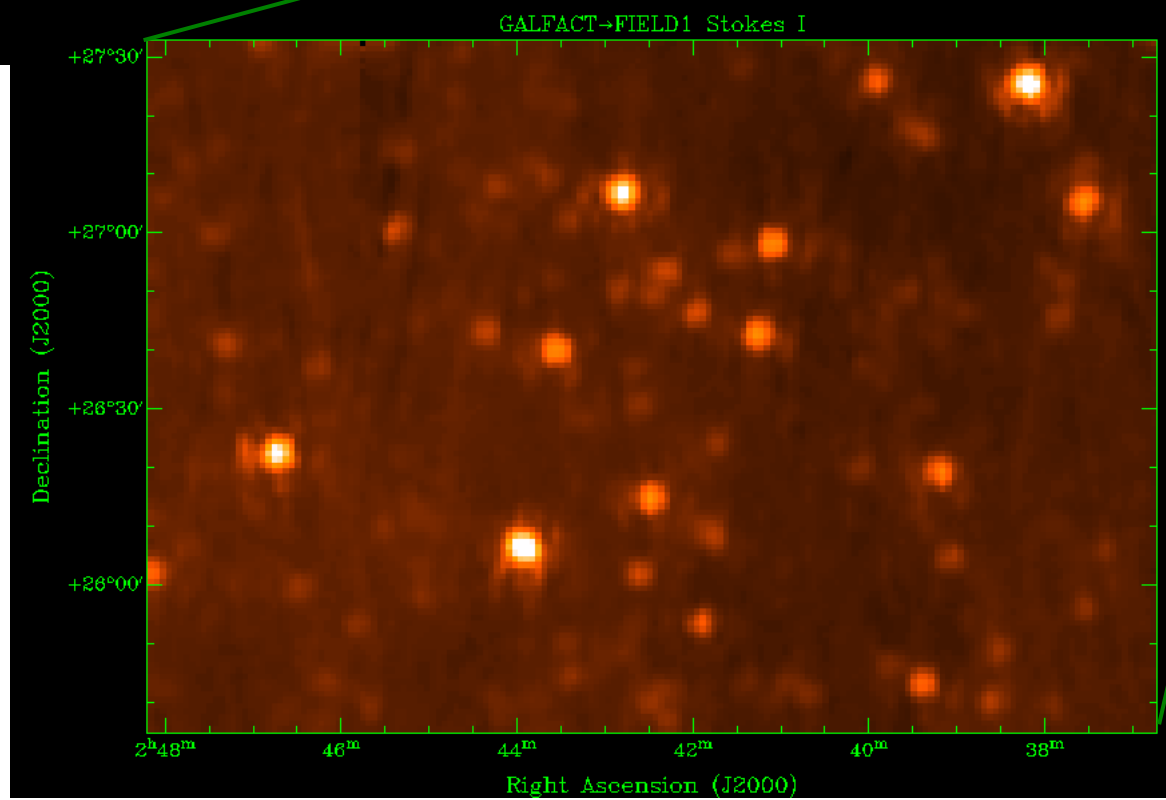
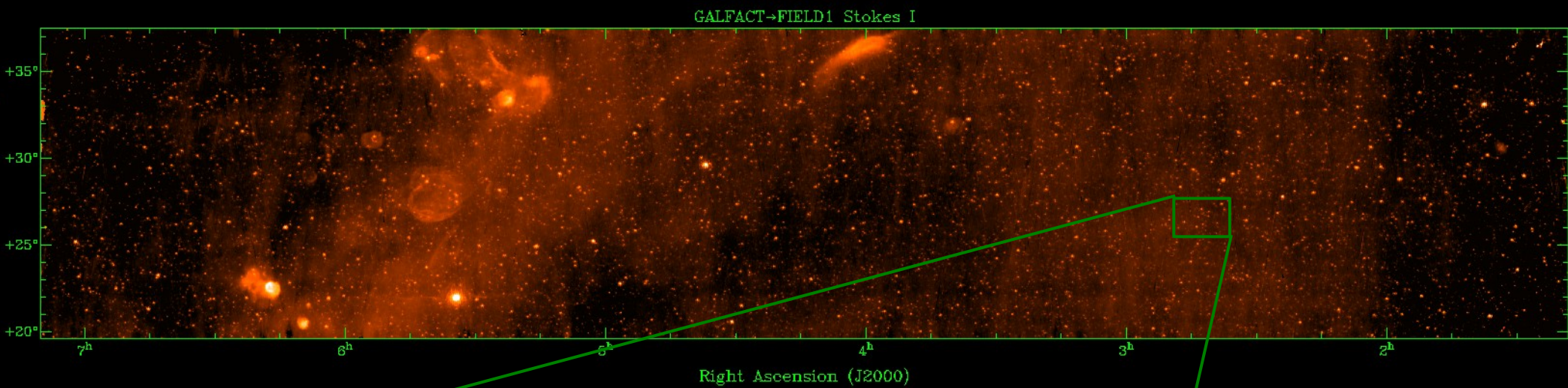
Basketweaving

Basic assumption: observation of same point on the sky should give same value

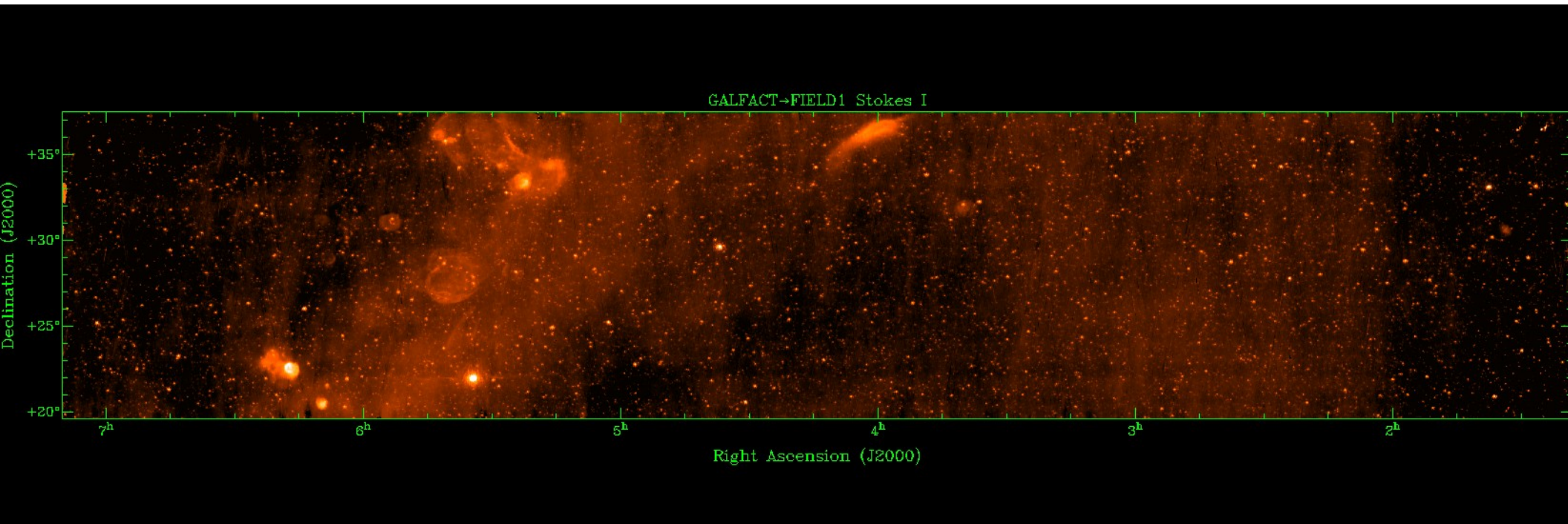
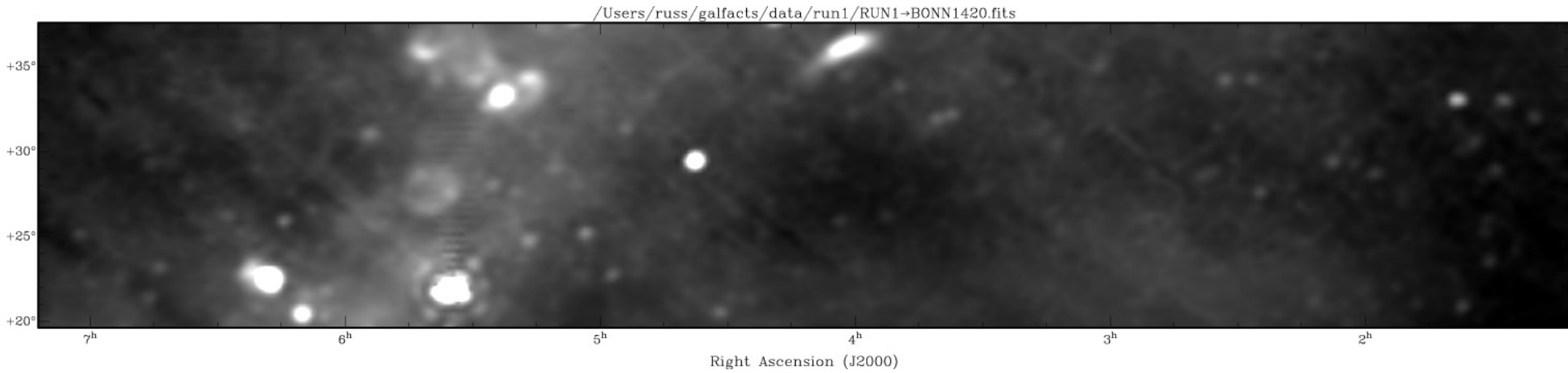
- Find the crossing points between various tracks and fit the differences at these points with a progressively increasing polynomial
- Subtract this polynomial (Chebyshev) times the loop gain from the original data. Iterate over the data until improvement become too small
- Change the polynomial order by one and repeat all the steps



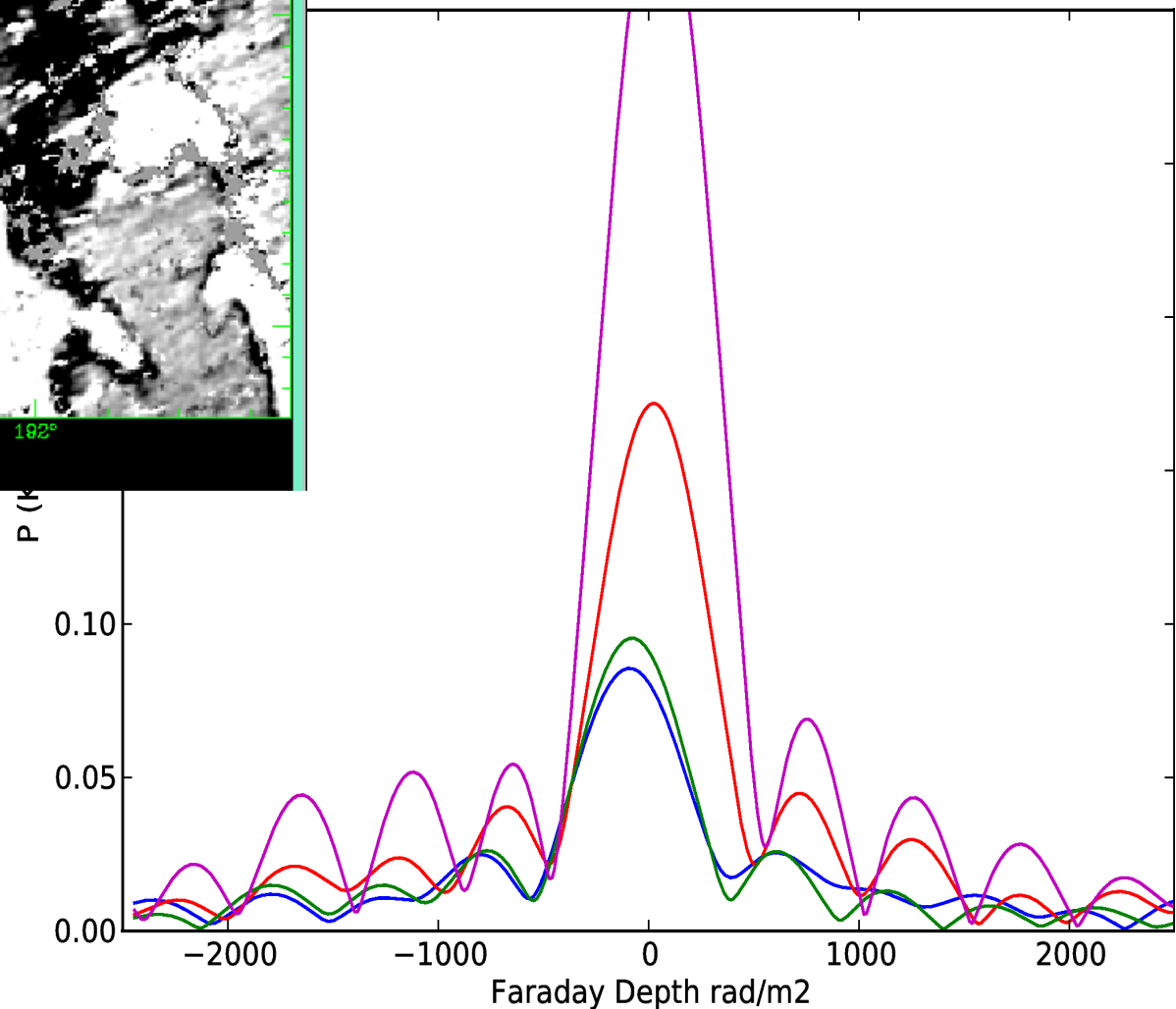
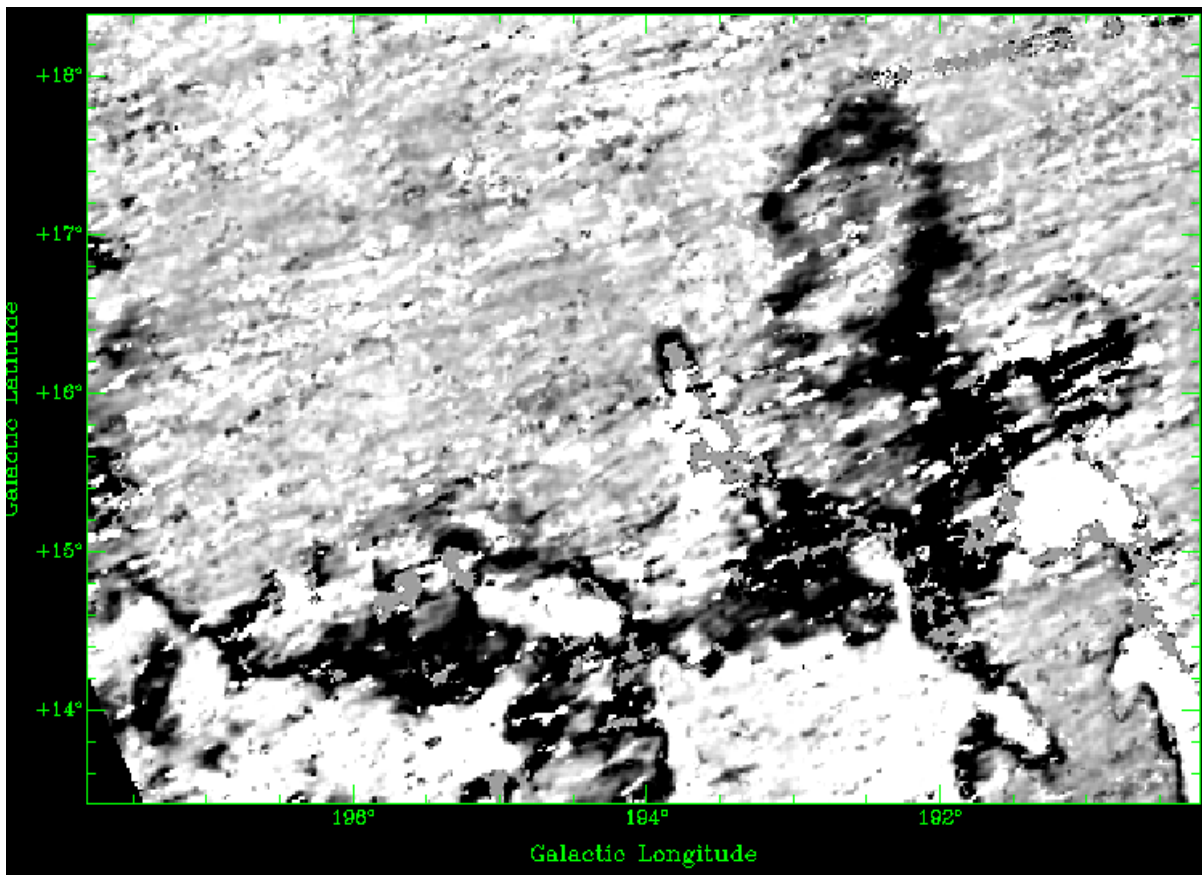




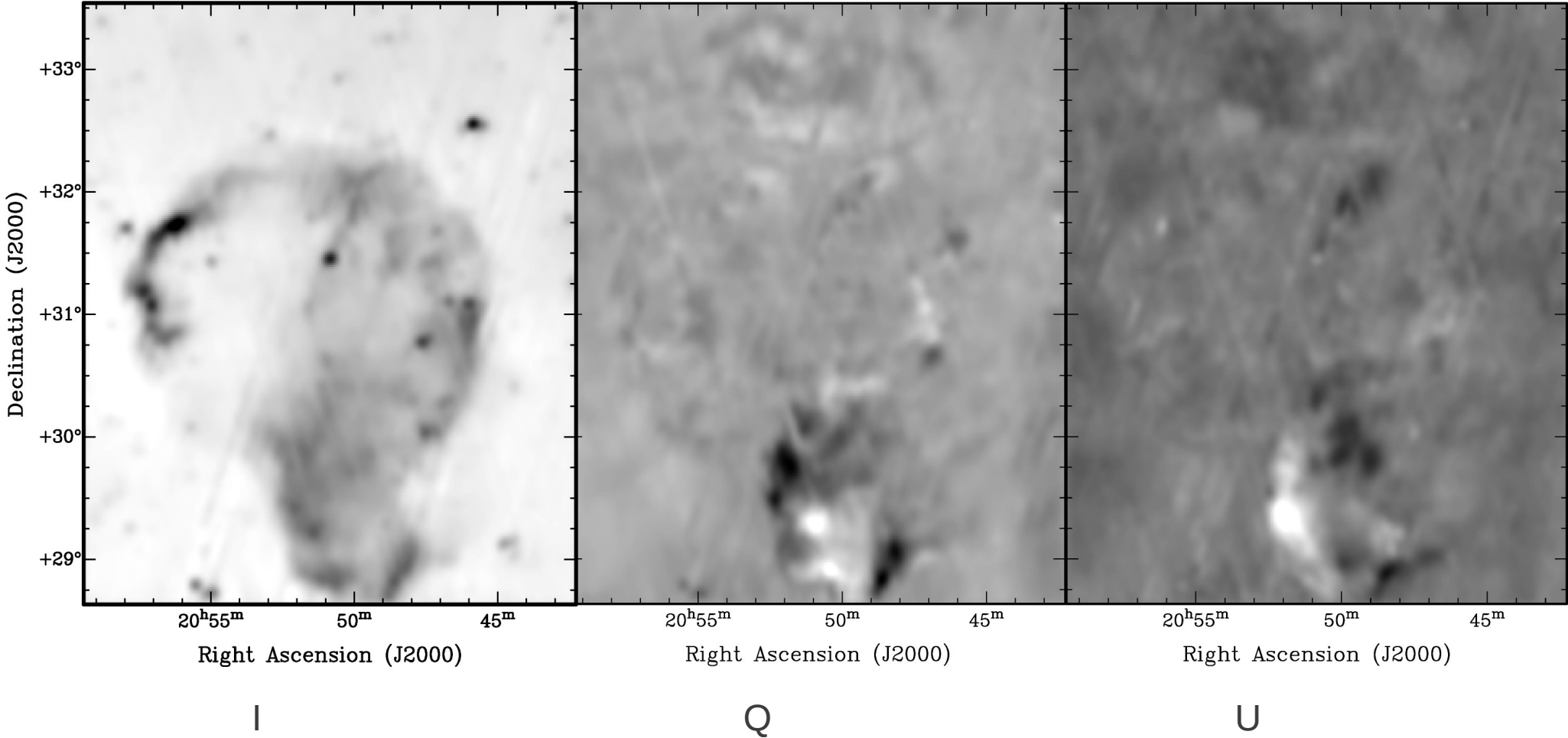
Effelsberg Survey Comparison

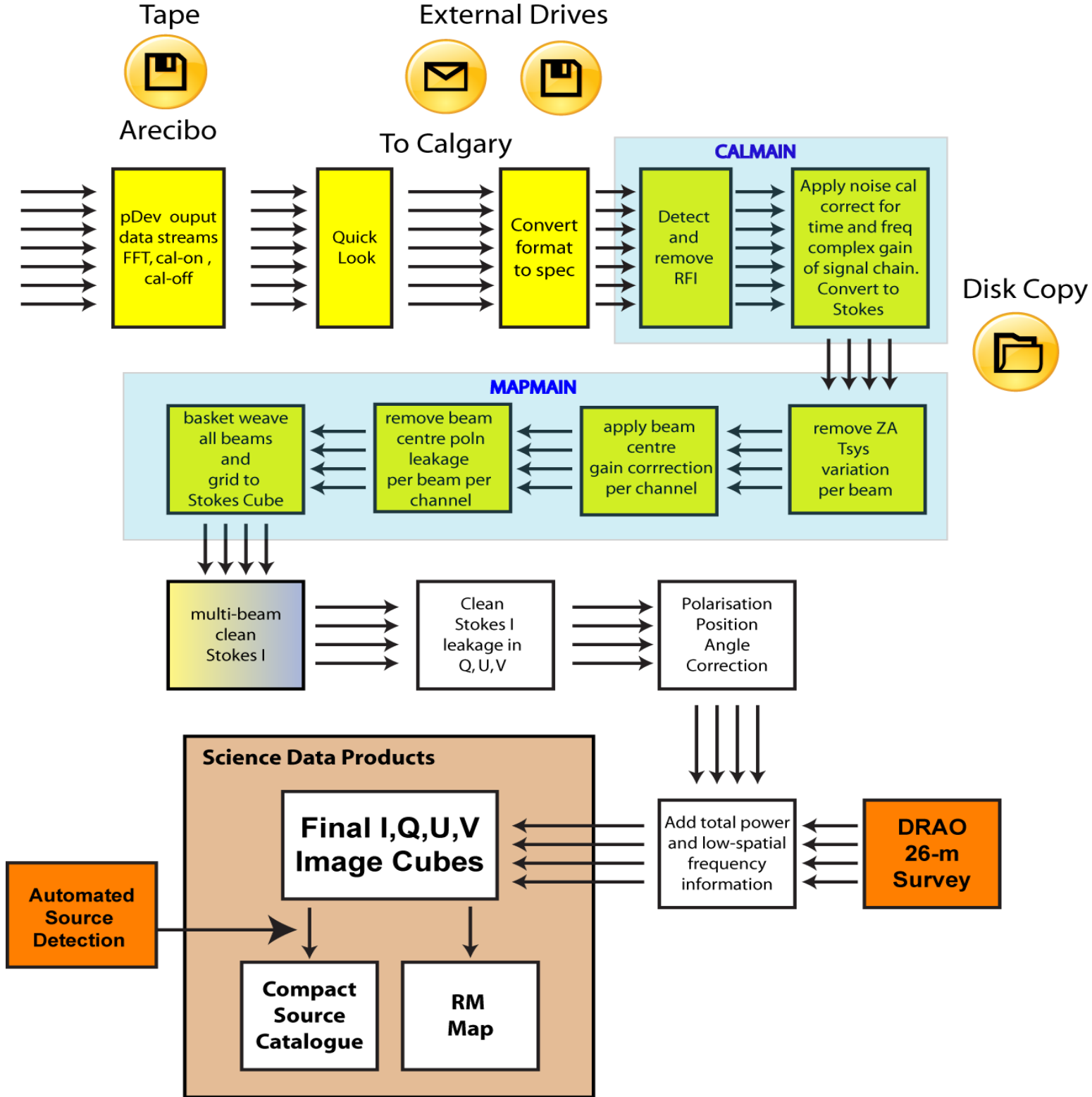


Rotation Measure Loop in N1

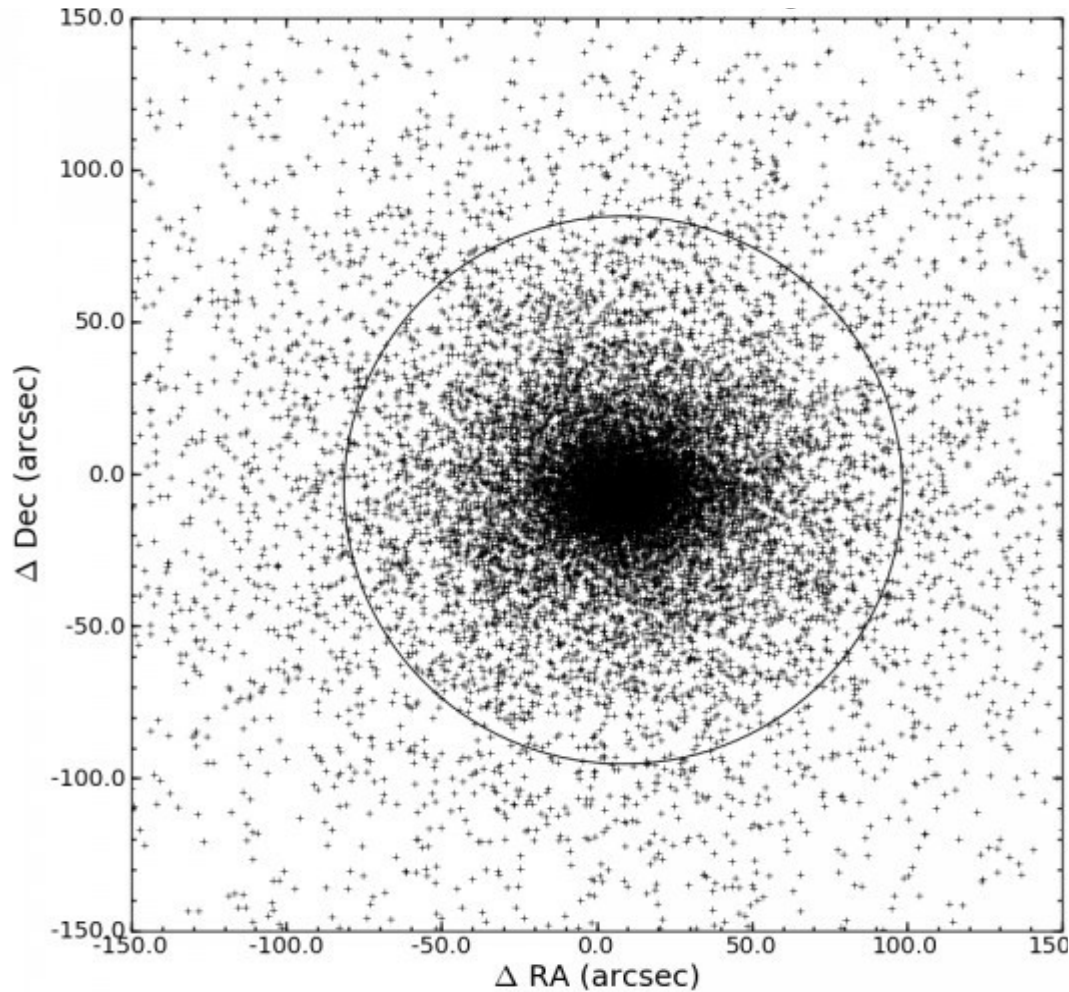


D Field Cygnus Loop



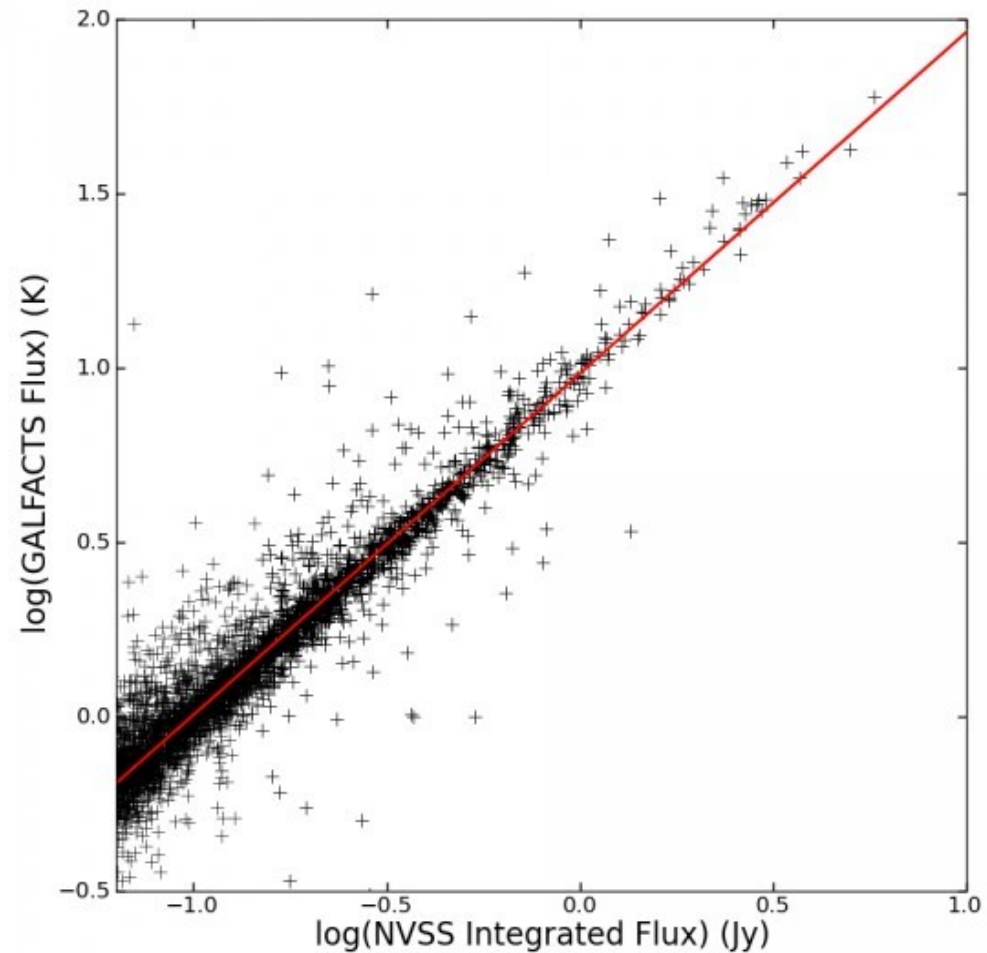


Automated Source Finding – compare with NVSS



mean position offset :

$$\Delta\alpha = 8.63'' \pm 0.01, \quad \Delta\delta = -4.44'' \pm 0.01$$



Gradient of 9.5231 K/J for sources
with NVSS flux > 150 mJy

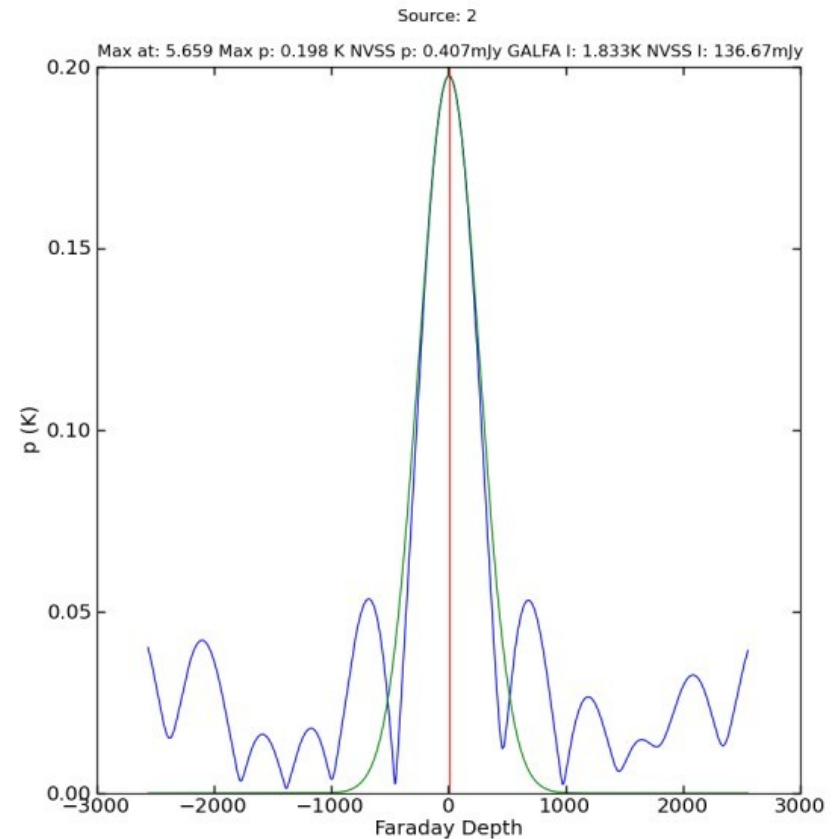
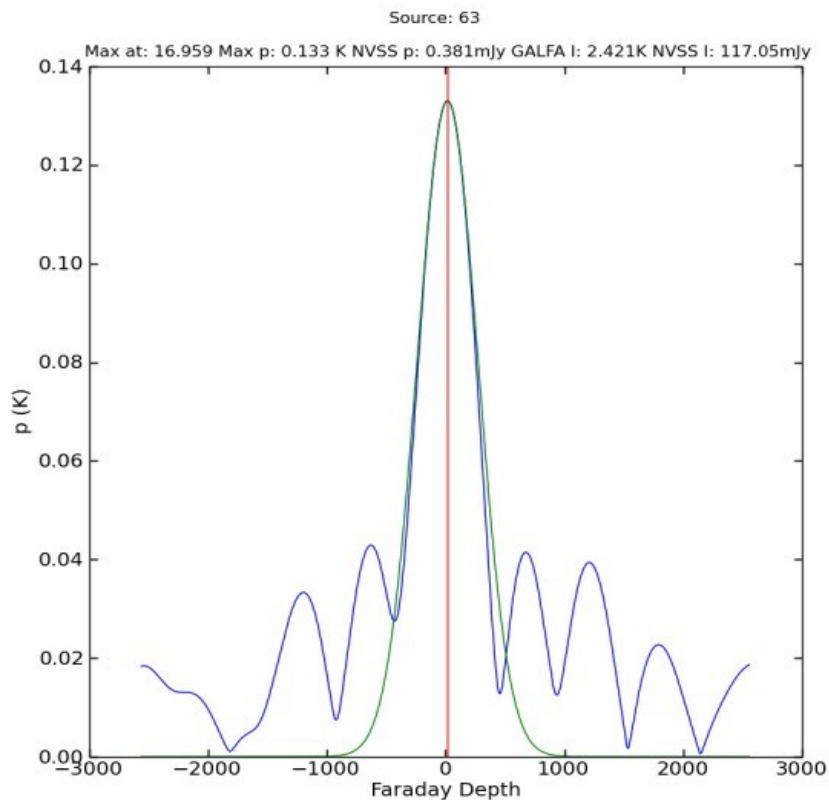
Automated RMs

Sources are found in Stokes I image

Instead of making RM cube of whole dataset (computational expensive) – make RMs of detected sources

Highly parallel – bash script that keeps track of jobs submitted and what next (uses desktops aswell as cluster)

Currently dominated by leakage terms on source

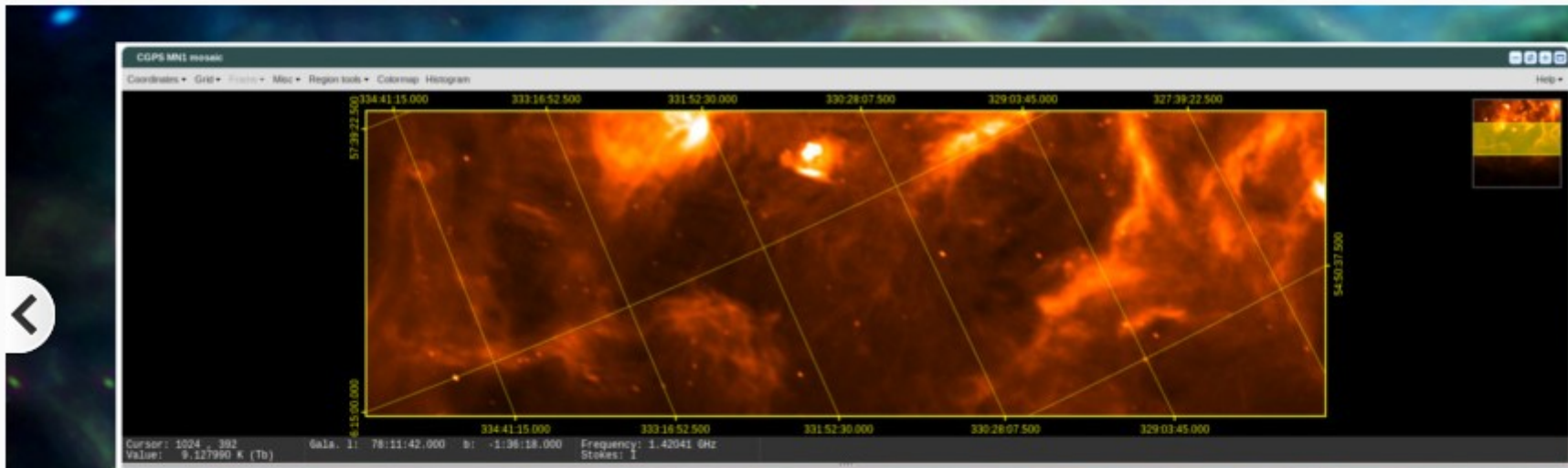


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