The LOFAR MKSP RM-Synthesis Pipeline



Anna Scaife (DIAS)

on behalf of

Mike Bell (MPIA Garching)

& the LOFAR MKSP

CALIM 2011, University of Manchester



Dublin Institute for Advanced studies Institiúid Ard-Léinn Bhaile Átha Cliath





Rotation Measure Synthesis The LOFAR BM Synthesis Pipeline Imaging, Deconvolution & Object Detection



Faraday Rotation



$$\phi = 0.81 \int_{\text{pc}} \frac{n_e}{\text{cm}^{-3}} \frac{B_{||}}{\mu \text{G}} \text{d}z \text{ rad } \text{m}^{-2}$$

For an external screen: $\phi = RM$

F(φ)





Faraday Depth

In general:

$$\phi \neq RM$$
, $RM = \frac{d\chi(\lambda^2)}{d\lambda^2}$ where $\chi = \frac{1}{2} \tan^{-1} \frac{U}{Q}$.

For the single source:

$$\chi(\lambda^2) = \chi_0 + \phi \lambda^2$$
, therefore $\frac{d\chi(\lambda^2)}{d\lambda^2} = \phi = RM$.



Multiple Faraday structures:

$$P(\lambda^2) = \int F(\phi) e^{2i\phi\lambda^2} d\phi$$
 (Burn 1966)

That single source again:

$$F(\phi) = \delta(\phi - \phi_0) \rightarrow P(\lambda^2) = e^{2i\phi_0\lambda^2} = \cos(2\phi_0\lambda^2) + i\sin(2\phi_0\lambda^2) = Q + iU$$



RM Synthesis

The Faraday dispersion function is a Fourier relationship:

 $P(\lambda^2) = \int F(\phi) e^{2i\phi\lambda^2} d\phi$ (Burn 1966)

$$F(\phi) = \int P(\lambda^2) e^{-2i\phi\lambda^2} d\phi$$



Similarly to the relationship between the *uv* and image planes in aperture synthesis it is not fully sampled:

$$P(\tilde{\lambda}^2) = W(\lambda^2)P(\lambda^2)$$

We get a response function similar to that of a PSF:

$$RMSF(\phi) = \frac{\int_{-\infty}^{\infty} W(\lambda^2) e^{-2i\phi\lambda^2} d\lambda^2}{\int_{-\infty}^{\infty} W(\lambda^2) d\lambda^2}$$

Brentjens & de Bruyn 2005



RM Synthesis

Resolution is a function of coverage in λ^2 : $\delta \phi \approx \frac{2\sqrt{3}}{\Delta \lambda^2}$ $\begin{array}{l} \text{Sensitivity to maximum scale in } \phi \text{ is a} \\ \text{function of resolution in } \lambda^2 \text{:} \\ ||\phi_{\max}|| \approx \frac{\sqrt{3}}{\delta\lambda^2} \end{array}$







RM Synthesis

- RMSF from 30-50 MHz + 60-80 MHz: $\delta \phi = 0.05 \text{ rad m}^{-2},$ $\phi_{\text{max}} = 19 \text{ rad m}^{-2}$
- RMSF from 120-150 MHz + 180-210 MHz: $\delta \phi = 1.0 \text{ rad m}^{-2}$, $\phi_{\text{max}} = 1200 \text{ rad m}^{-2}$

Heald 2009











RM Synthesis Pipeline

- FFT based synthesis
- RM-Clean and Wiener Filter deconvolution implemented
- Wavelet deconvolution under development
- Supports multiple image formats





RM Synthesis Pipeline





Early Results



Heald et al. 2011

Early Results





Early Results



Andreas Horneffer



Early Results



Andreas Horneffer

RM Synthesis Pipeline



Early Results

 Observation split into 8×1 hour blocks



Andreas Horneffer





Aris Noutsos



Charlotte Sobey



RM Clean

RM Clean (Heald 2009)

Works in the same way as standard CLEAN Iterative subtraction of a δ -fnc scaled by a loop gain factor.





RM Clean

RM Clean (Heald 2009)

Works in the same way as standard CLEAN lterative subtraction of a δ -fnc scaled by a loop gain factor.



RM Synthesis Pipeline





Fan region



Marijke Haverkorn























































Extended emission (Fan region)



WSRT



Extended emission (Fan region)



LOFAR: Marco Iacobelli & Marijke Haverkorn



RM Synthesis

Faraday spectra are **complex**: the modulus defines the emission and the phase the PA

$$\begin{aligned} \mathcal{P}(\lambda^2) &= \int \epsilon(z) \mathrm{e}^{2i\chi(z)} \mathrm{e}^{2i\phi(z)\lambda^2} \mathrm{d}z \\ \mathcal{F}(\phi) &= \epsilon(\phi) \mathrm{e}^{2i\chi(\phi)} \left(\frac{\mathrm{d}\phi}{\mathrm{d}z}\right)^{-1} \end{aligned}$$

Standard RM Synthesis does not recover the complex components as there is no information at $\lambda^2 < 0$

Requires a degree of inference about the underlying signal distribution



Frick et al. 2010



RM Synthesis

Wavelet based RM Synthesis can recover real and imaginary parts of $F(\phi)$ more accurately

Requires a degree of inference about the underlying signal distribution \rightarrow symmetry of dispersion function



Frick et al. 2010



Inference Based Reconstruction

max L subject to ⊓

Signal	Method
Sparse in pixel space (Dirac basis)	CLEAN
Sparse in some basis + RIP	Compressed Sensing
Gaussian Random Field	Wiener filtering
Non-Gaussian Random Field	Information Theory



CS for Faraday Thin Sources









CS-RM-Thin



Li et al. 2011



Faraday Caustics



(Bell, Enßlin & Junklewitz 2011)

Caused by reversals of the B-field along the l.o.s.

Leads to Heaviside functions in the Faraday dispersion spectrum





CS for Faraday Caustics

$$\begin{split} &\min ||\bar{x}||_{\mathrm{TV}} \text{ subject to } \quad \tilde{\chi}^2 \leq \epsilon^2 \\ & \text{Generalized Gaussian Distribution:} \\ & P(\nabla x|\rho) \propto \exp - |\frac{\nabla x}{\rho s}|^q \\ & \text{Sparse if } q \leq 1 \\ & \min ||\bar{x}||_{\mathrm{TV}}^q \text{ subject to } \quad \tilde{\chi}^2 \leq \epsilon^2 \\ & \text{(Wiaux, Puy & Vandergheynst 2010)} \end{split}$$





LOFAR RM Pipeline Status

Task	Status
Definition of input/output format(s)	Not started
DFT synthesis algorithm	Done
Gridding & FFT synthesis algorithm	Translate to C++
RMCLEAN algorithm	Translate to C++
Wiener Filter algorithm	Done
Support for automatic beam convolution	Translate to C++
Document	On going



Conclusions

- Polarization imaging is already possible with LOFAR. . . although polarization calibration currently isn't
- There is an interim RM synthesis pipeline (python-based) in place
- The RM synthesis pipeline accepts both imaging and pulsar pipeline data
- Reconstruction of complex Faraday spectra requires some prior information on the signal
- Inference based reconstruction methods are under development for the pipeline