

DVAC CONCEPT DESCRIPTION:

OFFSET GREGORIAN DISH — DVAC-1 PRIME FOCUS DISH — DVAC-2

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- **1.** Dish Verification Antenna China in General
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- 4. DVAC-1 Concept Design
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- 8. DVAC-2 Specification Budget





Potentially three types of reflector antenna could be used:

- > Prime focus reflector antenna
- > Dual symmetric reflector
- > Dual offset reflector



Prime focus reflector antenna

A prime focus reflector antenna has advantage of the simplest optical design, a symmetry helps the mechanical design and low cost. But disadvantages are:

 ✓ impossible to simultaneously optimize aperture efficiency and noise temperature;

✓ lower efficiency and higher side-lobe due to larger blockage;

 ✓ mechanically difficult to accommodate multiple feeds and a PAF at the primary focus.

1. DVAC General



- Dual symmetric reflector antenna
 - ✓ Aadvantages
 - Shaping produce high aperture efficiency and low noise T;
 - Feed spillover pointing to sky further reduce noise temperature;
 - Symmetry helps with mechanical design and cost.
 - ✓ Disadvantages
 - Subreflector has to be small to reduce aperture blockage, limiting the low frequency performance;
 - Small subreflector requires high gain (narrow beam) feeds, limiting use of broadband feeds with wide angle illumination;
 - Lower frequency feed and PAF to be at the primary focus, requiring a feed interchange mechanism, difficult to accommodate two feeds at the primary focus.

1. DVAC General



Dual offset reflector antenna

✓ Advantages

- Shaping produce high aperture efficiency and low noise T;
- No blockage design further enhances aperture efficiency and reduces wide angle sidelobes;
- Feed spillover pointing at the sky can further reduce the noise temperature;
- Mechanically easy to accommodate multiple feeds at the secondary focus and a PAF at the primary focus.

✓ Disadvantages

asymmetry increases the complexity of mechanical design leading to higher costs.





JLRAT propose two concept designs for the SKA dish.

- Dish Verification Antenna China #1 (DVAC-1) refers to an offset Gregorian dish;
- DVAC-2 refers to an axis-symmetric dish (prime focus reflector antenna).





Reference

- SKA Dish Verification Antenna: Executive Summary
- SKA Dish Verification Antenna System
 Functional Specifications
- >Requirements_spreadsheet_v1_20100929(1)

Main specifications and Concept Design

2. Design Principle



- Excellent performance
- Low cost
- Ease of transportation and installation
- Minimal routine maintenance
- Long lifetime



DVAC CONCEPT DESCRIPTION: OFFSET GREGORIAN DISH --- DVAC-1

3. Main Specifications for DVAC-1



Antenna Type	Offset-Gregorian Antenna, Diameter 15m
Mount Type	EL over AZ (AZ: Gear, EL: Screw)
Frequency Band	0.3GHz ~ 10GHz
Frequency Band Switch Manner	Switching Feeds within 30s
Surface Accuracy of Main Reflector	\leq 1.2 mm RMS (at night, under low wind) \leq 1.25mm RMS (Wind 7m/s , $△$ T=5°C) \leq 1.75mm RMS (Wind 20m/s , $△$ T=7°C)
Pointing Accuracy	≤10 arcsec RMS (at night and no wind) TBC (at daytime, with wind)
Antenna Aperture Efficiency (%)	≥ 55%
First Sidelobe Level	≤-18dB

3. Main Specifications for DVAC-1



Polarization	Dual-LP/Dual-CP
Travel Range	AZ: ±270°, EL: 15°~85°
Slew Rates (Max)	AZ: 3° /s, EI: 1° /s
Acceleration (Max)	AZ: 3° /s², EI: 1° /s²
Wind Velocity	Drive to stow :70 km/h Survival: 160 km/h (at El=54°)
Design Lifetime	≥ 30 years





- Offset-Gregorian Antenna
- Wide Band Feed (WBF)
- Integrated Modular Design
- Integrated Main Reflector Surface (Single Panel)
- Sealed and Lubricated Driving Devices
- Mature Technology

4. Concept Design Design and Manufacture





Block Diagram of 15 Meter Antenna System





Microwave Optical Design Structure Design Servo Control Design

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→ Feed Design

Main and Sub Reflector Curve Design

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→ Feed Design

Operating frequency: 0.3GHz~10GHz (33 octaves)

two wide-band feeds (WBF)

WBF advantages:

- Bandwidth of several octaves;
- Dual linear or circular polarization
- Constant phase centre
- Equal E- and H-plane beamwidth





→ Feed Design

Feed 1(0.3GHz ~ 1.5GHz) and Feed 2(1.5GHz ~ 10GHz) Eleven Feed

Frequency (GHz)	Length×Width×Height (mm)	Weight (kg)	
0.3~1.5	1040×1040×350	20 -	
1.5~10	250×250×120	8	Simulation Model



→ Feed Design

Subreflector Edge Taper: -9 ~ -15dB







Radiation Patterns of Feed1 at 0.3, 0.9 and 1.5GHz





Radiation Patterns of Feed2^{Exal tri19}.5, 6^{ivand th}10GHz^{largest radio telescope}

60

80

Phi=0°

Phi=90°



Main and Sub Reflector Curve Design











CO:phi=90 XP:phi=90 CO:phi=0 XP:phi=0

CO:phi=90

XP:phi=90

CO:phi=0

XP:phi=0

4

Radiation Performance of Antenna with PAF at Prime Focus





Initial Design



Current Design

- Single Panel
- Simple Structure
- Light Weight
- Low Cost
- Fast Installation







→ Reflector Design

Hount Design

Structural Mechanics Analysis

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- Single integrated main reflector
- Minimal spar structure
- Turning head design with a lead screw elevation actuator
- Support and interchange mechanism for a PAF and 3 SPFs or 2 WBFs.





Reflector Design

Subreflector Main reflector Main Feeds & Reflector Switch Back structure Subreflector Feed switch mechanism Back Structure



- → Reflector Design Main reflector
 - ✓ Design 1: Aluminum sandwich structure
 Single aluminium panel
 - Skins: 2mm (upper)/1mm (lower) in thickness, 2m in width
 - Skin and ribs are glued through negative pressure method on mould

Surface accuracy $\sigma \leq 0.8 \text{ mm}^{-1}$







- → Reflector Design Main reflector
 - ✓ Design 2: Carbon fibre sandwich structure
 - Single carbon fibre panel
 - Carbon fibre skins: 1.5mm (top)/1mm (bottom) in thickness
 - **Polyurethane foam: in the middle**
 - Surface accuracy $\sigma \leq 0.8$ mm





→ Reflector Design — Back structure

The backup structure is based on US TDP design with some modifications (some details see to DVAC-1).



escope



→ Reflector Design — Subreflector

Magnesium material, 30% lighter than aluminum alloy. Surface accuracy $\sigma \leq 0.25$ mm



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→ Reflector Design — Feed Switch Mechanism



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Hount Design





→ Mount Design — Azimuth part

Dual-motor anti-backlash drive >External gear bearing, easy to maintain Seal cover is used to exclude dust and sand AZ Rotation Table Cable Wrap Device





Mount Design — Elevation part A planetary reducer with a ball screw drive is used for the elevation part without a counterweight.





Hount Design

- A flexible-axis drive technique is adopted for Az and El encoder mechanism.
- > A double-layer ring structure is used for AZ cable wrap.
- > A modular design for all rotating parts.
- A Line-Replaceable Unit (LRU) design is applied to reducer, motor, encoder and limit device, azimuth cable wrap, and elevation lock device. Not only for ease of replacement and maintenance, but also suitable for batch production.



Weight of Dish

ITEM	WEIGHT (aluminum, Kg)	WEIGHT (carbon fibre, Kg)
Reflector	7250	7050
Mount	11250	11250
Total weight	18500	18300




Finite Element Model









Structural Mechanics Analysis

Reflector Surface Deformation by Gravity







Reflector Surface Deformation by Gravity







Reflector Surface Deformation by Wind







Reflector Surface Deformation by Temperature

Temperature Difference	2° C	5° C	7°C
Surface Error (r.m.s. mm)	0.081	0.203	0.284





Strength Analysis

Elevation (degree)	Wind speed (m/s)	Gravity	Max. stress (MPa)	Safety coefficient
10 °	20	\checkmark	77.4	4.5
54 °	20	\checkmark	80.3	4.3
90 °	20	\checkmark	150	2.3
54 °	45	\checkmark	150	2.3

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> Antenna Modal Analysis

Order	1	2	3	4	5
Resonant frequency (Hz)	2.42	3.25	4.61	4. 82	4.89



Structural Mechanics Analysis

Conclusion

The analysis results show that the structural

performance of antenna can meet the SKA

requirements





Investigation of Main Reflector Types



Aluminum Sandwich Structure (83mm thick, 2mm/80mm/1mm)





Carbon Fibre Sandwich Structure (82.5mm thick, 1.5mm/80mm/1mm)



Deformation of Aluminum Structure

Deformation of Carbon Fibre Structure





Investigation of Main Reflector Types

Туре	Name	Total thickness (mm)	Weight (t)	Maximum Deformation (mm)	Surface Error (rms, mm)
1	Aluminum sandwich structure	83	2.1	31.5	3.877
2	Carbon fibre sandwich structure	82.5	1.9	22.4	1.629

Surface accuracy of type 2 is better than that of type 1

4. Concept Design(3) Servo Control Design





4. Concept Design(3) Servo Control Design



Main features of control system

- Mature Product
- State-of-the-art components
- Fully digital control system
- Very high reliability
- > Modular design, easy for maintenance
- > Brushless motors, no maintenance
- Spare part available

4. Concept Design(3) Servo Control Design



> STANDBY

Power-on default operation mode or return-on-fault mode

PRESET

Moving to predefined position

> RATE

Moving at user-defined constant velocity

PROGRAM TRACK

Tracking of an object along a pre-defined path

> STOW

Automatically rotating to preset stow position and locking stow pin

5. Main Specification Budget (1) Full Radiation Pattern Calculation







5. Main Specification Budget (1) Full Radiation Pattern Calculation



Frequency (GHz)	First sidelobe (dB)		
	0° plane	90° plane	
0.3	(-22.77, -21.87)	(-25.51, -25.51)	
1.5	(-21.22, -20.38)	(-24.37, -24.37)	
6	(-21.21, -20.13)	(-24.64, -24.64)	
10	(-21.35, -19.73)	(-24.24, -24.24)	

First sidelobe: less than -19.73dB

5. Main Specification Budget (2) Antenna Aperture Efficiency



Frequency (GHz)	η ₁ η ₂	η ₃	η ₄	η ₅	ת (%)
0.3	0.71	1	0.95	0.98	66
0.9	0.76	1	0.95	0.98	71
1.5(feed 1)	0.78	0.99	0.95	0.98	72
1.5(feed 2)	0.77	0.99	0.95	0.98	71
6	0.81	0.91	0.95	0.98	69
10	0.81	0.78	0.95	0.98	59

Antenna aperture efficiency: more than 59%

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5. Main Specification Budget (3) Noise temperature





5. Main Specification Budget (4) Pointing accuracy



Error source (r.m.s.)	Error (arcsec)	Residual error (arcsec)	Modification method
Verticality of the azimuth axis	10	3	Pointing model
Azimuth-Elevation non- orthogonality	3	3	-
Azimuth bearing run-out	4	4	-
Adjust error of sub-reflector and feed	3	3	-
Gravity deformation	11	2	Lookup table
Thermal deformation	<1	<1	
Wind deformation	-	-	
Servo error	5	5	
Uncertain error	3	3	
Total error (RMS)	8.7 arcsec (at night and windless)		

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DVAC CONCEPT DESCRIPTION: PRIME FOCUS DISH --- DVAC-2

6. DVAC-2 Specifications



Antenna Type	Prime Focus Antenna, Diameter 15m
Focal length / Diameter ratio (f/D)	0.4
Mount Type	AZ-EL-POL mount (AZ, POL: Gear, EL: Screw)
Frequency Band	0.3GHz ~ 10GHz
Frequency Band Switch Manner	Switching Feeds within 30s
Surface Accuracy of Main Reflector	≤1.1 mm RMS (at night, under low wind) TBC(at daytime, with wind)
Pointing Accuracy	≤10 arcsec RMS (at night and no wind) TBC (at daytime, with wind)
Antenna Aperture Efficiency (%)	≥ 50%
First Sidelobe Level	≤-20dB

6. DVAC-2 Specifications



Polarization	Dual-LP/Dual-CP
Travel Range	AZ: $\pm 270^{\circ}$, EL: $15^{\circ} \sim 85^{\circ}$
Slew Rates (Max)	AZ: 3° /s, EI: 1° /s
Acceleration (Max)	AZ: 3° /s², EI: 1° /s²
Wind Velocity	Drive to stow :70 km/h Survival: 160 km/h (at El=90°)
Design Lifetime	≥ 30 years

7. DVAC-2 Concept Design Main Attractions of DVAC-2 Design



- Wide Band Feed (WBF)
- Integrated Modular Design
- Integrated Main Reflector Surface (Single Panel)
- Sealed and Lubricated Driving Devices
- Mature Technology

7. DVAC-2 Concept Design



Design and Manufacture



7. DVAC-2 Concept Design



Microwave Optical Design Structure Design Servo Control Design

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7. DVAC-2 Concept Design (1) Microwave Optical Design



→ Feed Design

→ Main Curve Design

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7. DVAC-2 Concept Design (1) Microwave Optical Design



→ Main Curve Design



F/D = 0.4

7. DVAC-2 Concept Design (2) Microwave Optical Design















New Design

- Single Panel
- Simple Structure
- Light Weight
- Low Cost
- Fast Installation







→ Reflector Design

Hount Design

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- Single integrated main reflector
- > Minimal spar structure
- Turning head design with a lead screw elevation actuator
- Four support legs and interchange mechanism for a PAF and 3 SPFs or 2 WBSPFs.





Reflector Design





- → Reflector Design Main reflector
 - ✓ Design 1: Aluminum sandwich structure Single aluminium panel Skins: 2mm (upper)/1mm (lower) in thickness, 2m in width Skin and ribs are glued through negative pressure method on mould Gluing Al Skin Surface accuracy $\sigma \leq 0.8$ mm **Rib Configuration** Gluing & Al Skin Riveting



- → Reflector Design Main reflector
 - Design 2: Carbon fibre sandwich structure
 Single carbon fibre panel
 Carbon fibre skins: 1.5mm (top)/1mm (bottom) in thickness
 - **Polyurethane foam: in the middle**
 - Surface accuracy $\sigma \leq 0.8$ mm





→ Reflector Design — Back structure









Mount Design — Azimuth part

- Dual-motor anti-backlash drive
- External gear bearing, easy to maintain
- Seal cover is used to exclude dust and sand


7. DVAC-2 Concept Design (2) Structure Design



Mount Design — Elevation and polarization part

Elevation part: a planetary reducer with a ball screw drive

Polarization part: a disc bearing



7. DVAC-2 Concept Design (2) Structure Design



Mount Design

- A flexible-axis drive technique is adopted for Az and El encoder mechanism.
- > A double-layer ring structure is used for AZ cable wrap.
- > A modular design for all rotating parts.
- A Line-Replaceable Unit (LRU) design is applied to reducer, motor, encoder and limit device, azimuth cable wrap, and elevation lock device. Not only for ease of replacement and maintenance, but also suitable for batch production.

7. DVAC-2 Concept Design (2) Structure Design



Weight of Dish

ITEM	WEIGHT (aluminum, Kg)	WEIGHT (carbon fibre, Kg)
Reflector	6800	6550
Mount	12500	12500
Total weight	19300	19050

7. DVAC-2 Concept Design(3) Servo Control Design





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7. DVAC-2 Concept Design (3) Servo Control Design



Main advantages of the control system

- Mature Product
- State-of-the-art components
- Fully digital control system
- Very high reliability
- > Modular design, easy for maintenance
- > Brushless motors, no maintenance
- Spare part available

7. DVAC-2 Concept Design(3) Servo Control Design



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Power-on default operation mode or return-on-fault mode

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8. DVAC-2 Specification Budget (1) Full Radiation Pattern Calculation







8. DVAC-2 Specification Budget (1) Full Radiation Pattern Calculation



Frequency	First sidelobe (dB)		
(GHz)	0° plane	90° plane	
0.3	(-28.2, -28.2)	(-28.2, -28.2)	
1.5	(-28.5, -28.5)	(-28.5, -28.5)	
6	(-28.7, -28.7)	(-28.7, -28.7)	
10	(-28.9, -28.9)	(-28.9, -28.9)	

First sidelobe: less than -28dB

8. DVAC-2 Specification Budget (2) Antenna Aperture Efficiency



Frequency (GHz)	η ₁ η ₂	η ₃	η ₄	η ₅	ת (%)
0.3	0.74	1	0.95	0.98	69
0.9	0.71	1	0.95	0.98	66
1.5(feed 1)	0.70	1	0.95	0.98	65
1.5(feed 2)	0.72	1	0.95	0.98	67
6	0.70	0.93	0.95	0.98	60
10	0.68	0.81	0.95	0.98	51

Antenna aperture efficiency: more than 50%

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8. DVAC-2 Specification Budget (3) Noise temperature



8. DVAC-2 Specification Budget (4) Pointing accuracy



Error source (r.m.s.)	Error(arcsec)	Residual error(arcsec)	Modification method
Verticality of the azimuth axis	10	3	Pointing model
Azimuth-Elevation non- orthogonality	3	3	-
Polarisation-Elevation non-orthogonality	3	3	
Azimuth bearing run-out	4	4	-
Adjust error of feed	3	3	-
Gravity deformation	9	2	Lookup table
Thermal deformation	<1	<1	
Wind deformation	-	-	
Servo error	5	5	
Uncertain error	3	3	
Total error(RMS)	9.2arcsec(at night and windless)		



Thank You END

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