



Machine Learning for Real-Time Transient Detection

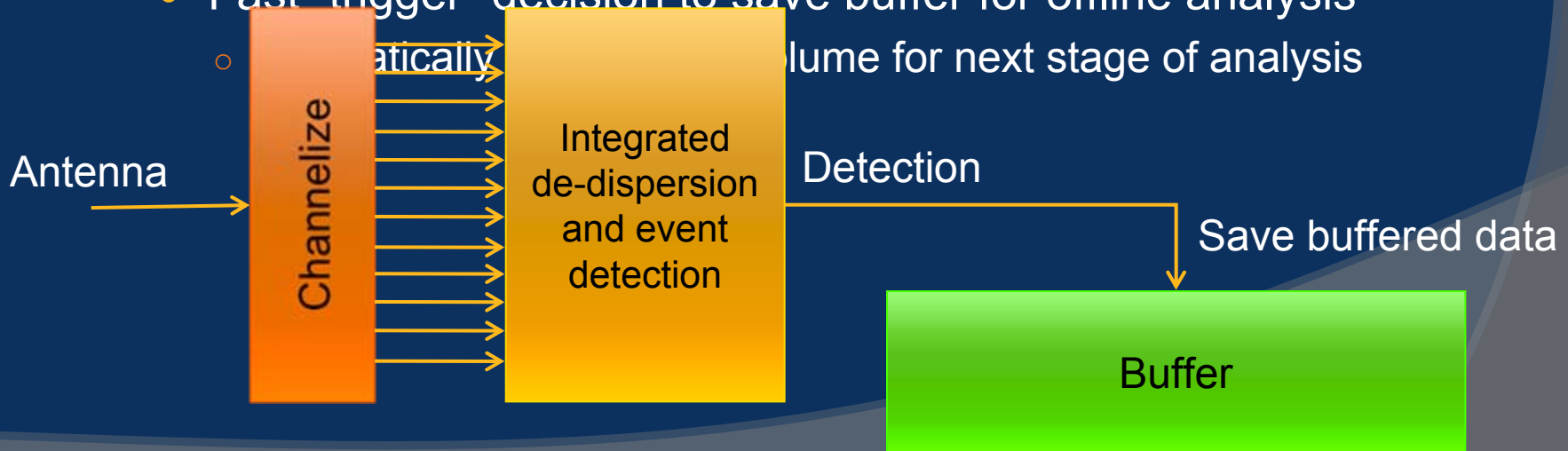
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March 24, 2010

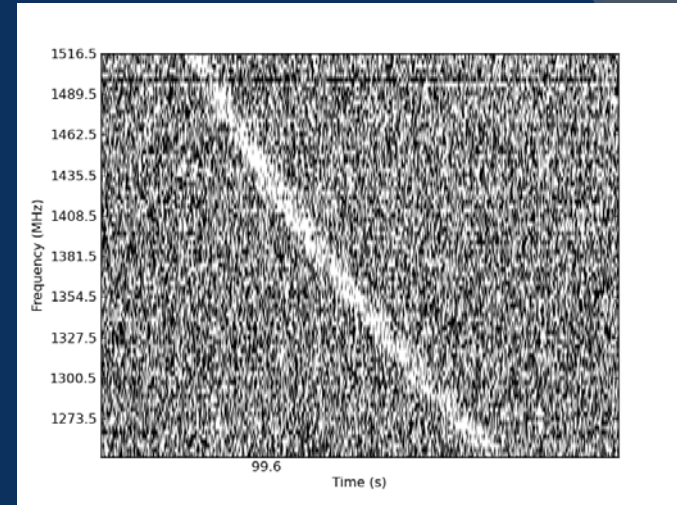
Machine Learning & Fast Transients

- Machine Learning: robust analysis inferred from data
 - Automatically choose tests and detection thresholds
- Detect short-duration radio events: major SKA goal
 - Pulsars, RRATs, merging neutron stars, evaporating black holes, gravitational wave events, etc.
 - Fast “trigger” decision to save buffer for offline analysis
 - Automatically choose volume for next stage of analysis

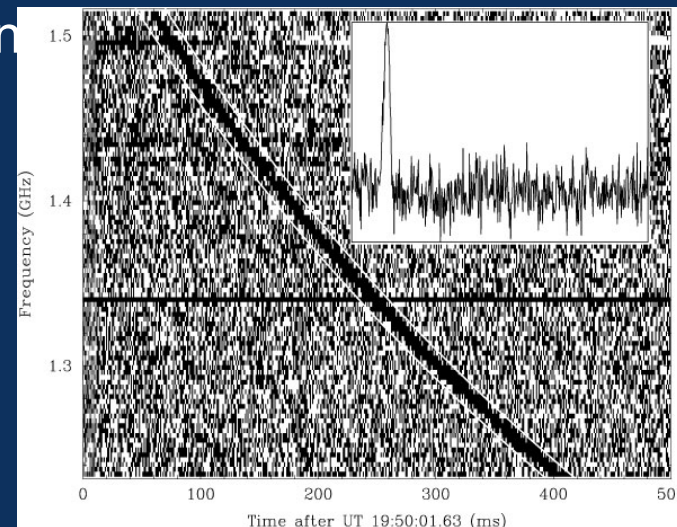


Signal Processing

- ⦿ Dispersion
 - Delays caused by intervening free electrons; stronger for lower frequencies
- ⦿ Incoherent de-dispersion (assuming given DM)
 - Sum pulse power across channels according to expected dispersion
- ⦿ Event detection
 - Is summed power $> \theta$?



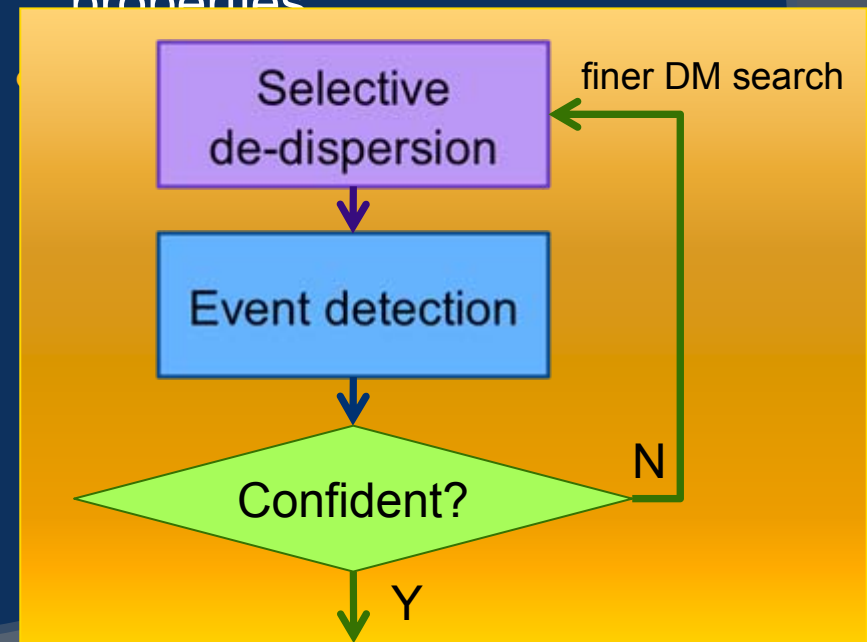
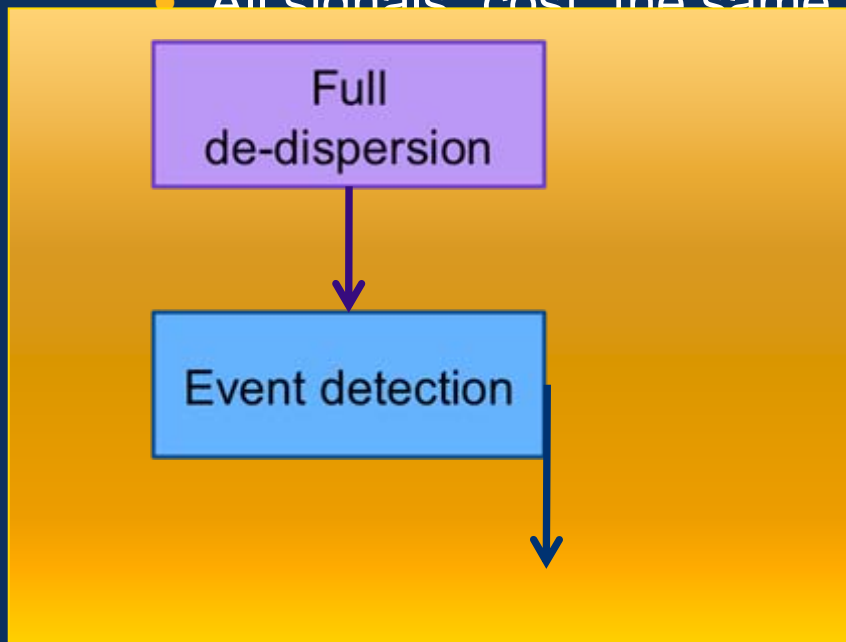
Pulsar J0742-2822, DM 73.78
Parkes Beam 5 [Edwards et al., 2001]



4.6-ms pulse at DM 375 (August 21, 2001)
[Lorimer, 2007]

De-dispersion & Event Detection

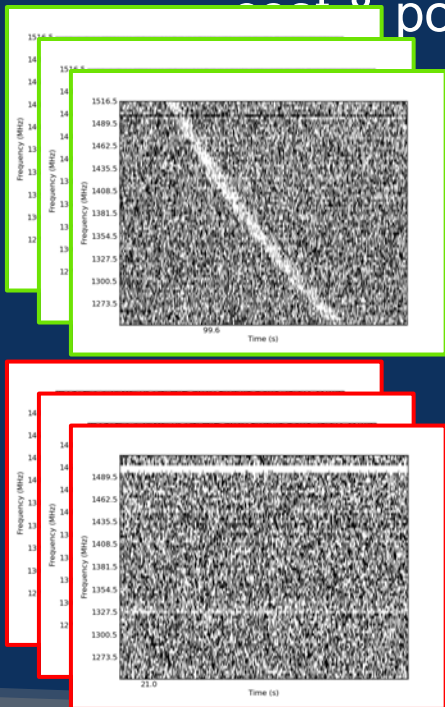
- Standard: full DM search, then event detection
 - Constant or linearly increasing spacing
 - All signals “cost” the same
- Machine Learning: learn which DMs to test for a given signal
 - Coarse-to-fine DM search
 - Flexible: adapts to data properties



Decision Tree

Input:

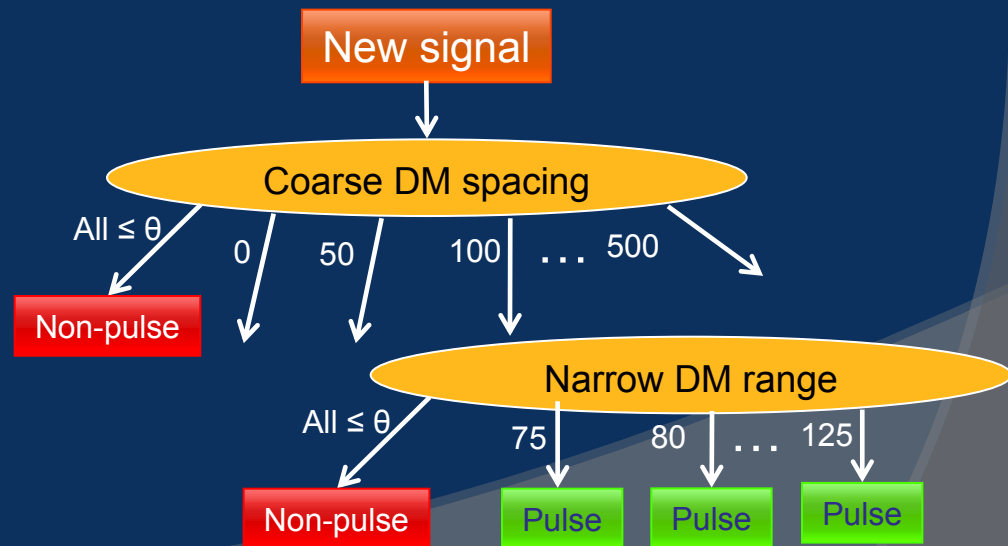
- Observations, labeled as **pulse** or **non-pulse**
- Cost of missed detection, false detection
- Capacity: Max. number of parallel de-dispersions conducted (applies to each tier of the tree); constrain HW cost & power



optimize



Choice of DMs, thresholds θ tuned to data



Adaptive Priors

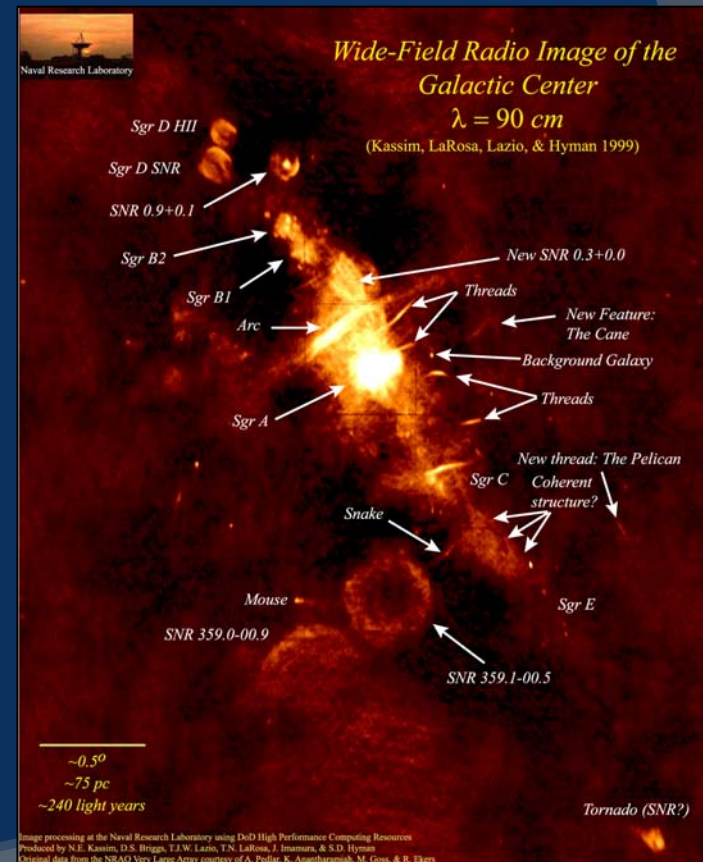
- What if training data doesn't match new data?

Radio Sky from Green Bank, WV



NRAO/AUI/NSF

Galactic Center



N. E. Kassim, D. S. Briggs, T. J. W. Lazio, T. N. LaRosa, J. Imamura (NRL/RSD)

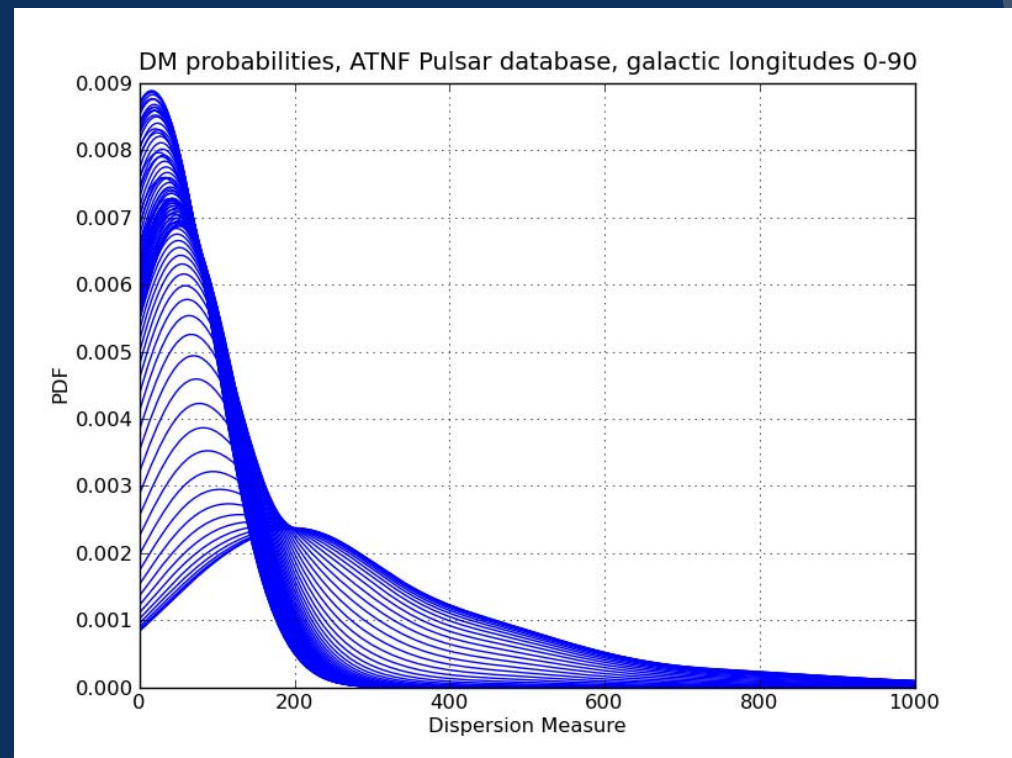
Adaptive Priors

- ◉ What if training data doesn't match new data?
 - Modify old training data according to new target
 - Increase weight of similar signals
 - Decrease weight of dissimilar signals

Probability of pulse
with given DM
depends on galactic longitude:

Could also model:

- Extragalactic sources
- Negative DMs
- Etc.



Simulation

Assumptions

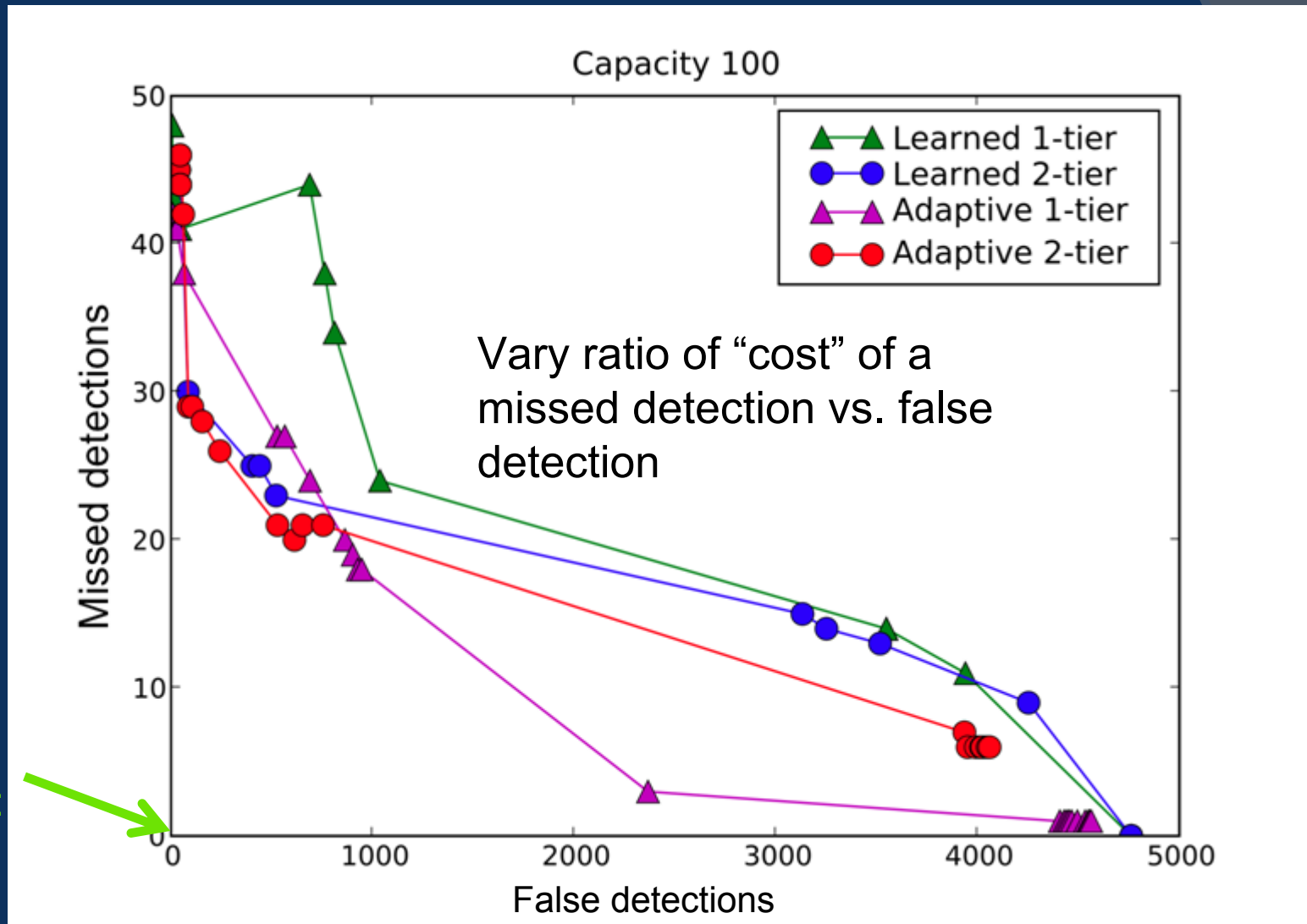
- $P(\text{pulse}) = 1 \times 10^{-6}$; $P(\text{non-pulse}) = 1 - 1 \times 10^{-6}$
- Hardware de-dispersion in parallel; vary capacity of system

Data

- Parkes Multibeam [Edwards et al., 2001]
 - 13 beam positions, 1.4 GHz (288 MHz bandwidth), 125 μs sample time, 96 channels
- Real “noise” data + synthesized pulses
 - Uniform prior over amplitudes, DMs from 0-500 cm^{-3}pc , SNRs (5-10), pulse width (0.5 ms)
 - 11,668 training signals (uniform)
 - 5,074 test signals (galactic lat, lon = 90, 90)



Simulation Results





Simulation Results

- Machine learning, 2-tier trees cut hardware needs (and power consumption) by ~20%
 - Also reduce false detections
 - Adaptive trees further reduce false detections

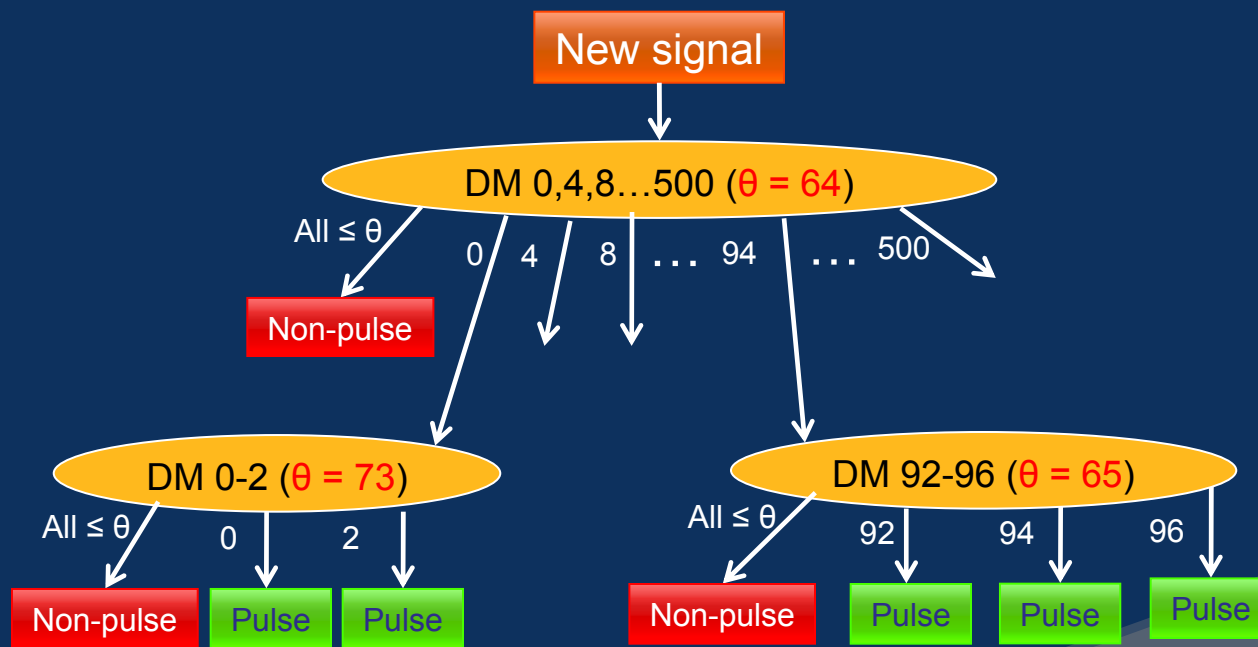
To achieve ≤ 20 missed (of 313):

Model type	Capacity required	False detections
Standard search	100 (125)	2000 (1000)
Learned 2-tier	100	1500
Adaptive 1-tier	100	900
Adaptive 2-tier	100	700

- Note: current results are data-limited

What was Learned?

- Top threshold set very low
- Threshold for DM ~ 0 sub-tests set high
 - Automatic RFI excision





Summary

- Machine learning for fast transient detection
 - 2-tier approach achieves same performance as standard search with 20% fewer DM units, fewer false positives
 - Adaptive trees enable extrapolation to new pointings
 - Some automatic RFI excision
 - Extensible: Can re-train tree as new signal types are discovered
- Next steps:
 - Incorporate information from multiple beams (RFI excision)
 - Other tests in decision tree nodes
 - E.g., event detection in time-frequency images

○ Thank you: Sarah Burke-Spolaor, Dayton Jones, Bob Preston
This work was carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration.

March 24, 2010 Larry D'Addario, Robert Navarro