



**"Exploring the Universe with the
world's largest radio telescope"**

2010

Annual WP2 Meeting

SKA System Design Plan

Kobus Cloete

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Overview

SPDO

- Memo 125
- Route to SKA



Memo 125

A Concept Design for SKA Phase 1 (SKA₁)

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SKA Memo 125 – SKA1 Science Goals

SPDO

Major Science Goals of SKA₁

The SKA Science Working Group [1, 2] has identified the science topics that can be addressed by SKA₁. Using these papers as a guide, the SKA Science & Engineering Committee (SSEC) has identified the following major science goals which drive the technical specifications for the SKA₁:

- (i) Understanding the history and role of neutral Hydrogen in the Universe from the dark ages to the present-day, and
- (ii) Detecting and timing binary pulsars and spin-stable millisecond pulsars in order to test theories of gravity (including General Relativity and quantum gravity), to discover gravitational waves from cosmological sources, and to determine the equation of state of nuclear matter.

SKA₁ Technical Concept

The SKA₁ baseline technical concept is driven by the need to address the two major science goals identified earlier in this document, i.e. understanding the history and role of neutral Hydrogen in the Universe from the dark ages to the present-day, and using pulsars as probes of fundamental physics.

The technologies required to achieve these two major science goals, lead us to a baseline design concept for SKA₁ that includes the following elements:

- 1) a low-frequency sparse aperture array with an A/T_{sys} of up to $2000 \text{ m}^2/\text{K}$ operating at frequencies between 70 and 450 MHz. The array will be centrally condensed but some of the collecting area will be in stations located out to a maximum baseline length of 100 km from the core, and
- 2) a dish array with $A_{\text{eff}}/T_{\text{sys}}$ of up to $1000 \text{ m}^2/\text{K}$ using approximately two hundred and fifty 15-metre antennas, employing an instrumentation package that will use single-pixel feeds to provide high sensitivity and excellent polarisation characteristics over a frequency range of 0.45-3 GHz. The array will be centrally condensed but some of the elements will be co-located with the sparse aperture array stations out to a maximum baseline length of 100 km from the core.



SKA Memo 125 – AIP

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Advanced Instrumentation Programme (AIP) for the full SKA

The SKA₁ baseline concept design presented here represents the first concrete step towards the realisation of the much larger and more ambitious SKA₂. The Advanced Instrumentation Programme (AIP) will seek to capitalise on investments made by the SKA Organisation and other parties in innovative technology development over the pre-construction period 2011-2015. In 2011-2015, advanced instrumentation systems under development for the SKA are expected to include: Phased Array Feeds (PAFs), Dense Aperture Arrays (DAAs), high frequency feeds etc.

Given the progress expected in all of these areas of instrumentation over the next 5 years, a decision identifying the most promising system for SKA₂ can be made in 2016, at the start of the initial SKA₁ construction phase. Advanced instrumentation such as PAFs or high frequency feeds may also be deployed as modular sub-systems on the SKA₁ dishes. DAAs will require the construction of a substantial standalone demonstrator. The AIP will realise an advanced system that will either greatly enhance the baseline SKA₁ telescope and/or will demonstrate an important technology prototype of direct relevance to SKA₂. The opportunity for individual research groups to fund new instrumentation relevant to the SKA should not be excluded.



Memo 125 – Summary (1)

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- Baseline
 - Low frequency sparse aperture array
 - Dish array
 - Signal transport and networks
 - Correlator and Non visibility processor
 - Central Data Processing, Science Processing and System Software.
 - Central timing and synchronisation subsystem, including time and frequency reference distribution,
 - Infrastructure (buildings, roads, facilities, labs etc.),
 - Power delivery and distribution,
 - Support and maintenance equipment and facilities



Memo 125 – Summary (2)

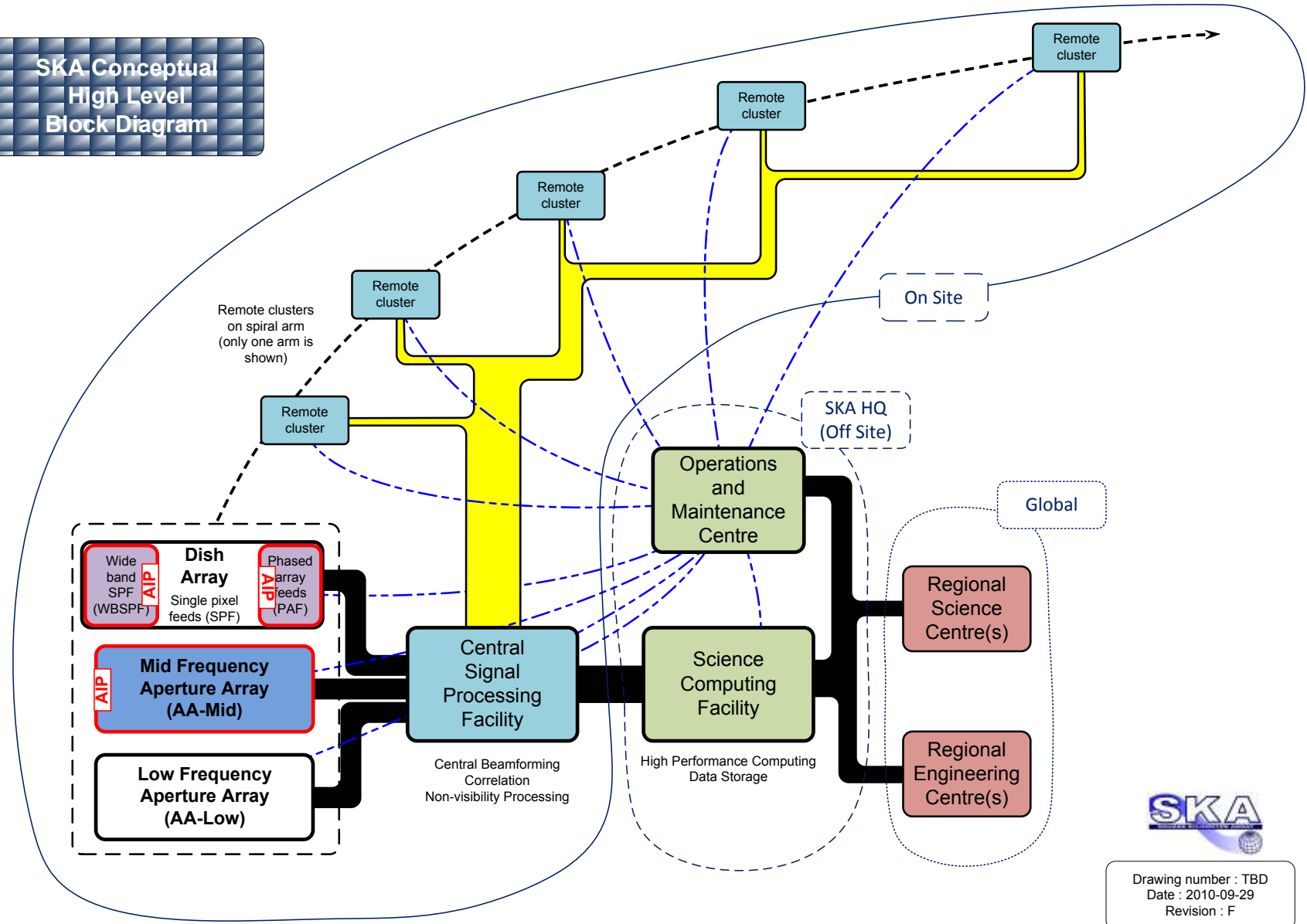
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- Advanced Instrumentation Program
 - Dense Aperture Arrays
 - Phased Array Feeds
 - Ultra Wide band Single Pixel Feeds
- Decision points for AIP identified
 - 2016, or
 - As modular sub-systems of the SKA1 dishes
- How do we continue with the SKA definition and design and at the same time take all of these aspects into consideration?

SKA High Level Conceptual Block Diagram

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SKA Conceptual High Level Block Diagram



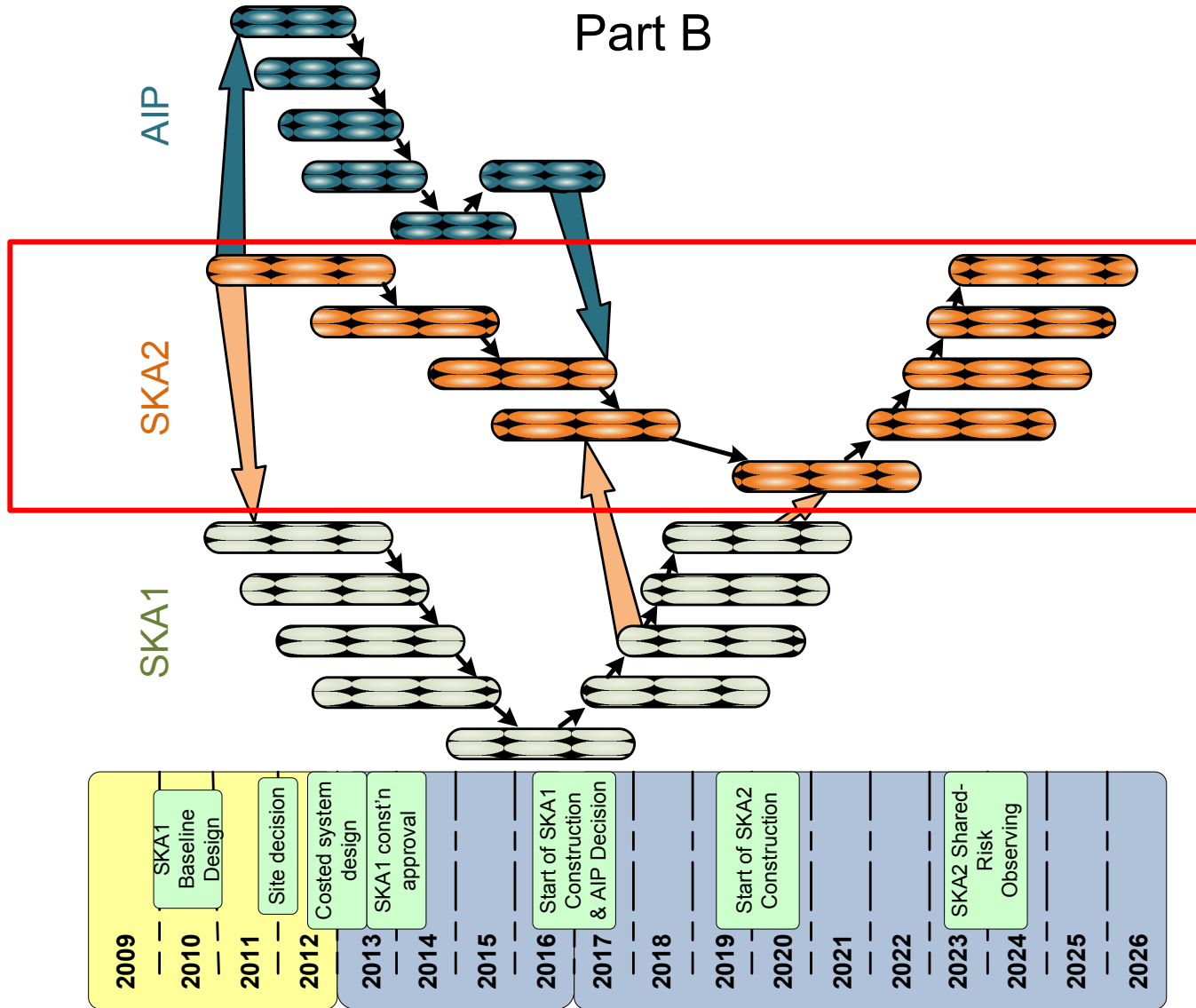


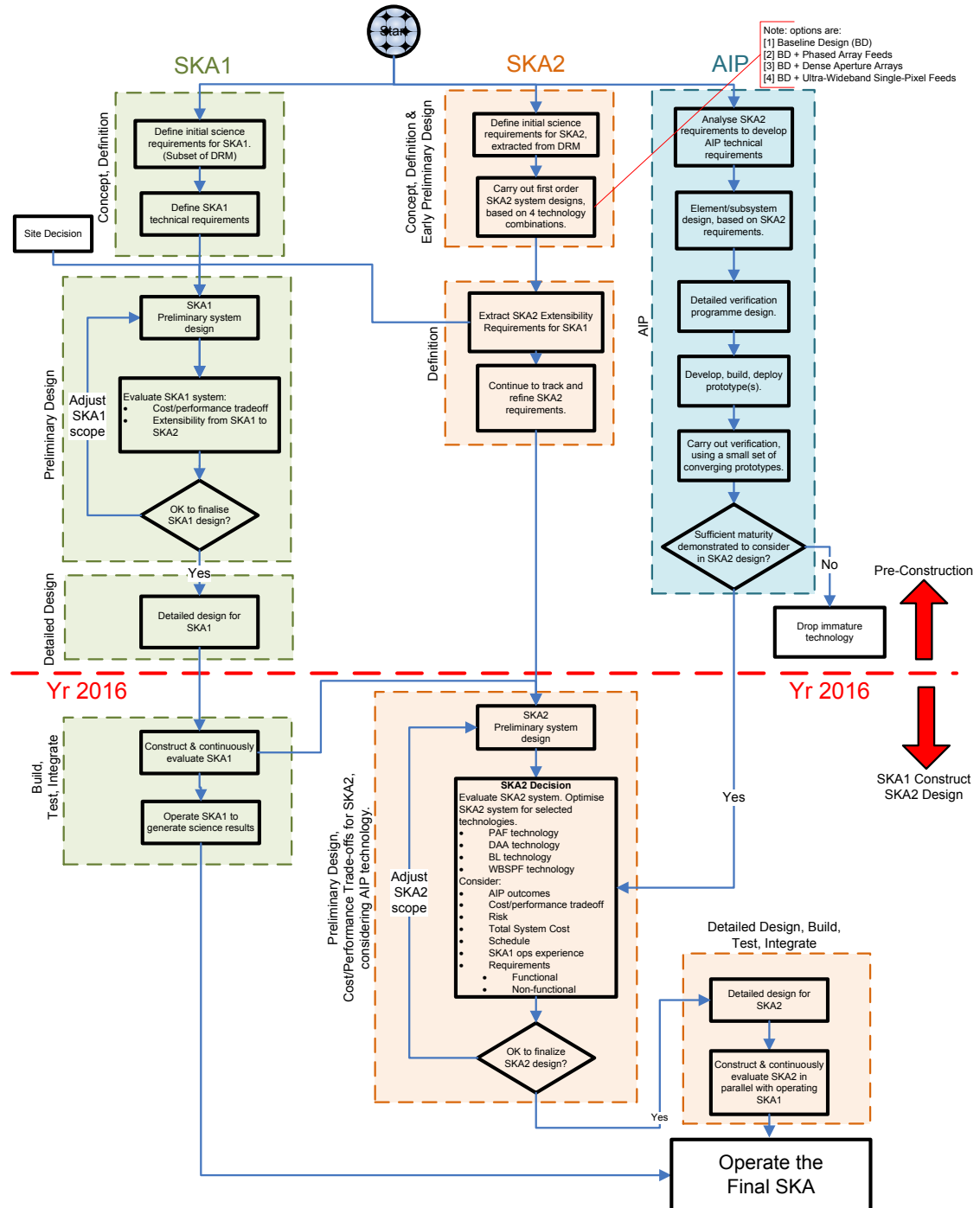
Route to SKA

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- How do we continue with the SKA definition and design and at the same time take all of these aspects into consideration?
- Recently a conceptual Route to SKA was developed attempting to maintain the structure of the project but at the same time maintain flexibility to accommodate all the identified future enhancements.
- Always maintain focus on the full SKA.

Graphical Representation

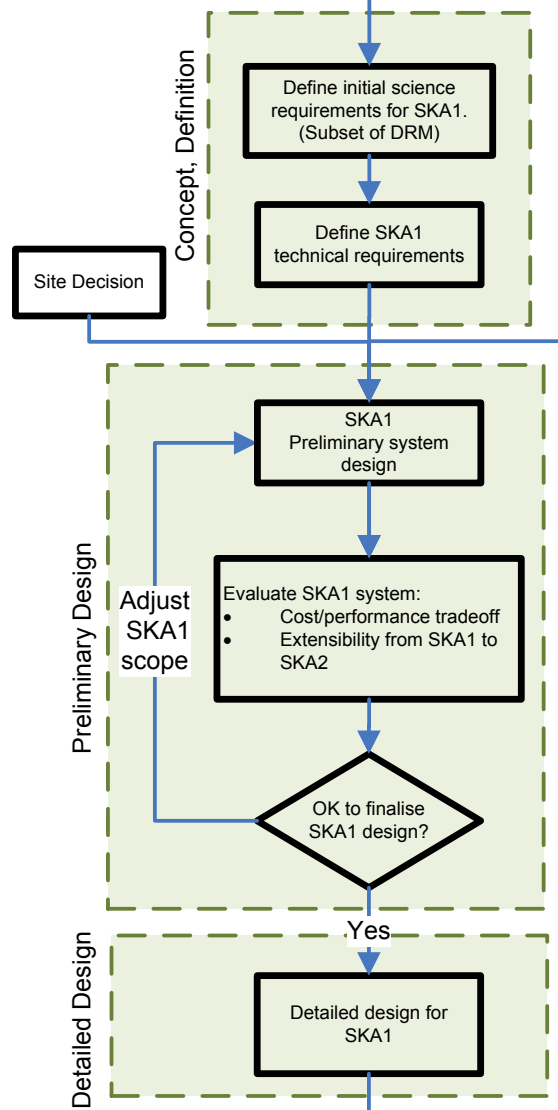




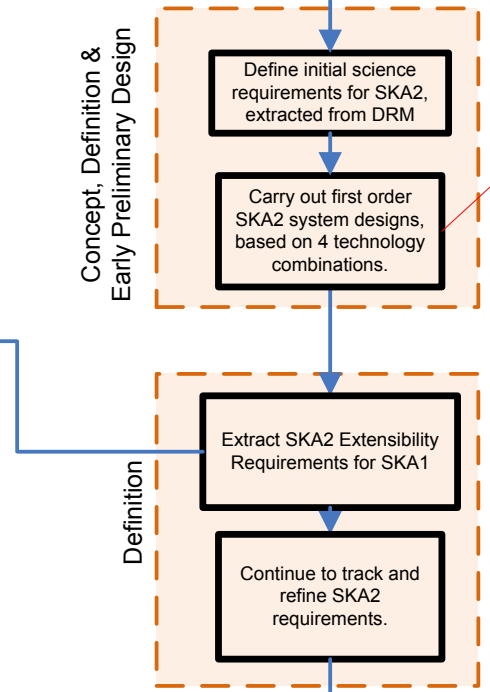


Note: options are:
[1] Baseline Design (BD)
[2] BD + Phased Array Feeds
[3] BD + Dense Aperture Arrays
[4] BD + Ultra-Wideband Single-Pixel Feeds

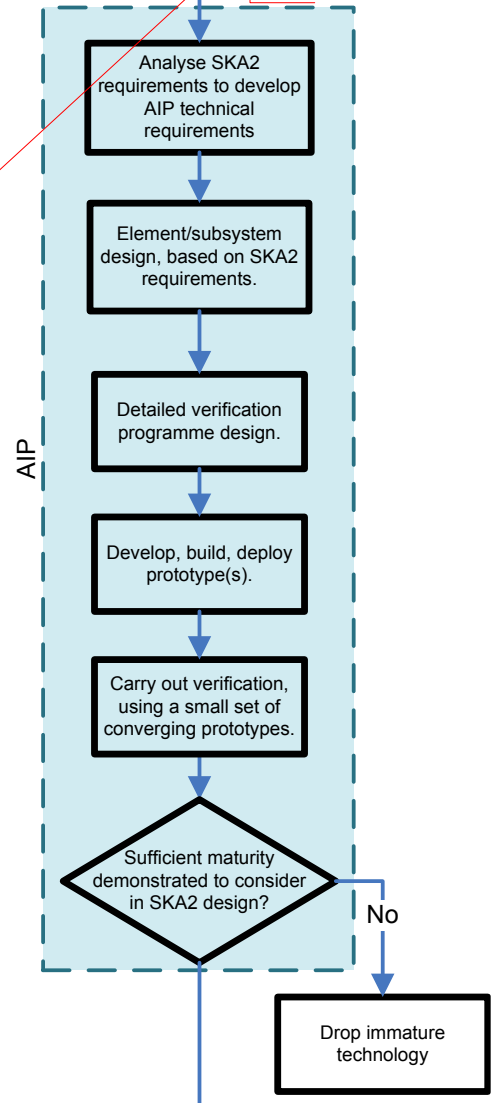
SKA1



SKA2



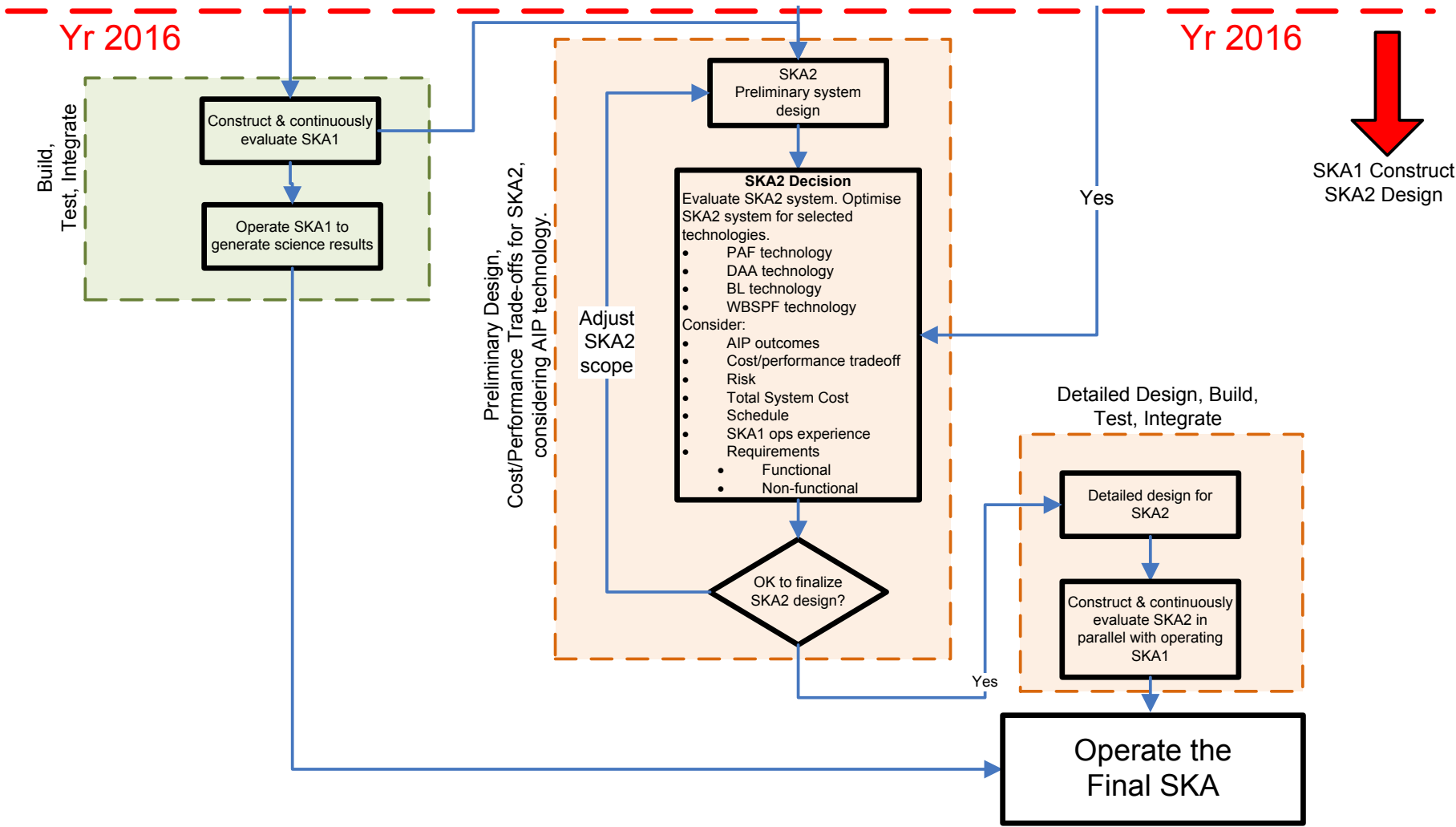
AIP



- From the SKA1 science requirements (Memo 125)
 - Derive the SKA1 technical requirements
 - Develop initial SKA2 system technical requirements based on the science requirements contained in the Design Reference Mission (DRM).
- Perform preliminary system design for SKA1
 - To be informed by early preliminary designs for the SKA2 options, so as to ensure extendibility to SKA2.
 - Tradeoffs of performance against cost.
- Full detailed design for SKA1.

- To inform the SKA1 design process
 - Draft initial technical requirements for the four system options for SKA2 (Baseline Technology alone + the three AIP options in combination with the Baseline Technology),
 - Carry out early preliminary system designs for each of the options.
- Continue to track Phase 2 requirements to prepare for a decision on technology selection in 2016.

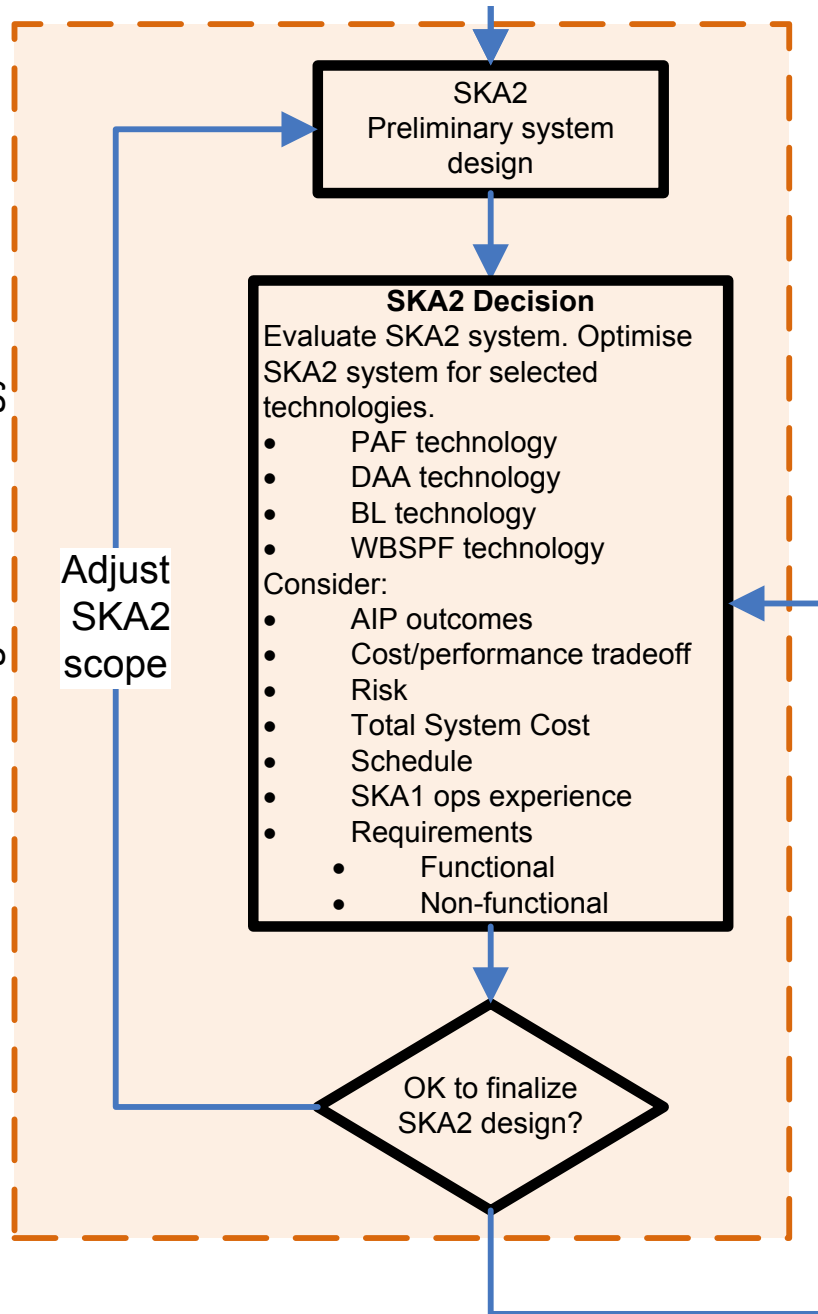
- The AIP will build up the level of maturity in anticipation of their utilisation in SKA1 and SKA2.
- General steps:
 - Analyse the SKA requirements to maximise potential to enhance system performance, achieve more of the initial system requirements and/or reduce cost, as compared with the baseline.
 - Develop a preliminary design assuming the particular AIP technology will be used at the element or subsystem level of the system.
 - Carry out a verification program to test the level of achievement of requirements, to develop performance/cost models for the AIP technology, and to ascertain remaining risk.



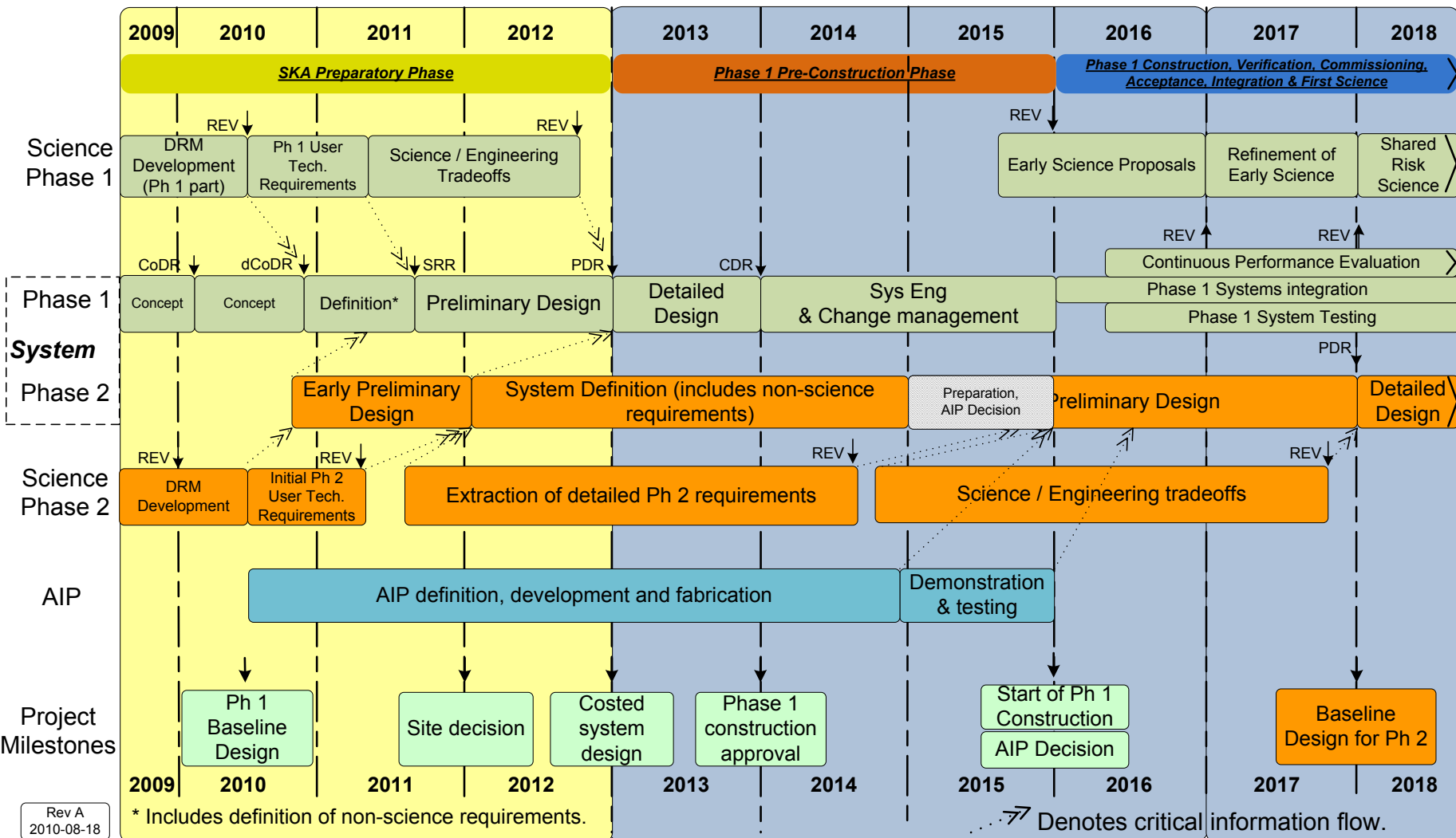
- SKA1:
 - Build, integrate, test, operate
- AIP:
 - The expected outcomes will be data on: in-system performance; good estimates of volume manufacturing, deployment and maintenance costs; verified operational models in the physical environment; verified calibration models; risk assessments.
 - Evaluate maturity and readiness and make decision for inclusion into SKA2



Preliminary Design,
Cost/Performance Trade-offs for SKA2,
considering AIP technology.



- SKA2 :
 - Perform Preliminary Design
 - Consider AIP technologies for inclusion
 - Separate assessment of the AIP technologies will take place to determine whether its level of maturity is sufficient to be included in the SKA2 system.
 - Detailed design for SKA2 after the selection of design option is made.
 - Feed in actual SKA1 system performance and cost





Summary

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- The phased construction of the SKA enables the project to make maximum use of advances in technology.
- These modifications will have a large system impact and will require a thorough impact analysis prior to deployment.
- A limited number of SKA1 subsystems may be obsolete by the construction of SKA2, and will be decommissioned accordingly.

