

Scheduling and deferring control operations

It is expected that DSH.LMC needs to perform controlled sequence of actions, possibly requiring durations beyond the default TANGO command response time, interactions with different devices and some kind of dialing interaction (i.e. progress reporting) between communicating parties. The configuration of the antenna for observation, performing known safety or error handling actions (i.e. dish stowing after power cut) in response to alarms, or setting-up the feed vacuum level for operations are among the functionalities of DSH.LMC. What is the suggested approach in TANGO (or available tools) to implement this kind of “workflow” or sequenced operation, beyond the provided client API?

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