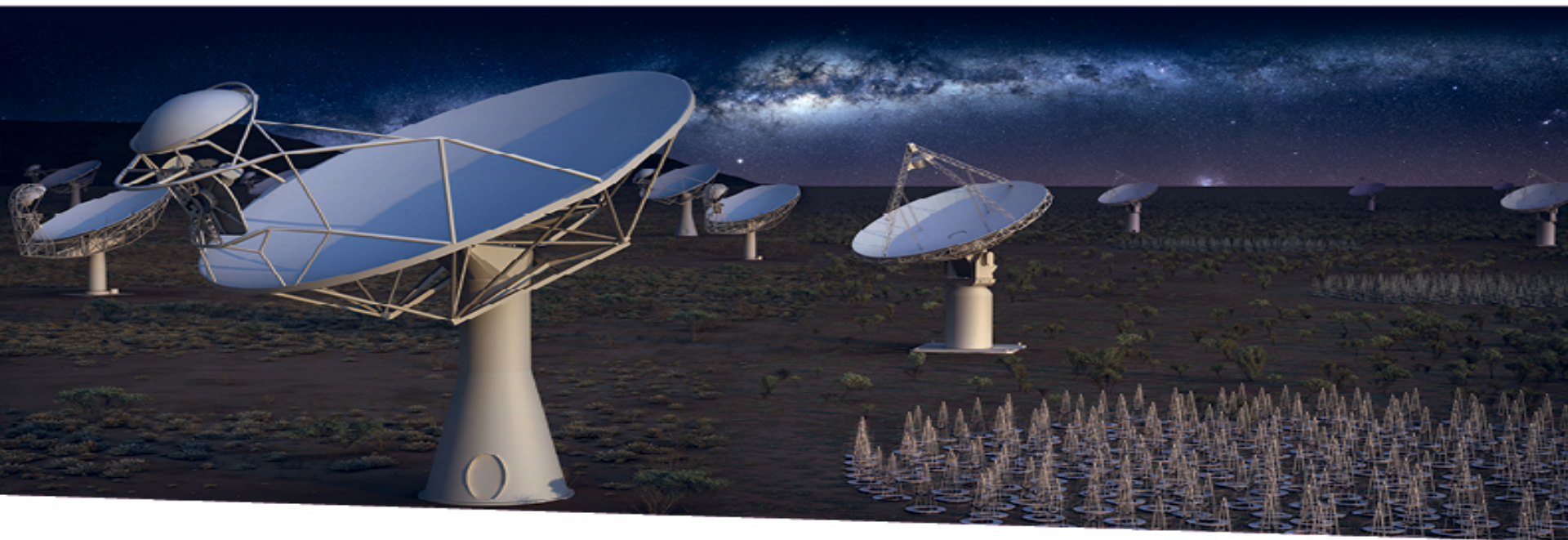


# Planning the Verification of the SKA1 Telescopes

2019 SKA Shanghai Meeting



**SQUARE KILOMETRE ARRAY**

Exploring the Universe with the world's largest radio telescope

**Richard T. Lord**  
26 November 2019

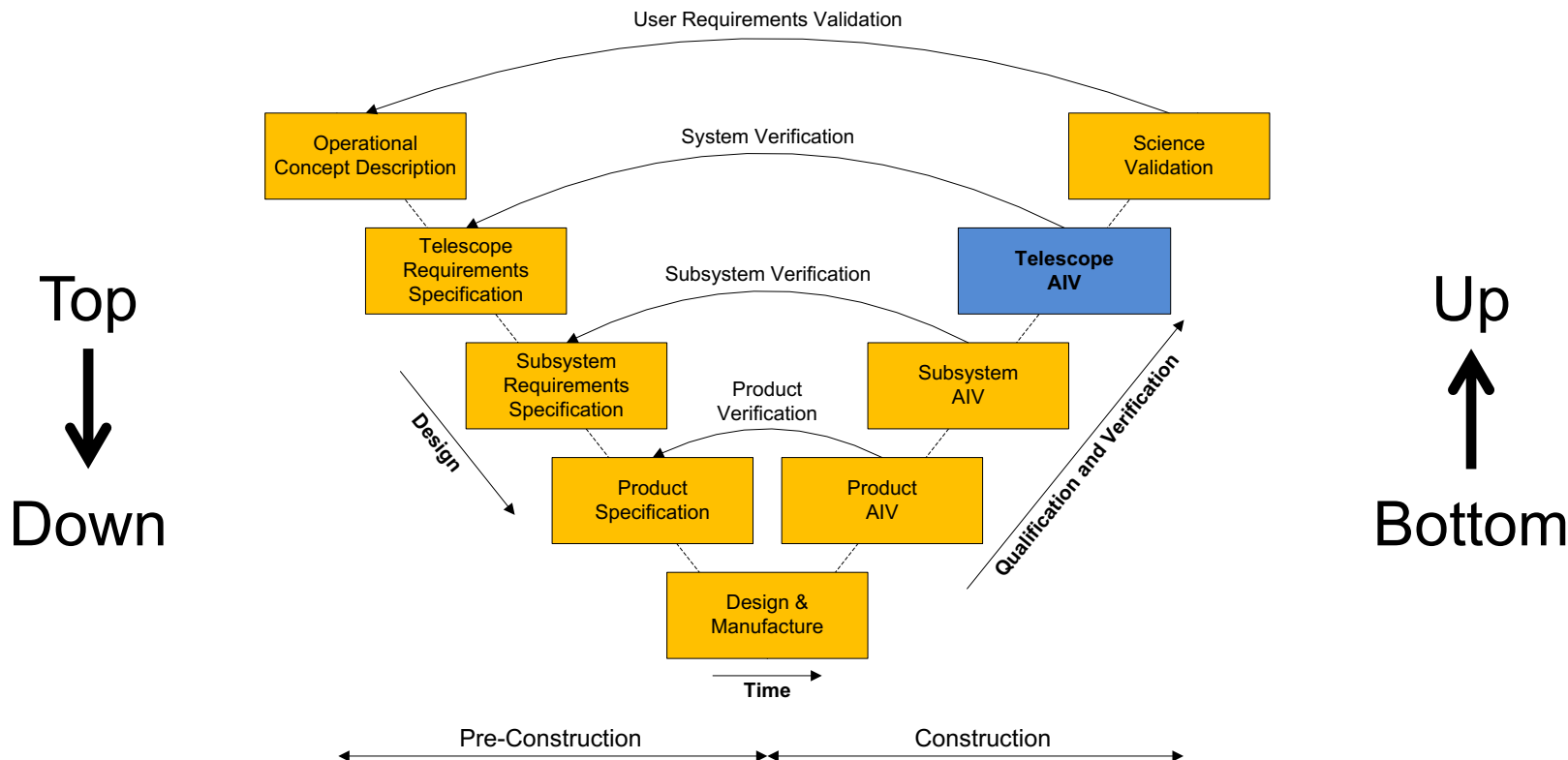
# Introduction

- Risk-based approach to verification planning
- Illustration and clarification of some of the key concepts regarding verification planning
- Lessons Learned

# It's all about Managing Risk

- Are we building the right thing?
  - Qualification of Design
- Are we building it correctly?
  - Verification of Requirements

# The Famous V-Diagram



# Element CDRs

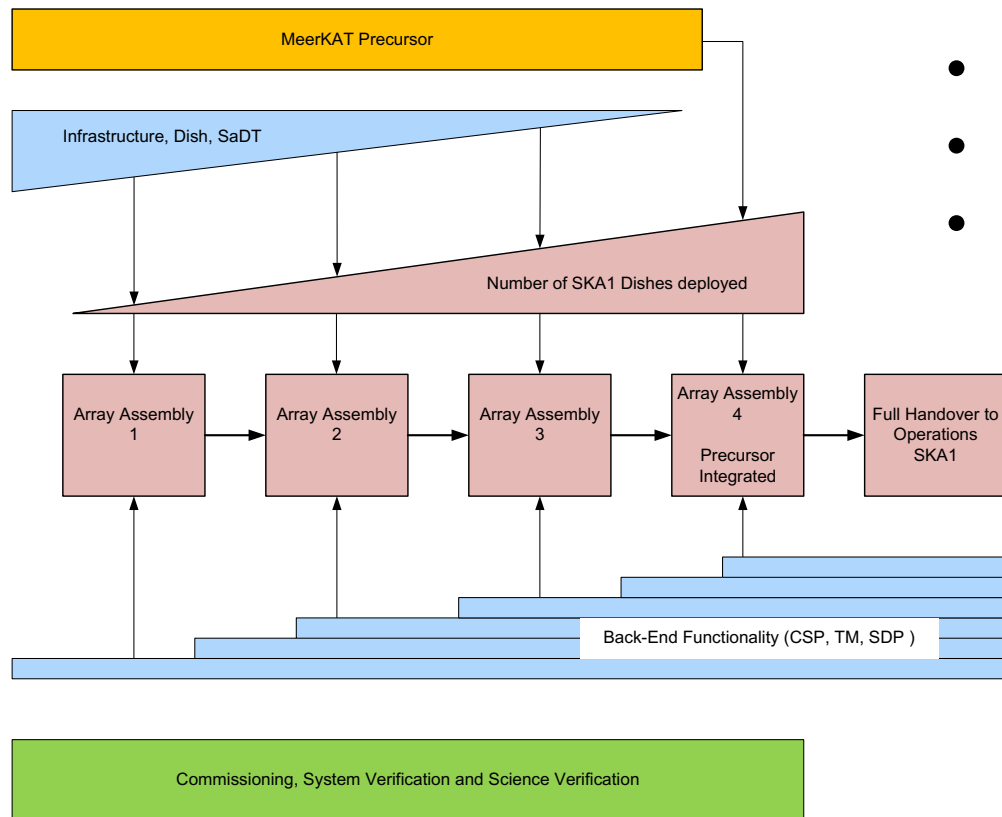
- Should provide evidence that design requirements have been met
- Heavy reliance on analysis
- Interfacing products do not exist
- Simulators/Emulators might mask problems
- Prototype hardware used
- Different levels of rigor applied

⇒ System-level risks remain after  
product-level designs have been qualified

# Product Hand-Over Process

- Important quality gate
- Well-tested products -> less system I&V issues
- Factory Acceptance Testing
- On-Site Acceptance Testing
- Product can be supported and maintained after hand-over

# Sequential Roll-Out



- Verify the system in stages
- Detect problems early
- Apply design changes early



















# Array Assemblies (AAs)

- Fixed number of Dishes / Stations
  - Determined by Correlator size
  - But: Flexibility regarding *which* Dishes / Stations
- Defined Capability / Functionality
  - Basis for the delivery of products and planning of I&V activities
- Start Date
  - When all AA components are available
  - But: Maintain I&V flexibility regarding exact product delivery date



# Observing Modes for each AA

	# Dishes	Frequency Bands	Imaging	Pulsar Timing	Dynamic Spectrum	Pulsar Search	Transient Capture	VLBI
AA1	8	Band: 1 + 2	 <ul style="list-style-type: none"> <li>Basic Continuum and Spectral Line imaging</li> <li>Using CASA</li> <li>16k channels</li> <li>400 MHz bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>Basic</li> <li>1 boresight non-steerable beam</li> <li>400 MHz bandwidth</li> </ul>				
AA2	64	Band: 1 + 2 Band: 5 (on 32 Dishes, but may not be supported by correlator)	 <ul style="list-style-type: none"> <li>Basic Continuum and Spectral Line imaging</li> <li>Using CASA</li> <li>16k channels</li> <li>800 MHz bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>6 steerable beams</li> <li>With de-dispersion</li> <li>800 MHz bandwidth</li> </ul>		 <ul style="list-style-type: none"> <li>16 steerable beams</li> <li>Not fully pipelined</li> <li>Non-real time operation</li> <li>Full bandwidth</li> </ul>		
AA3	128	Band: 1 + 2 Band: 5 (on 64 Dishes)	 <ul style="list-style-type: none"> <li>Continuum and Spectral Line imaging pipelines</li> <li>64k channels</li> <li>Zoom mode</li> <li>5200 MHz bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>16 steerable beams</li> <li>With de-dispersion</li> <li>Full bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>Maybe</li> </ul>	 <ul style="list-style-type: none"> <li>128 steerable beams</li> <li>Not fully pipelined</li> <li>Non-real time operation</li> <li>Full bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>Maybe</li> </ul>	
AA4	197	Band: 1 + 2 Band: 5	 <ul style="list-style-type: none"> <li>Full Continuum and Spectral Line imaging pipelines</li> <li>64k channels</li> <li>Zoom mode</li> <li>Full bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>16 steerable beams</li> <li>With de-dispersion</li> <li>Full bandwidth</li> </ul>	 <ul style="list-style-type: none"> <li>Supported by PST</li> </ul>	 <ul style="list-style-type: none"> <li>1500 steerable beams</li> <li>Fully pipelined</li> <li>Real time operation</li> <li>Full bandwidth</li> </ul>		 <ul style="list-style-type: none"> <li>4 beams</li> </ul>

# Integration Test Facility (ITF)

- Convenient environment to
  - install products
  - integrate with other products
  - test product-to-product interfaces
  - troubleshoot issues, etc
- Line-up of products to (partially) qualify the system-level design
- Verify new releases of software/firmware (and hardware), before installing on-site
- Knowledge transfer between contractors, engineers, AIV Team, Science Commissioning Team, etc

# Rolling-Out Software

- Scaled Agile Framework (SAFe ®)
- An agile process that allows scalability of overall team size by having “teams of teams”
- 3-month “cadence” called Program Increment
- Release on demand, develop on cadence
- Continuously builds value and reduces risk
- Has an evolving architectural runway
- Working product demonstrated frequently
- Regular stakeholder engagement

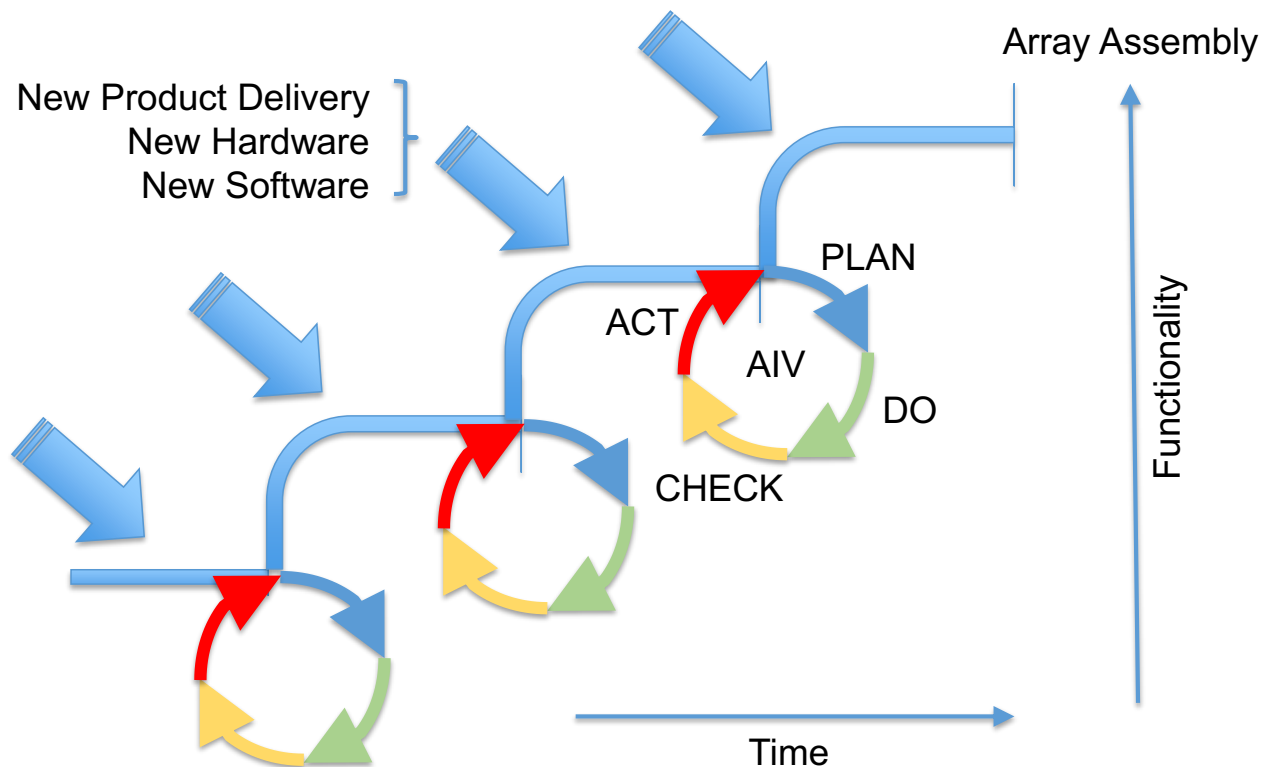


- Factory Acceptance Tests
- Delivery of hardware or software to site
- Site Acceptance Tests
- Major Verification Events
- Hand-over of responsibility from product contractor to SKAO

Useful to ensure that there are no gaps in the verification planning

(\*) Initiated by L. Stringhetti

# Iterative and Continuous Process



(Slide taken from P. Hekman)

# MeerKAT Precursor Integration

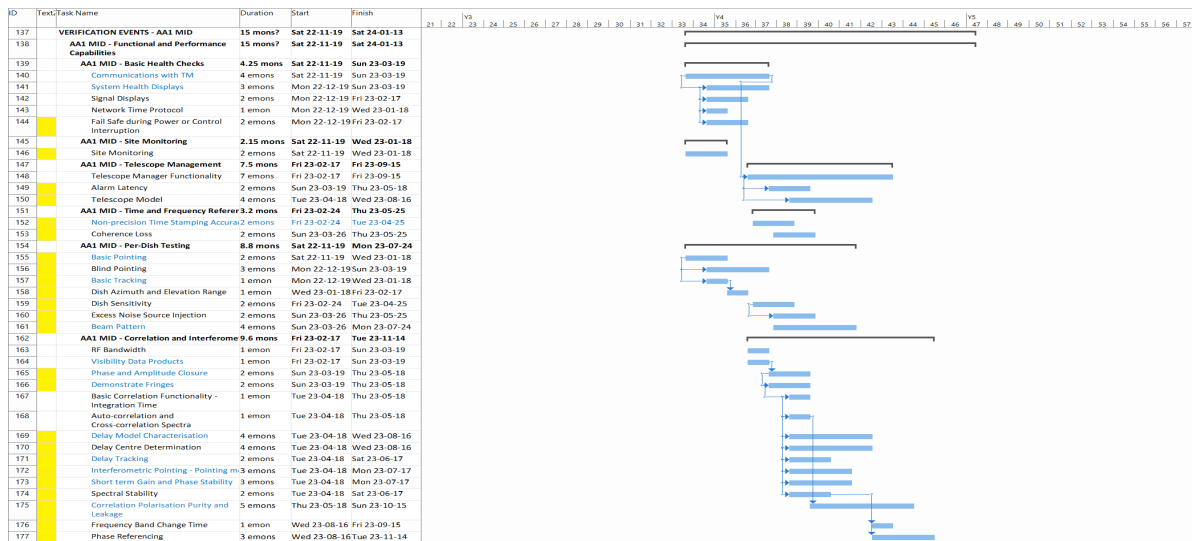
- Significant activity which carries schedule, technical and budgetary risks
- Requires careful roll-out planning
- Ensure that interfaces between MeerKAT components and SKA1-MID components are fully described



MeerKAT Precursor  
Telescope Dishes

# Integration & Verification Plan

- Structured framework, in which all integration and verification activities will be carried out in a coordinated manner



Gantt Chart showing Verification Events



# I&V Planning Level of Effort

Number of Engineering (Level-1) Requirements is about 650

		Integration Events	Verification Events	Test Procedures
SKA1-MID	ITF	20	13	25
	AA1	30	21	68
	AA2	35	27	86
	AA3		24	55
	AA4		22	28
SKA1-LOW	ITF	20	13	32
	AA1	20	21	70
	AA2	20	28	95
	AA3		27	105
	AA4		29	102

# Configuration Management

- Critical to the I&V effort
- Hardware / Firmware / Software configuration status of the Telescope shall be recorded with test results documentation

# Lessons Learned

- Roll-out activities and AIV work scope is often under-estimated, even at product level
- Separate R&D from construction
- The value of a qualified solution is immense (much more valuable than another unproven solution that looks good)
- Learn from prototypes
- Accurate and complete requirements (that are traceable to science goals) are very important, especially when placing contracts
- Properly qualify subsystems
- Integrate early!
- Get timely and effective support and maintenance

# Conclusions

- The SKA project is one of the largest scientific endeavours in history
  - Unprecedented scale
  - Remote sites
  - Global effort, etc
- It needs mature processes and thorough planning in order to succeed
  - Stakeholder management
  - Project management
  - Standardisation of tools
  - Issue tracking
  - Requirements management
  - Configuration management
  - Change management, etc
- Important to have a common Telescope roll-out vision across the project
- Keep looking at Lessons Learned

Thank You  
谢谢

