

# The Measurements and Calibrations for Large Radio Telescope (Tian ma 65m & SKA-P 15m)

Jinqing Wang(王锦清), Rongbing Zhao SHAO CAS

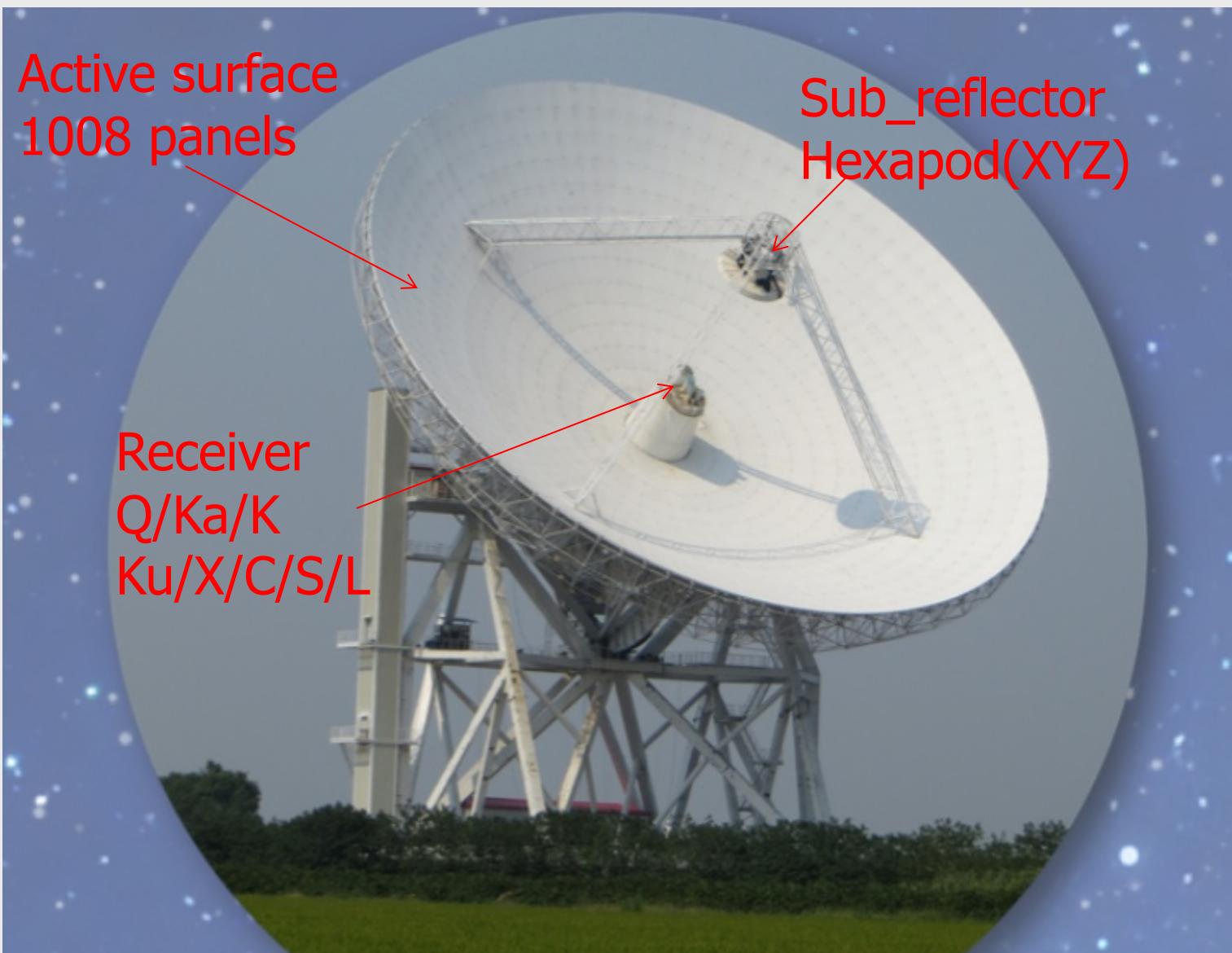
Yang Wu, Biao du CETC54

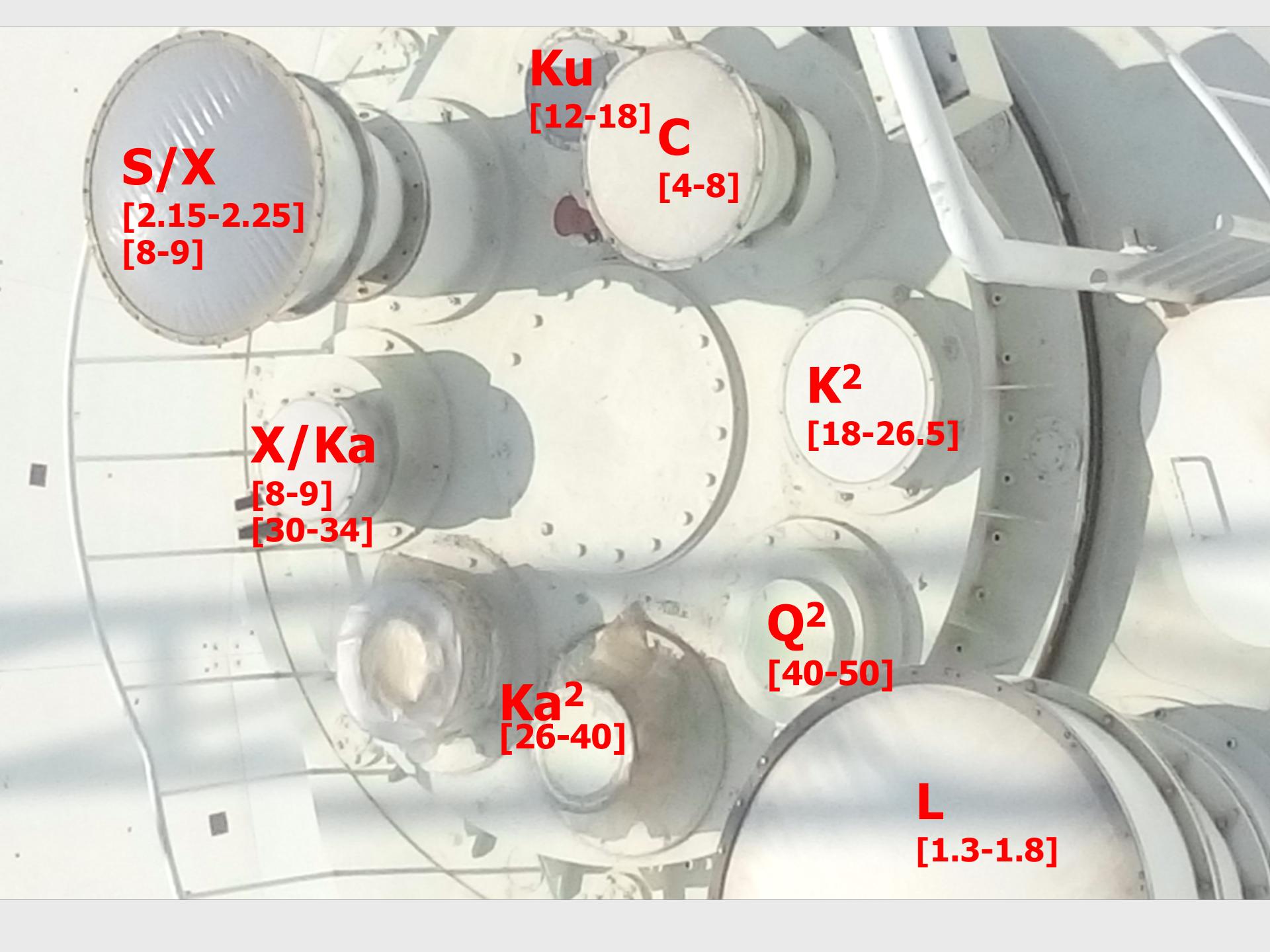
Michael Kesteven CSIRO

Liang Xiong, Lihua Zhang DFH Sat Co.

Shanghai SKA Meeting 2019

- ◆ Pointing model & separation
- ◆ Sub\_reflector model by amplitude method
- ◆ Antenna performance measurement
- ◆ Surface measurement by holography





**S/X**  
[2.15-2.25]  
[8-9]

**Ku**  
[12-18]  
**C**  
[4-8]

**X/Ka**  
[8-9]  
[30-34]

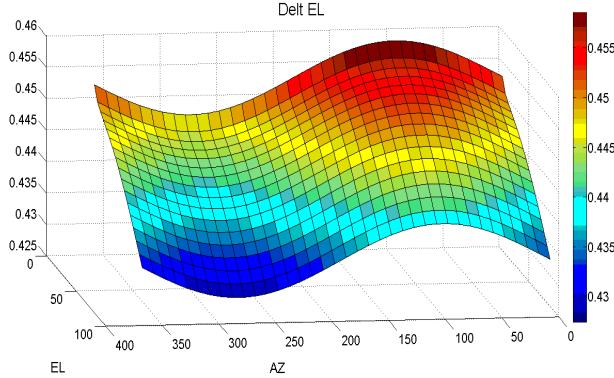
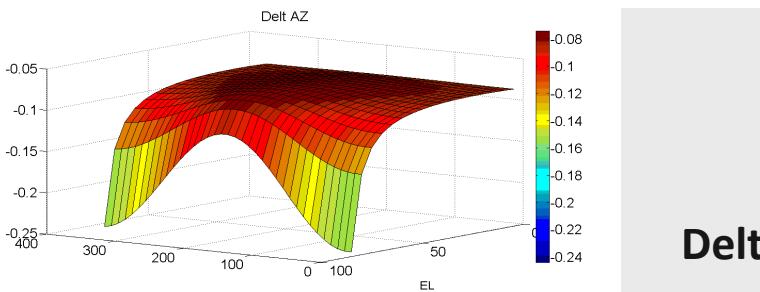
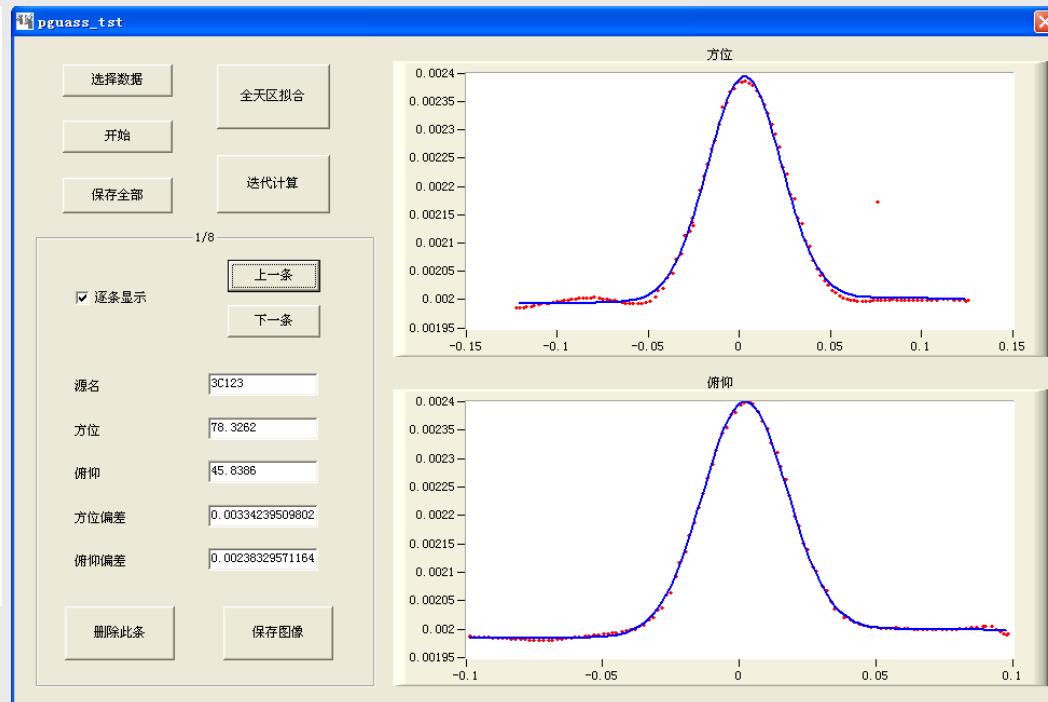
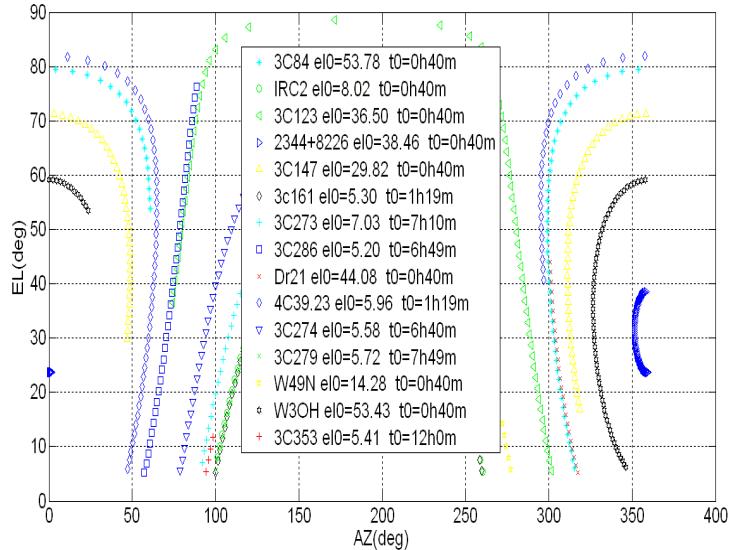
**K<sup>2</sup>**  
[18-26.5]

**Ka<sup>2</sup>**  
[26-40]

**Q<sup>2</sup>**  
[40-50]

**L**  
[1.3-1.8]

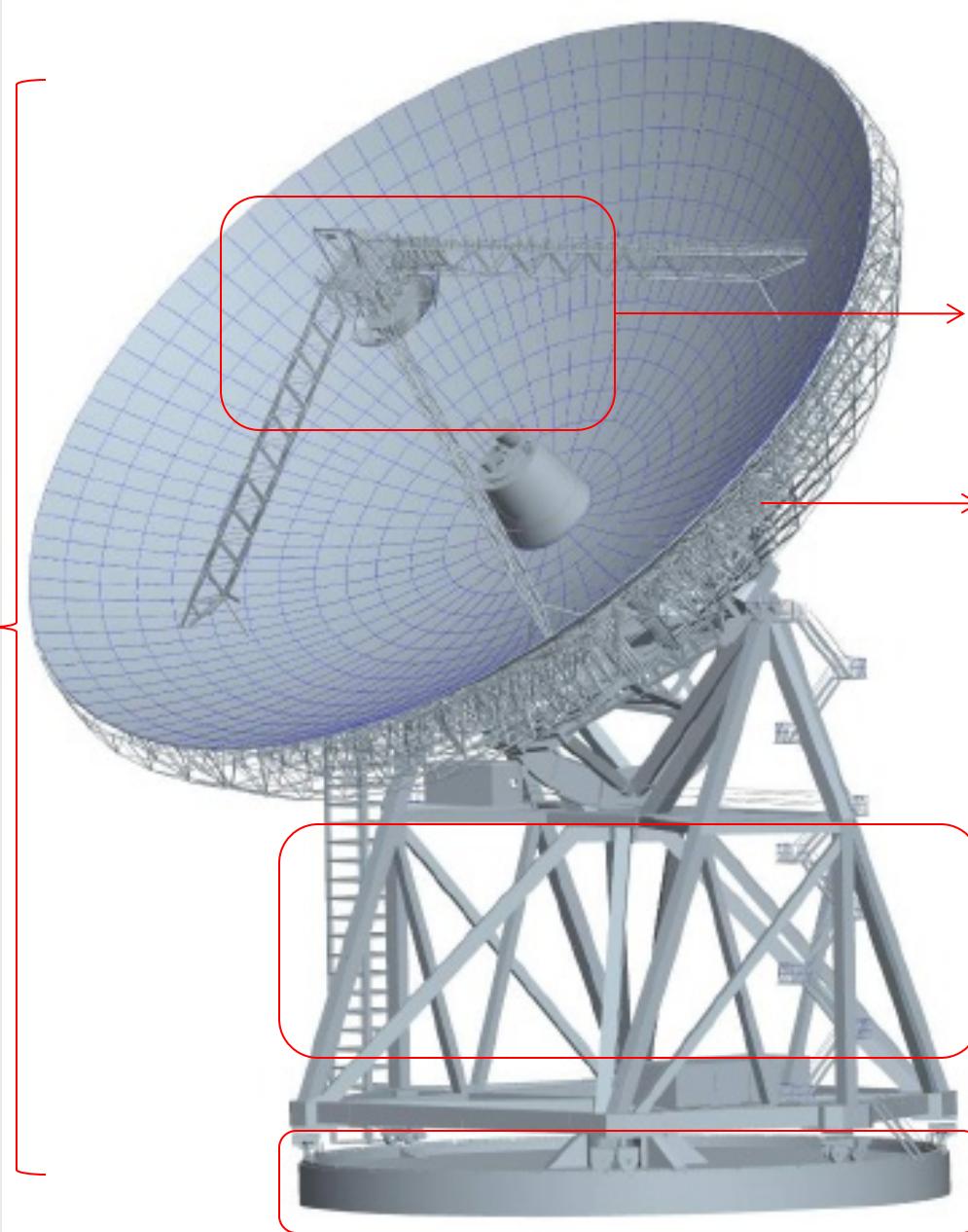
# Pointing Model Measurement



$$\text{Delt\_AZ} = C1 + \tan(E0) * \cos(A0) * C3 + \tan(E0) * \sin(A0) * C4 + \tan(E0) * C5 - 1 / \cos(E0) * C6$$

$$\text{Delt\_EL} = C2 - \sin(A0) * C3 + \cos(A0) * C4 + \cos(E0) * C7 + C8 / \tan(E0)$$

Half-power  
tracking,  
Cross scan,  
Five point



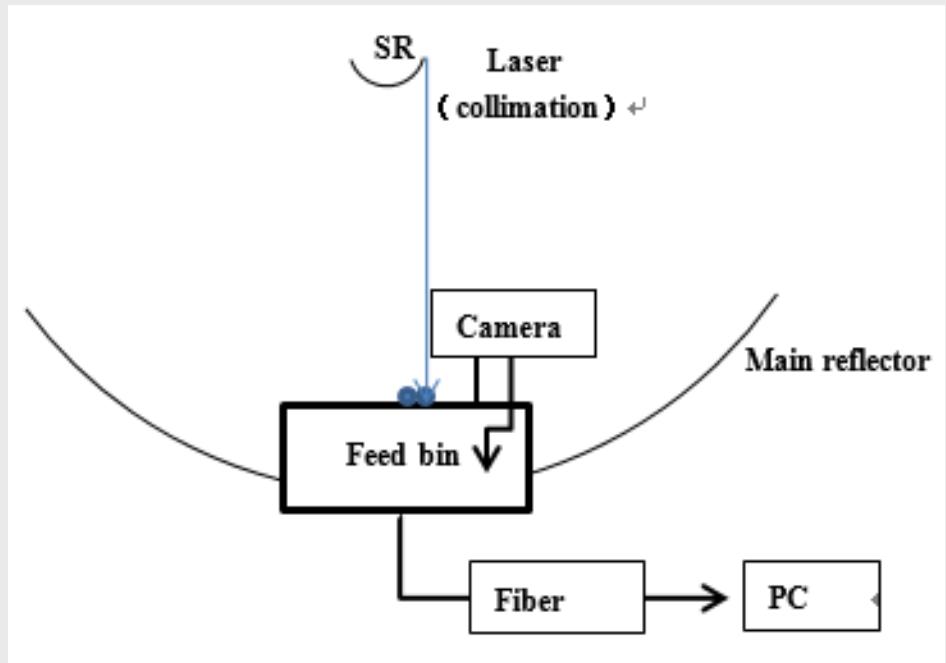
Sub-reflector:  
PSD+temperature sensor

Backup structure:  
Gravity model +  
temperature sensor

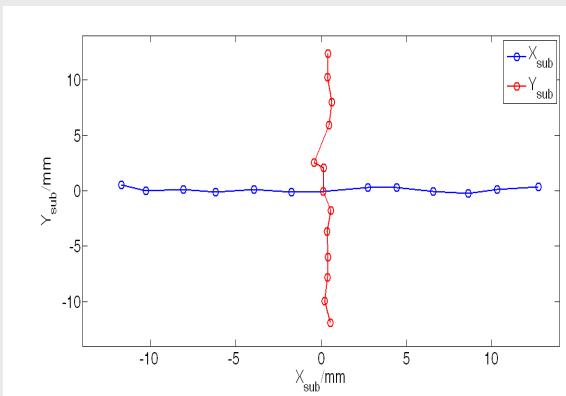
Frame:  
Tiltmeter +  
temperature sensor

Track:  
tiltmeter

# Pointing error caused by sub-reflector

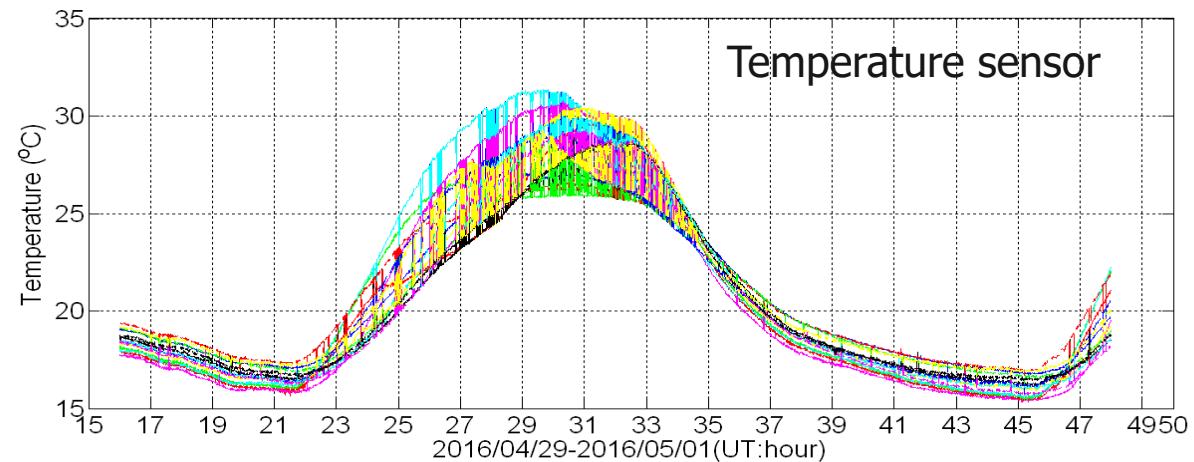
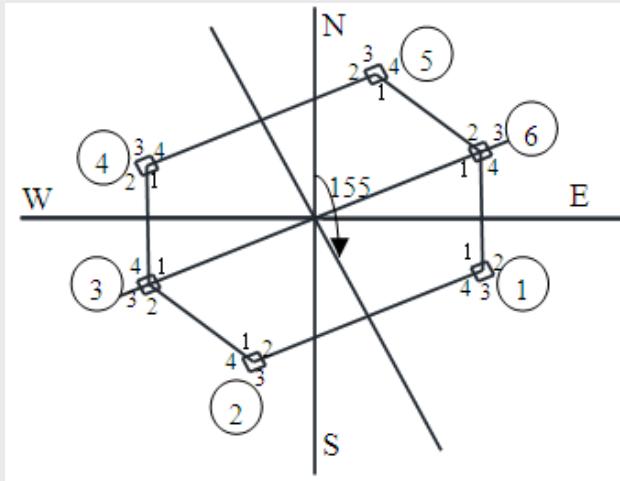
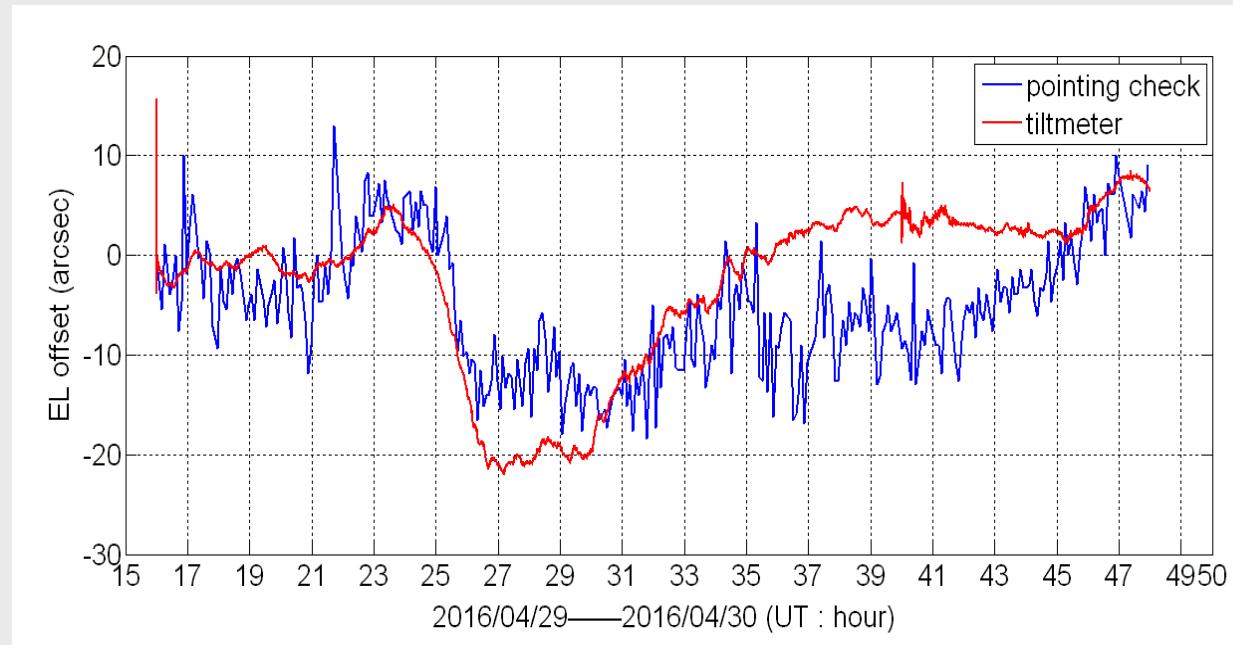
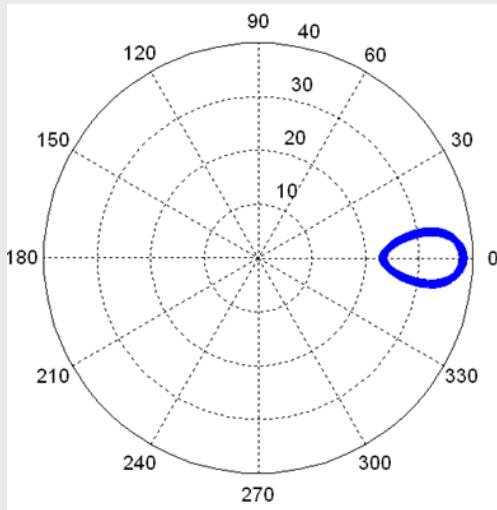


$$\begin{pmatrix} X_{sub} \\ Y_{sub} \end{pmatrix} = \begin{pmatrix} \alpha & 1 \\ 1 & \beta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 & k \\ 0 & 1 \end{pmatrix} \begin{pmatrix} X_{PSD} \\ Y_{PSD} \end{pmatrix} - \begin{pmatrix} X_{offset} \\ Y_{offset} \end{pmatrix}$$



# Pointing error caused by frame temperature

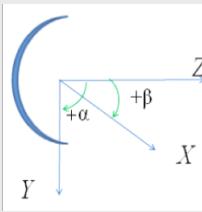
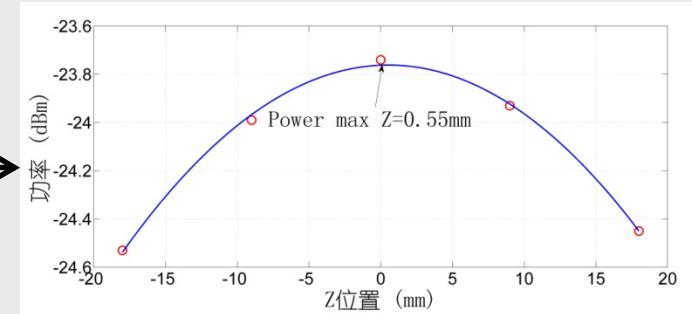
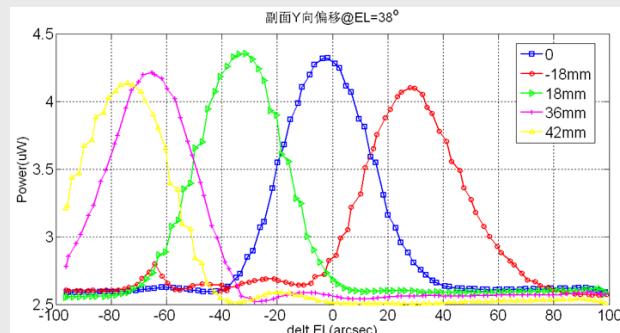
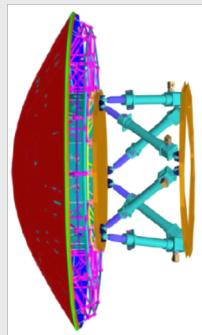
Source: 2344+8226



# Sub\_reflector Model

Amplitude sweep(active sub-reflector)

Aperture phase(holography)



X 方向位移(mm)

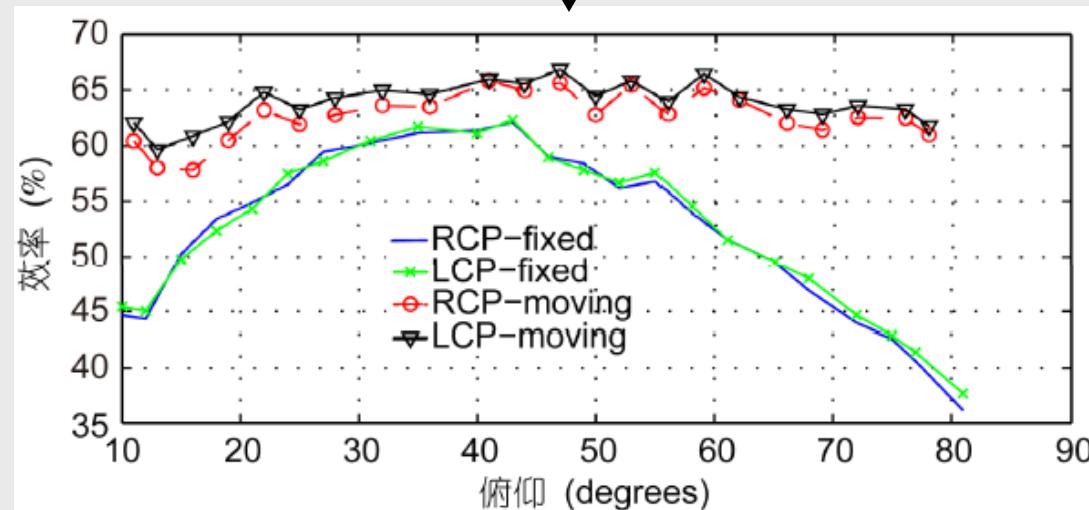
Y 方向位移 (mm)

Z 方向位移 (mm)

$$dX = A + B \cos(\omega_x * el) + C \sin(\omega_x * el) \quad \omega_x = 3.797$$

$$dY = D + E \cos(\omega_y * el) + F \sin(\omega_y * el) \quad \omega_y = 3.032$$

$$dZ = G + H \sin(el)$$

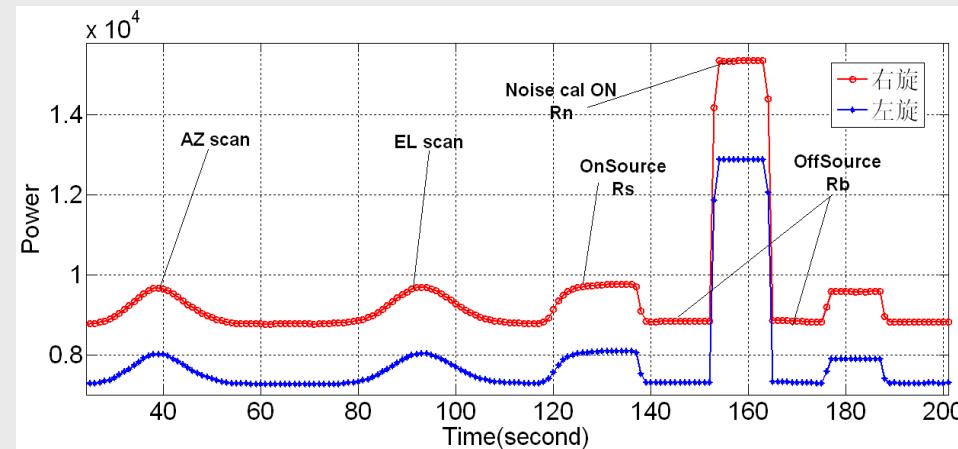
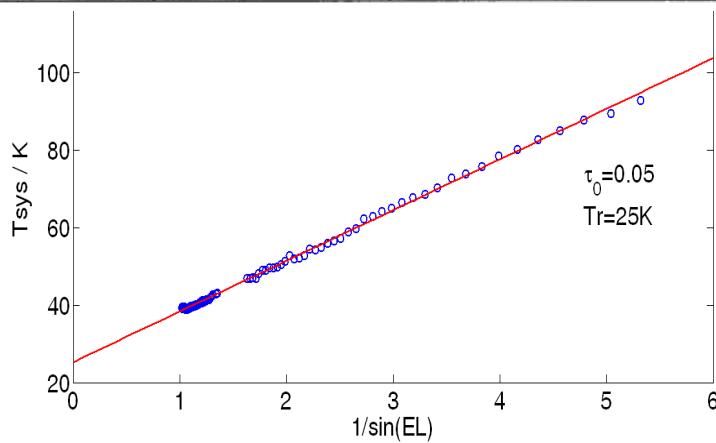


# Antenna performance measurement

Method: calibrated radio source + noise diode

1994A...284...331O

$\log S [\text{Jy}] = a + b * \log \nu [\text{MHz}] + c * \log^2 \nu [\text{MHz}]$					
source	range [MHz] from to		a	b	c
3C48	1408	23780	2.465	-0.004	-0.1251
3C123	1408	23780	2.525	+0.246	-0.1638
3C147	1408	23780	2.806	-0.140	-0.1031
3C161	1408	10550	1.250	+0.726	-0.2286
3C218	1408	10550	4.729	-1.025	+0.0130
3C227	1408	4750	6.757	-2.801	+0.2969
3C249.1	1408	4750	2.537	-0.565	-0.0404
VirA	1408	10550	4.484	-0.603	-0.0280
3C286	1408	43200	0.956	+0.584	-0.1644
3C295	1408	32000	1.490	+0.756	-0.2545
3C309.1	1408	32000	2.617	-0.437	-0.0373
3C348	1408	10550	3.852	-0.361	-0.1053
3C353	1408	10550	3.148	-0.157	-0.0911
CygA	4750	10550	8.360	-1.565	—
NGC7027	10550	43200	1.322	-0.134	—



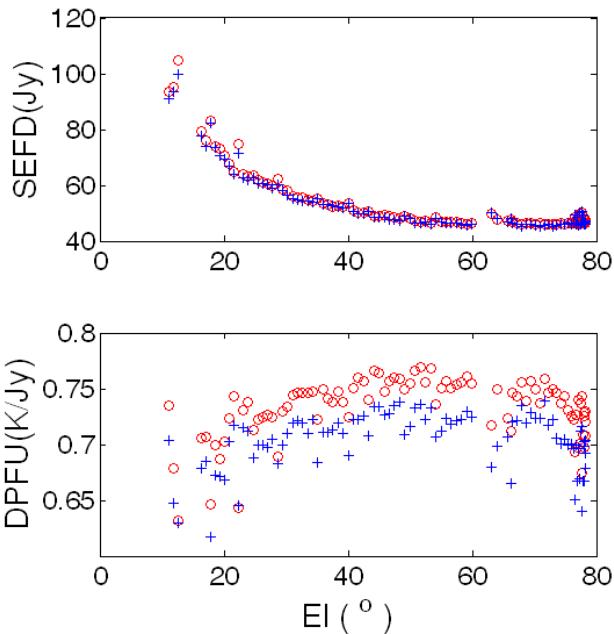
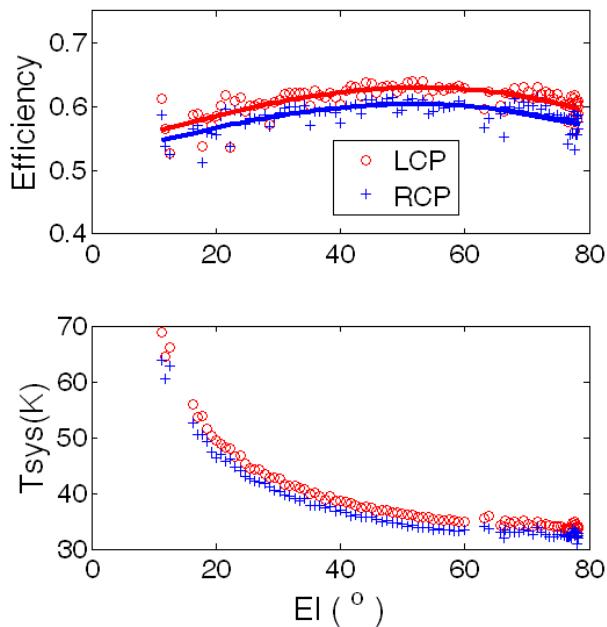
$$\eta(\varphi) = \frac{2kT_{as}(\varphi)K_1K_2K_3K_4K_5}{SA_g}$$

$$K_1 = \exp(\tau_0 / \sin El)$$

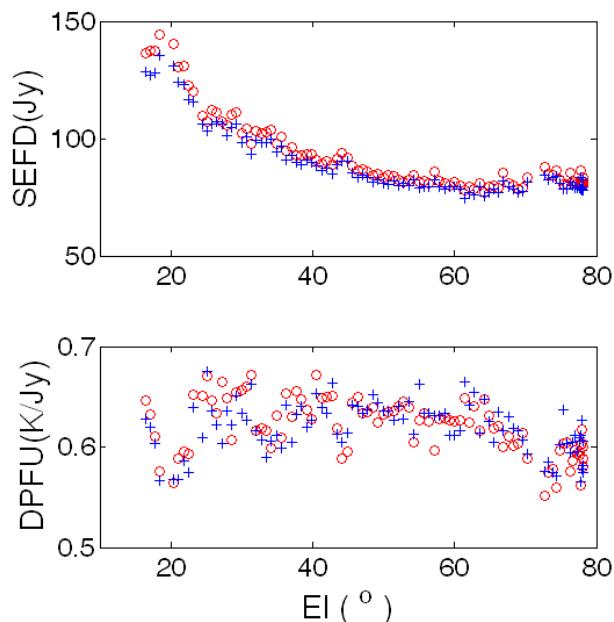
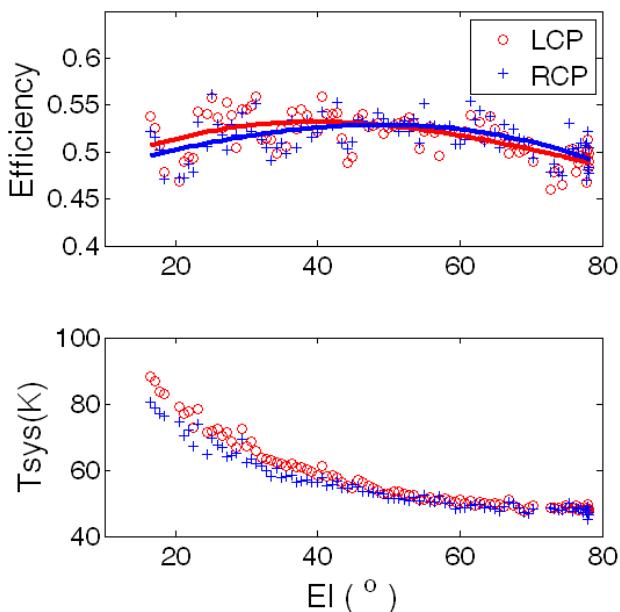
$$T_{as} = \frac{(R_s - R_b)}{R_N - R_b} T_{cal}$$

$$T_{sys} = \frac{R_b - R_0}{R_N - R_b} T_{cal}$$

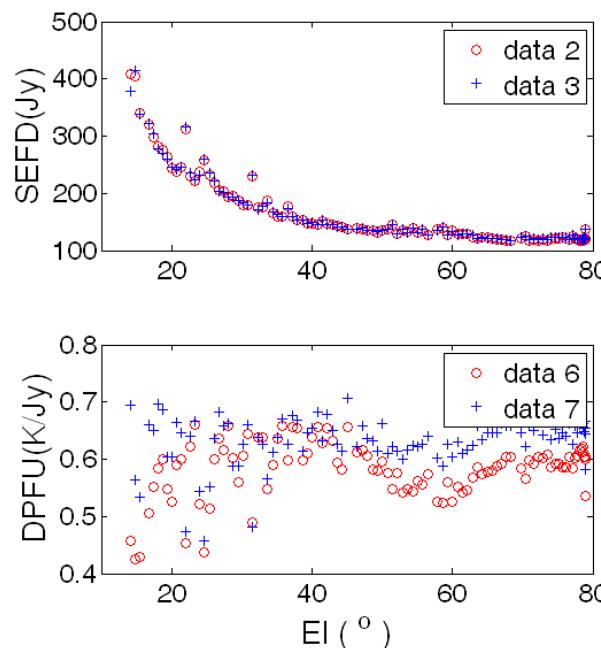
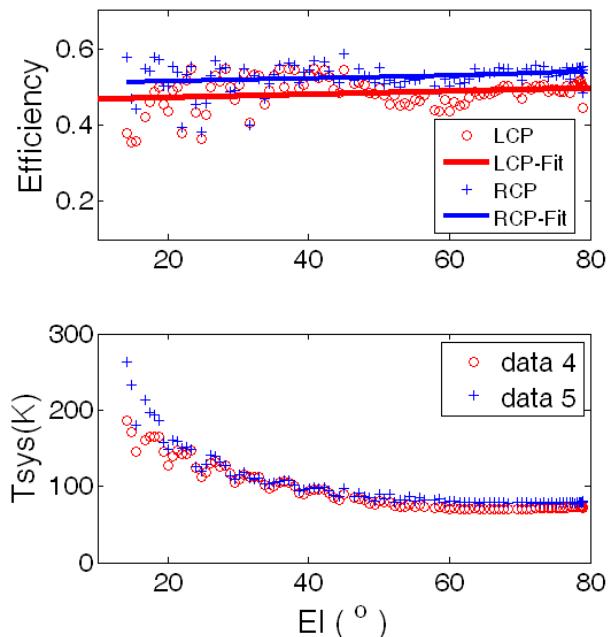
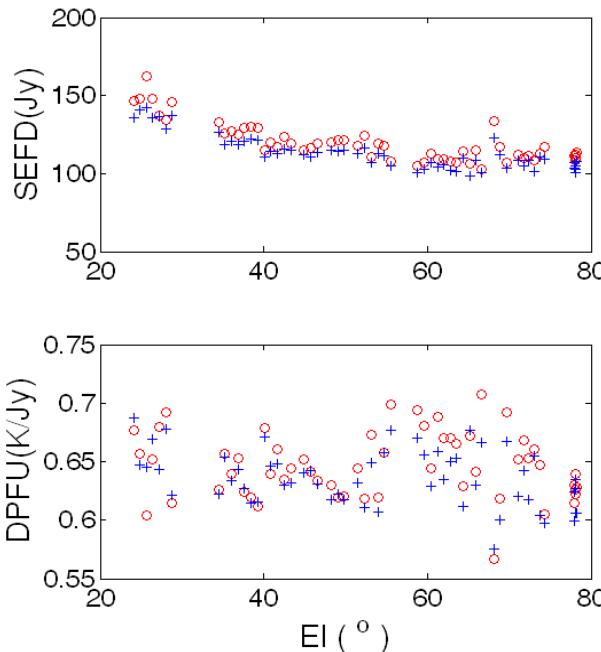
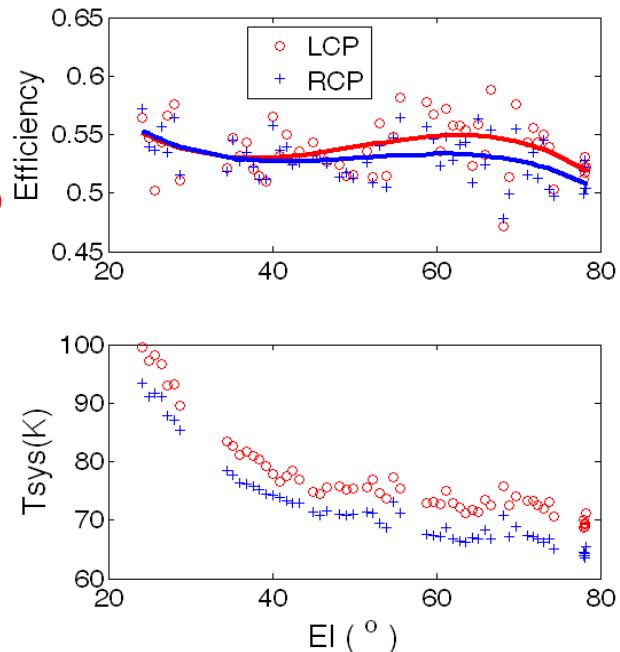
## Ku band (15.6GHz)



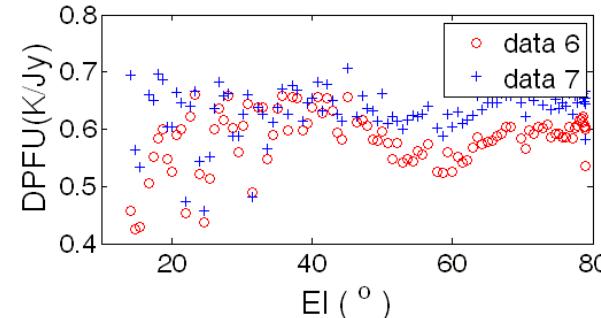
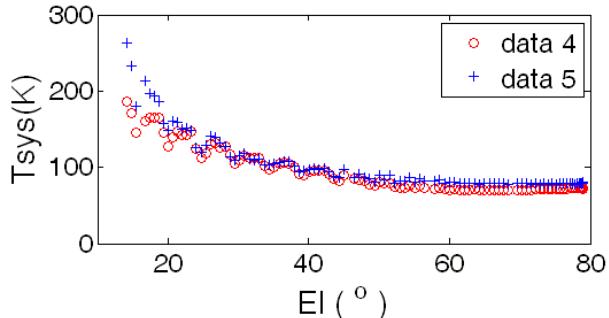
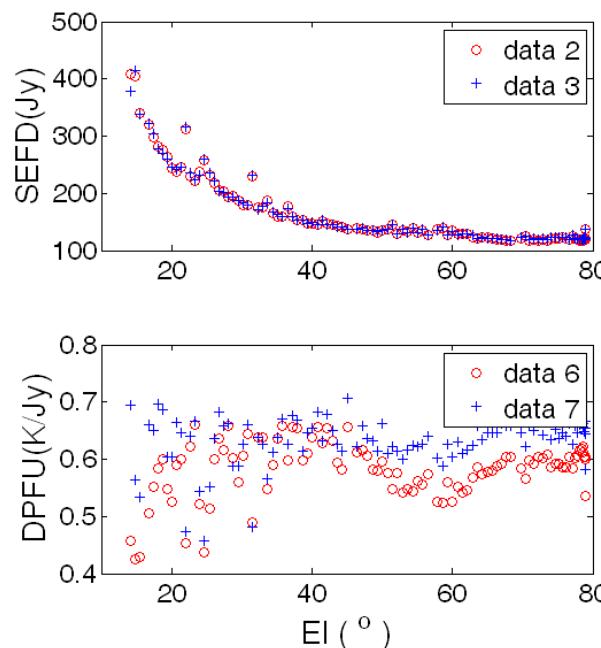
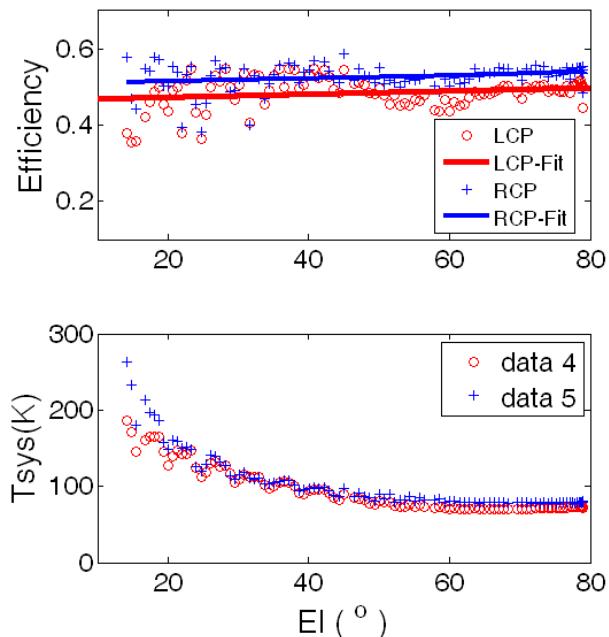
## K band (22GHz)



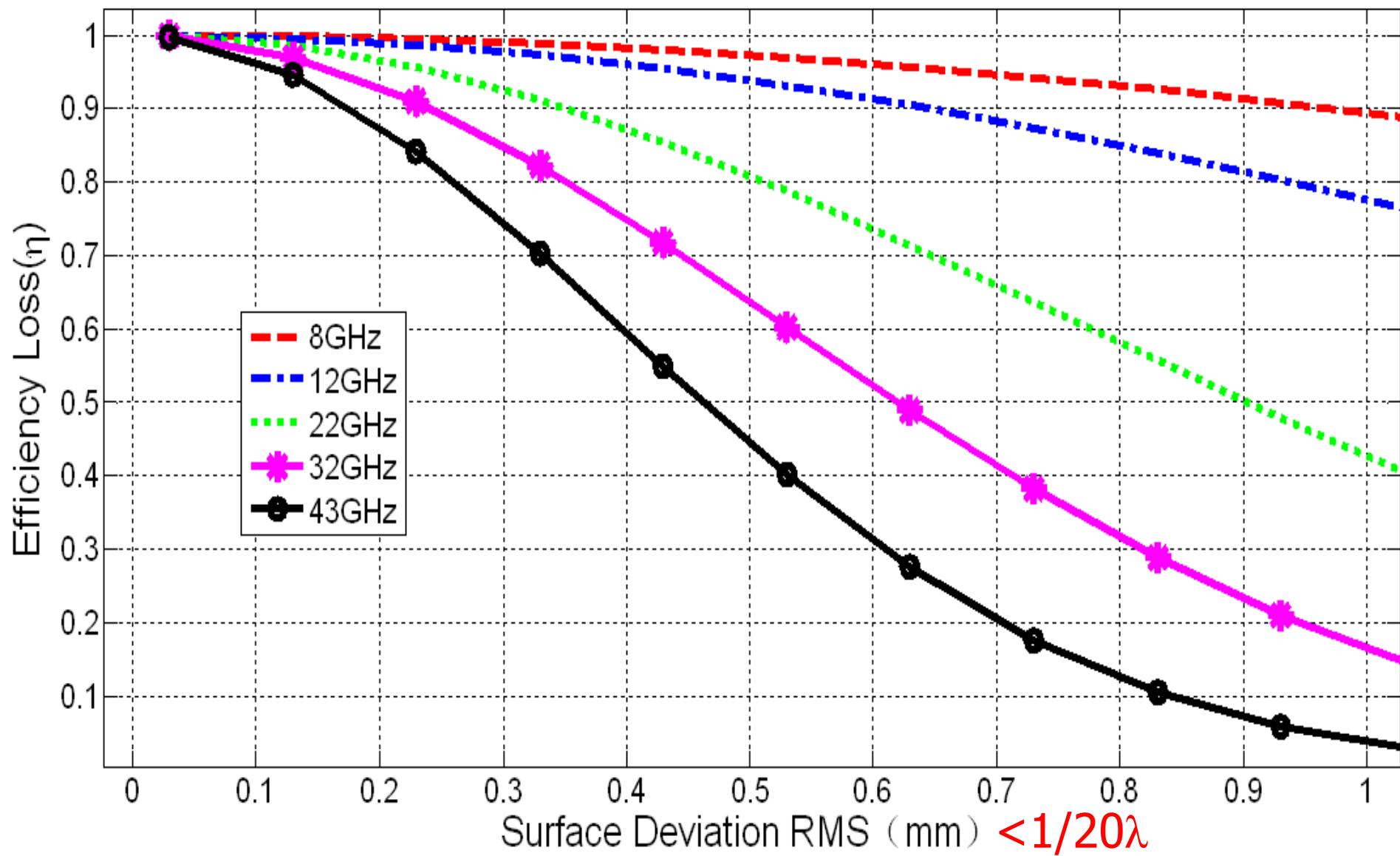
## Ka band (31.1GHz)



## Q band (43GHz)



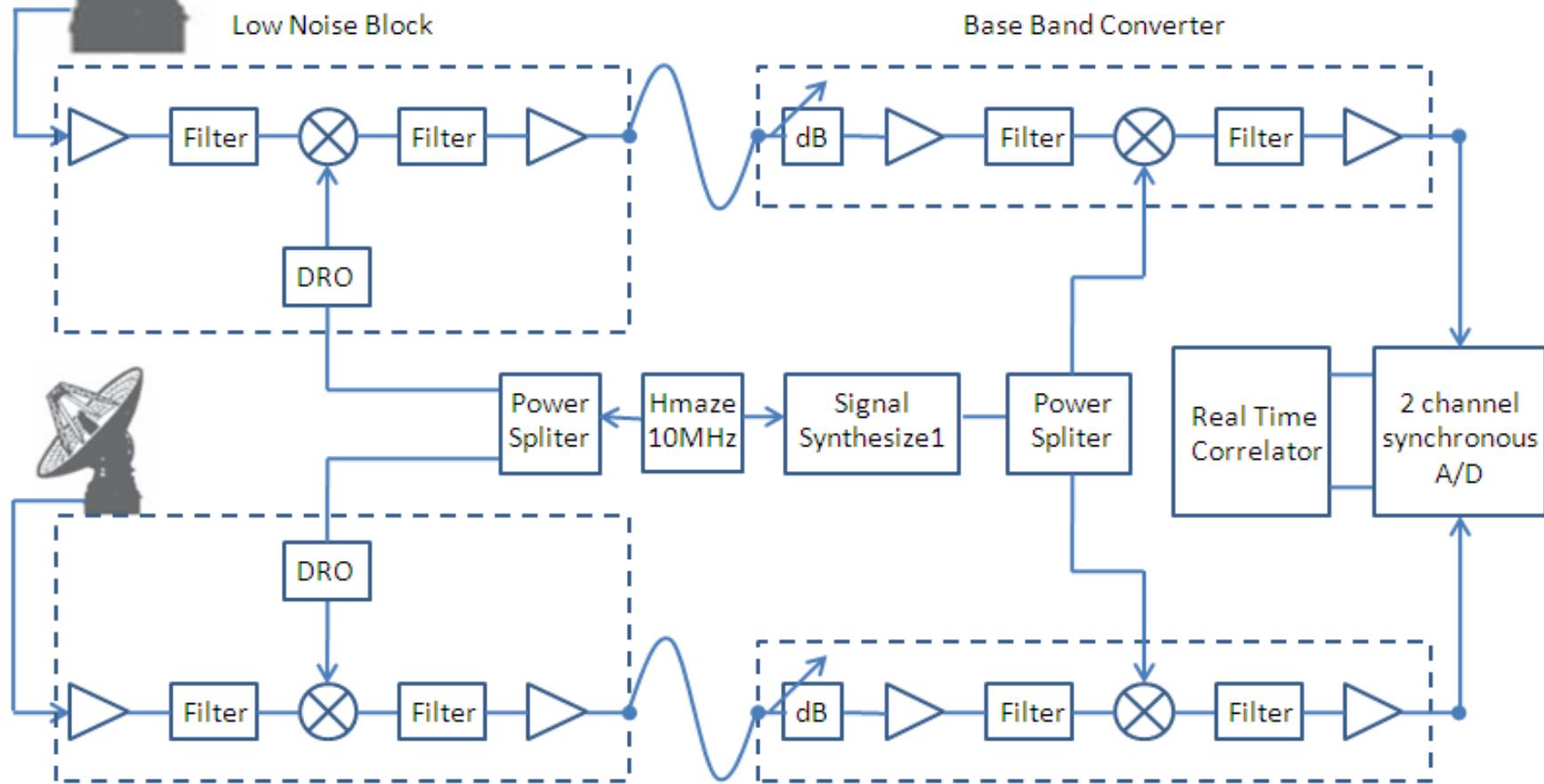
# Microwave holography for surface accuracy measurement

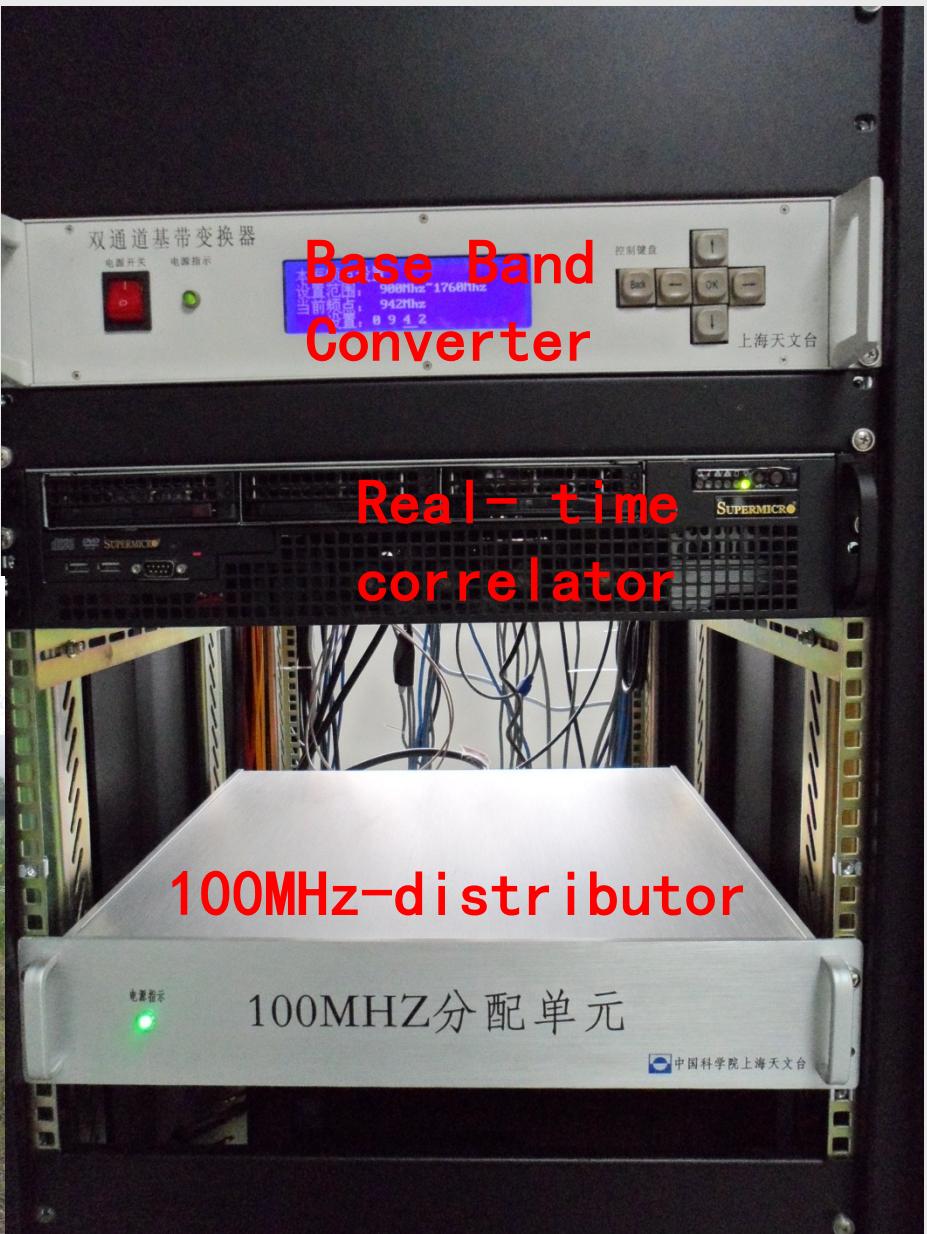


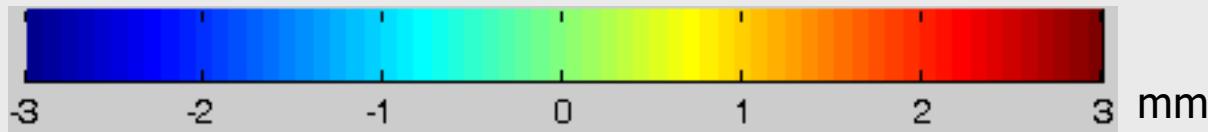
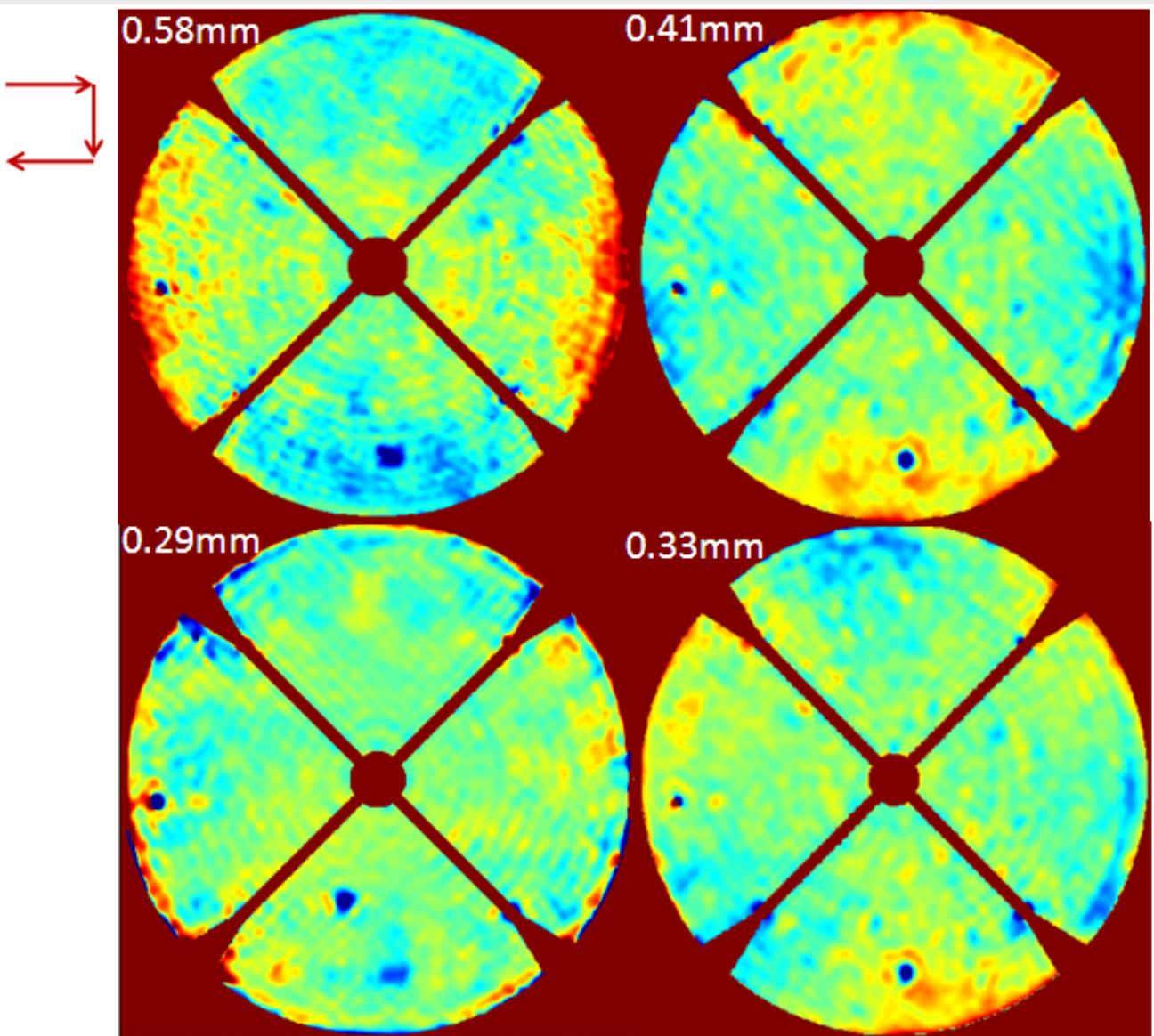


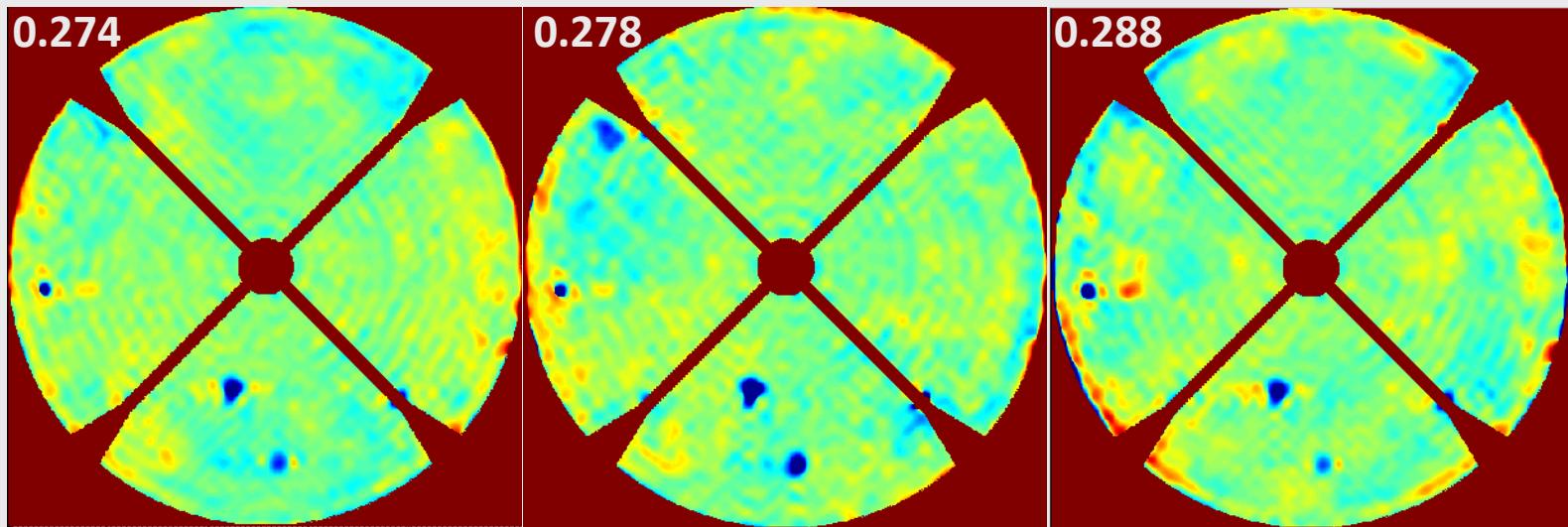
Input freq = 12.2GHz ~ 12.75GHz  
Output freq = 900MHz ~ 1450MHz  
Gain = 60dB  
LO = 11.3GHz

Input freq = 900MHz ~ 1450MHz  
Output freq = 100KHz ~ 15MHz  
Gain = 30dB  
Adjustable Atten = 30dB



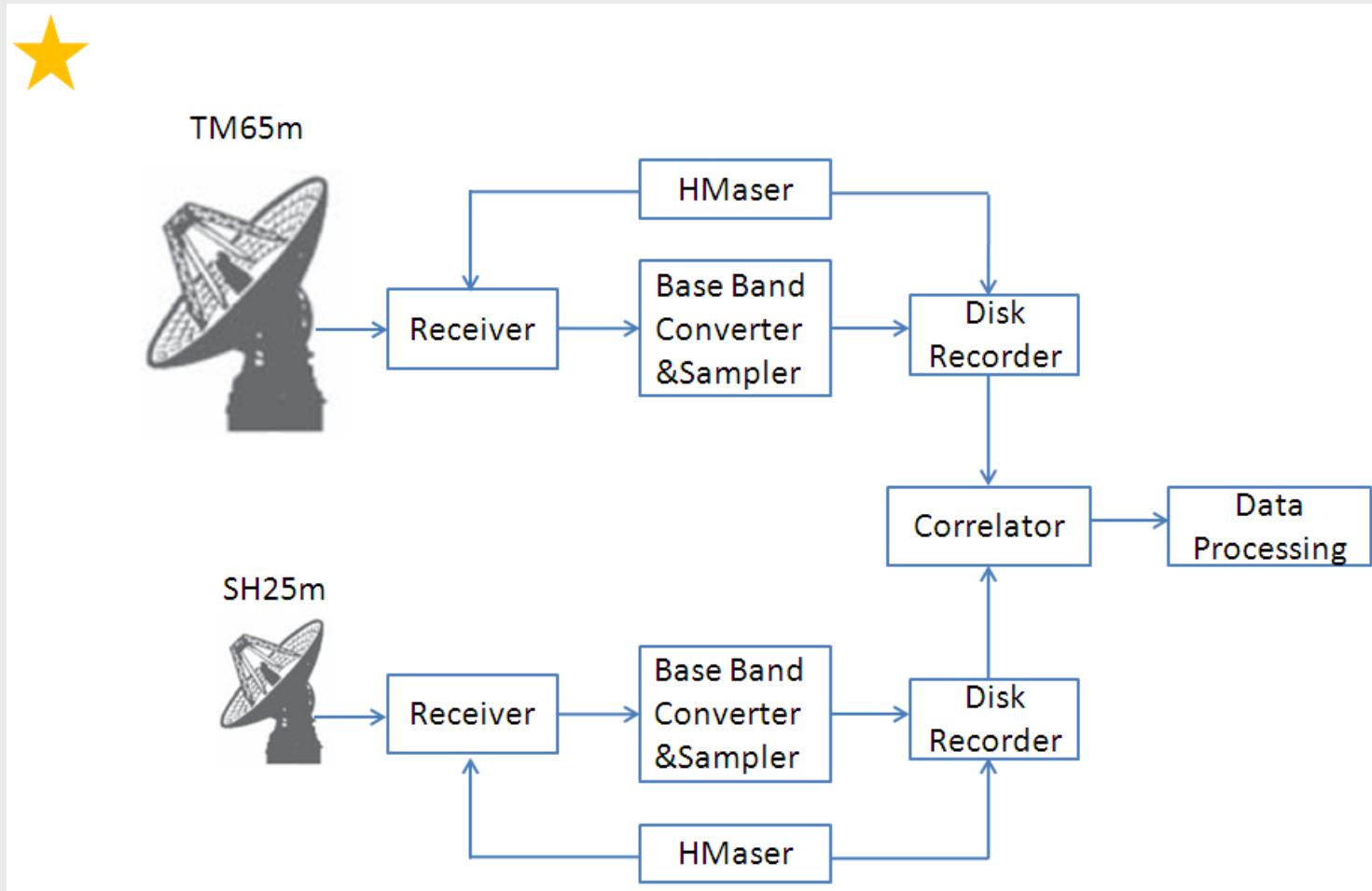






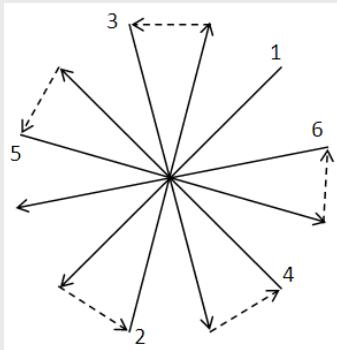
D(m)	65	63	60	58	56
RMS(mm)	0.274	0.267	0.257	0.251	0.243
	0.278	0.270	0.263	0.260	0.255
	0.288	0.281	0.273	0.263	0.256

# Main Surface Gravity Model Measurement by Short Baseline( $\sim$ 6km) VLBI

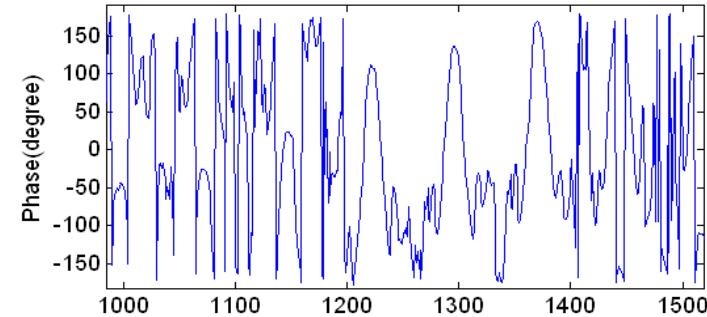
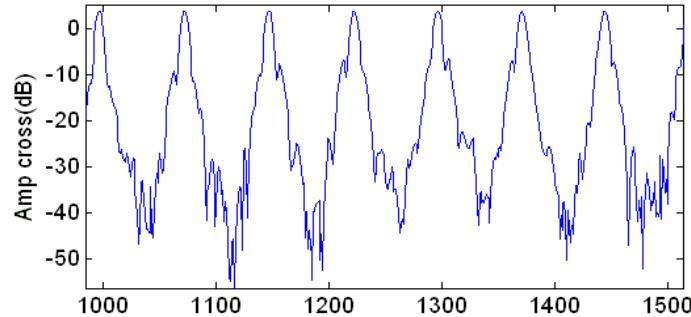
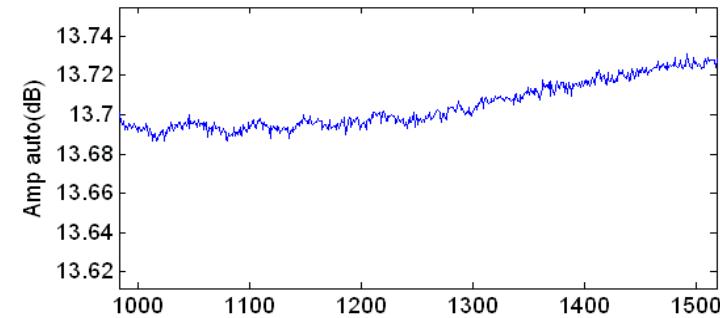
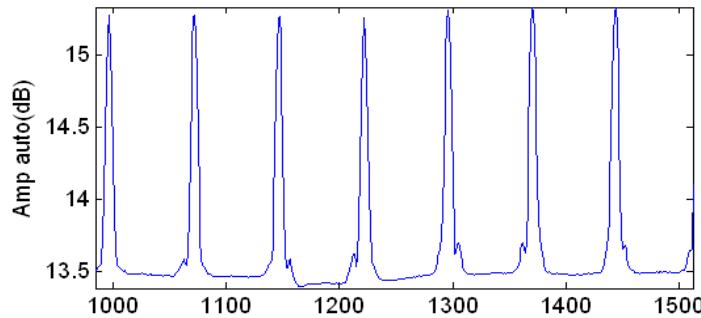


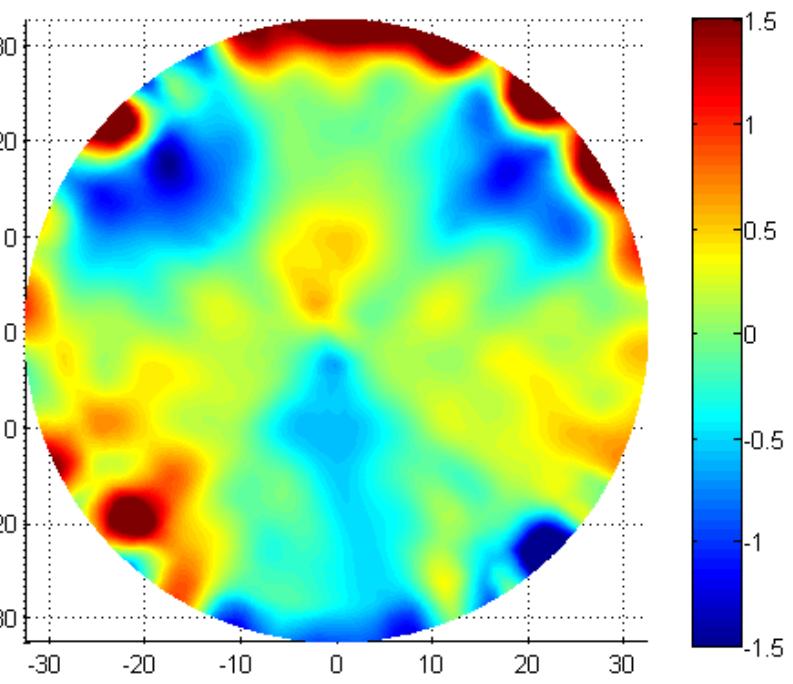
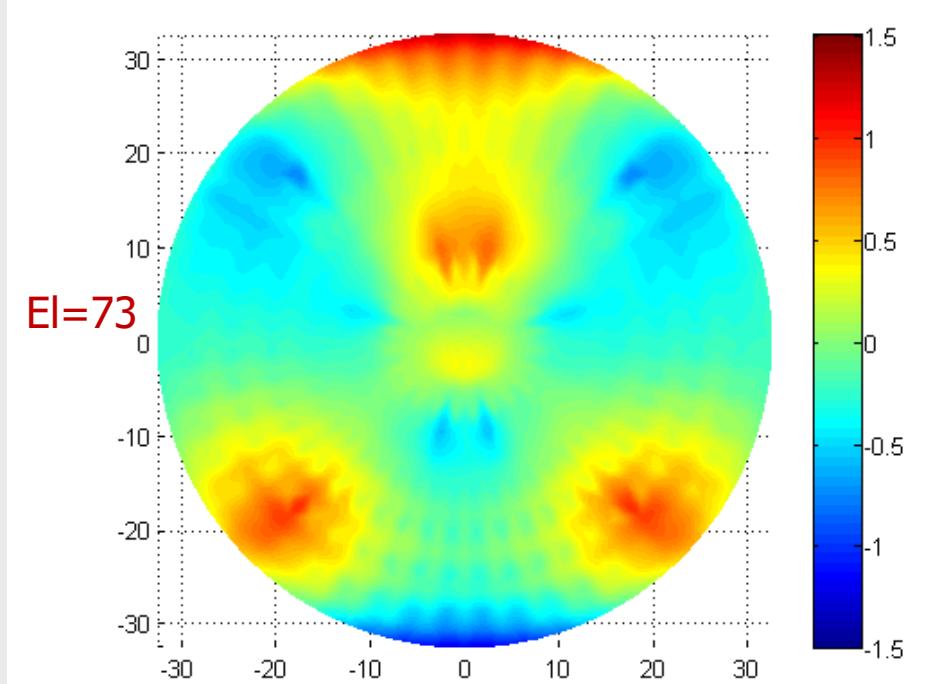
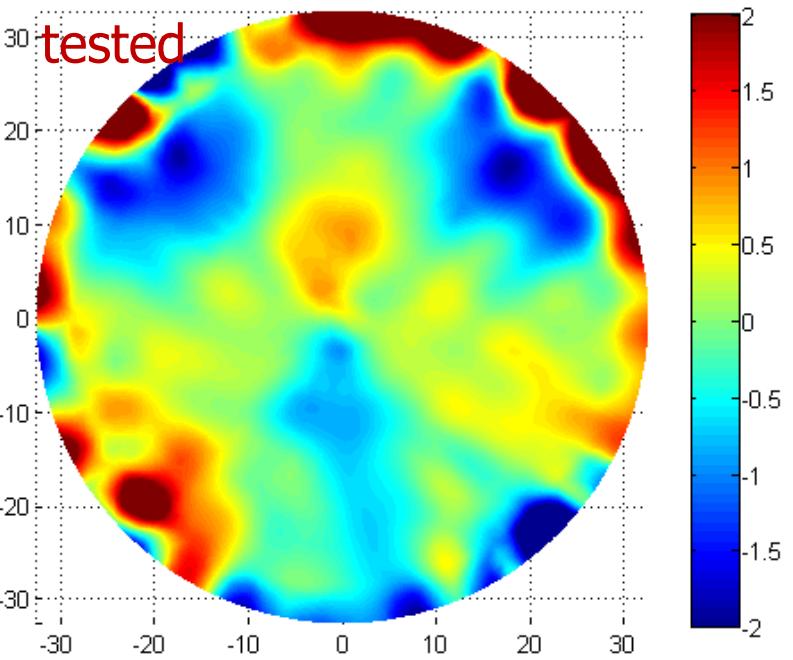
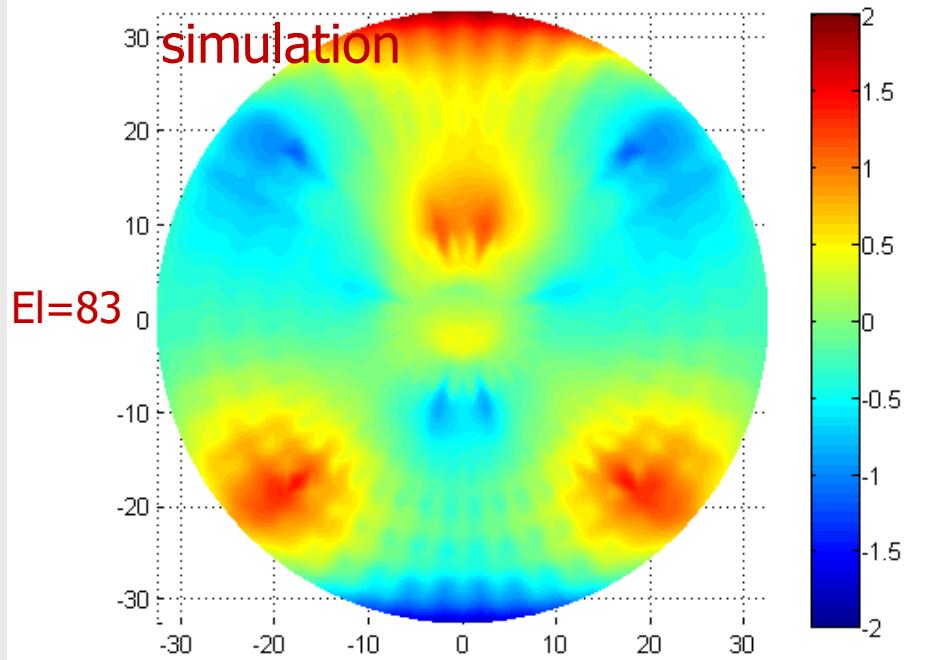
# Radial sweep and correlation

Radial sweep

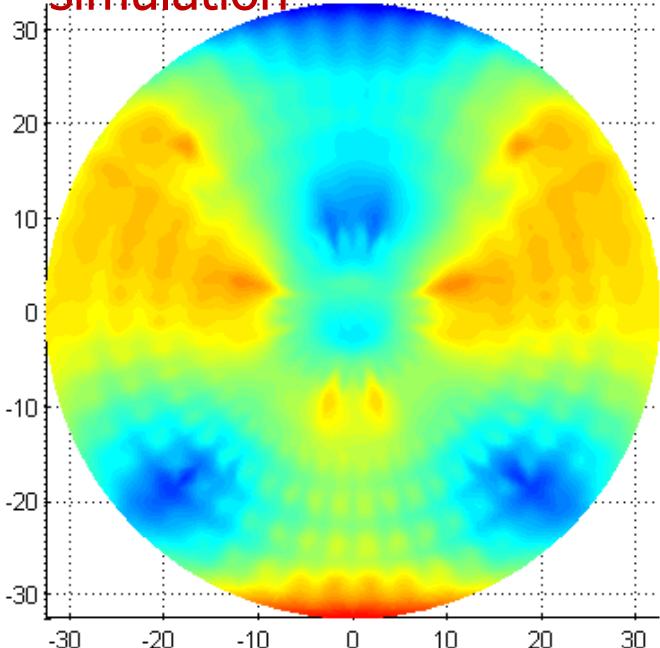


**One pattern:~20minutes**  
**Resolusion:~3m**  
**Meaure error:~0.17mm**  
**Radio source:3C84**  
**Integeeration time:1second**  
**Freq&Bandwidth:8.4GHz&16MHz**

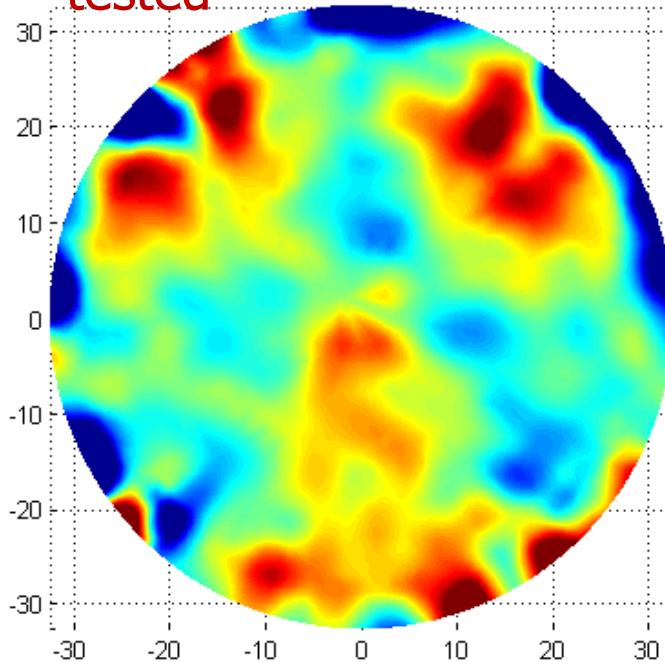




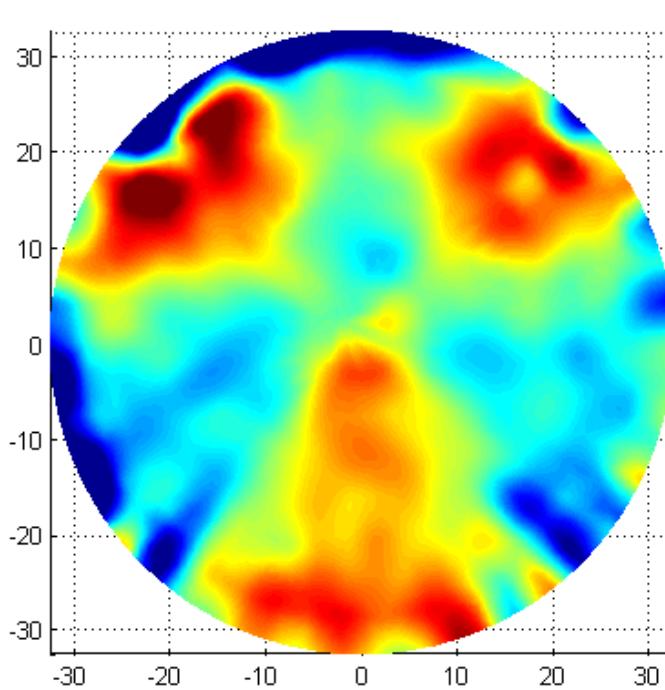
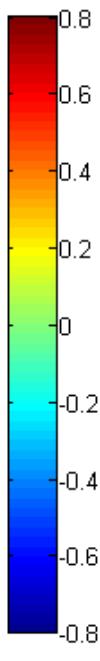
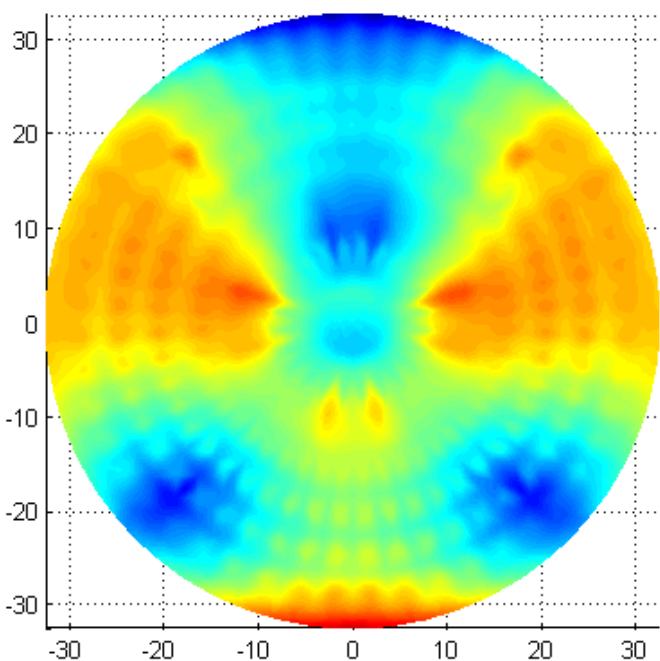
simulation



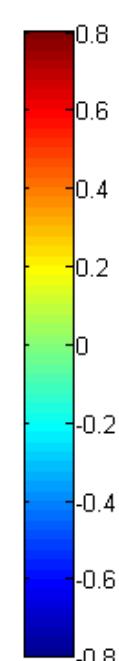
tested



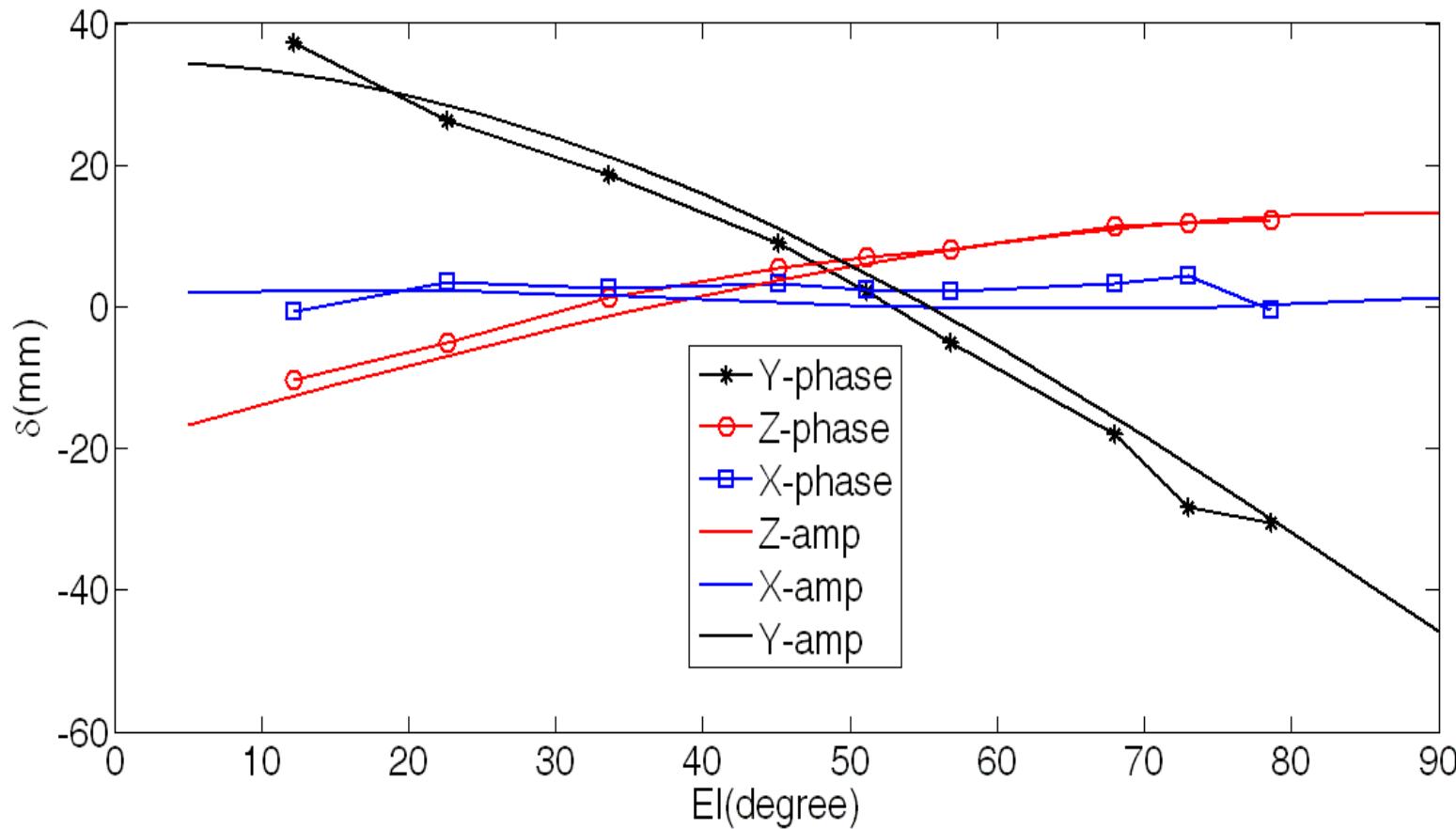
EI=43



EI=33



**Sub-reflector XYZ position derived from holography aperture phase  
VS  
the sub-reflector model constructed from amplitude sweep**



# SKA-P Satellite Holography

- ◆ Satellite Asia 4 @ 12.25GHz ,Elevation is about 45degrees
- ◆ Aperture resolution 0.5m (31 scans in elevation)
- ◆ 50minutes for every measurement
- ◆ Energy taper is about -10dB at the edge. And the beam seems nice
- ◆ Surface error is about 0.3mm RMS
- ◆ Several datasets are collected, all results are reliable and repeatable( $\sim 30\mu\text{m}$ )

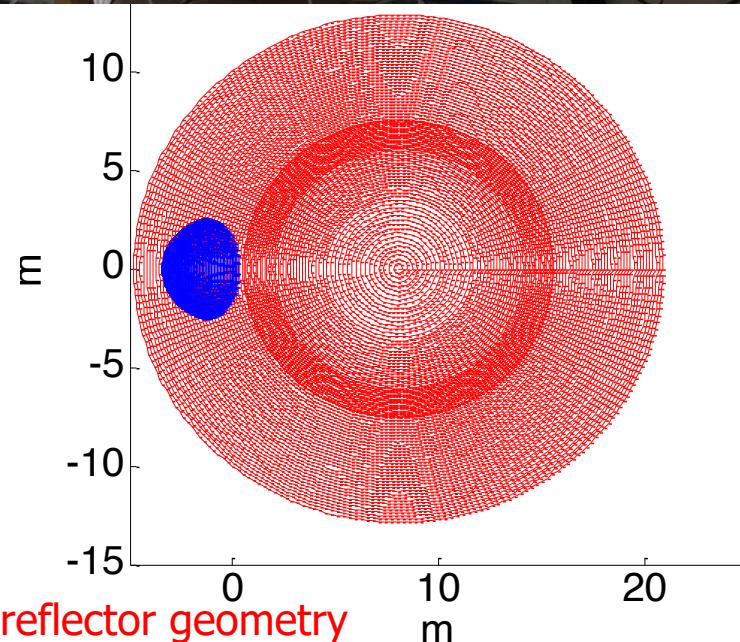
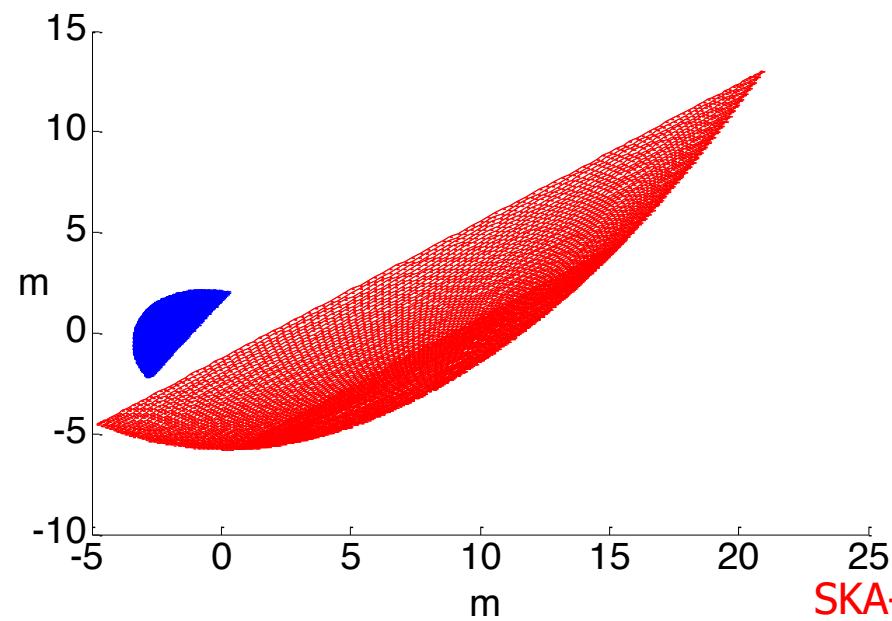
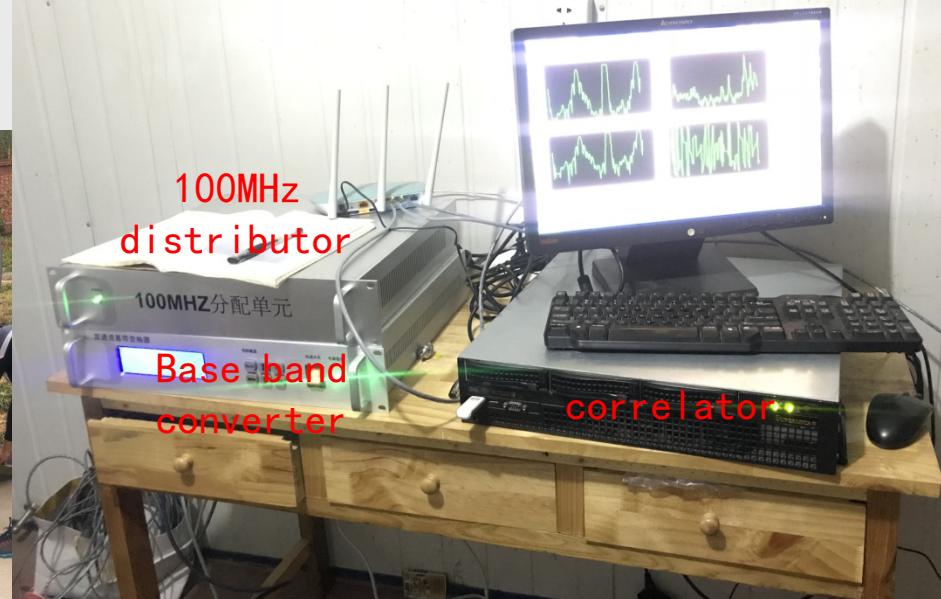
SKA-P at CETC54



Ref antenna

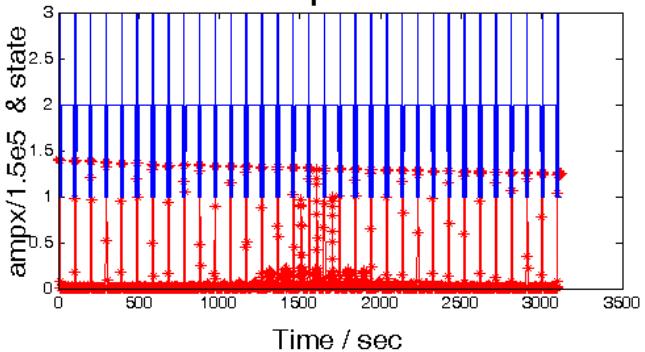


SKA-P holography equipments in prefab hourse

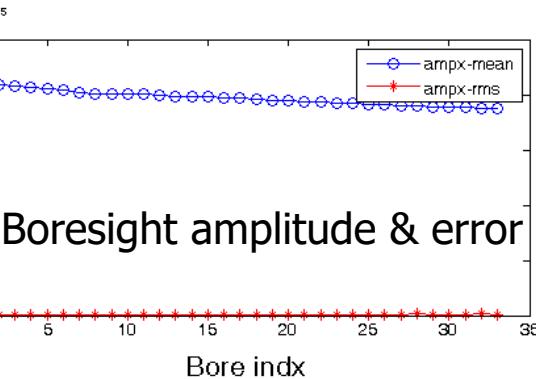
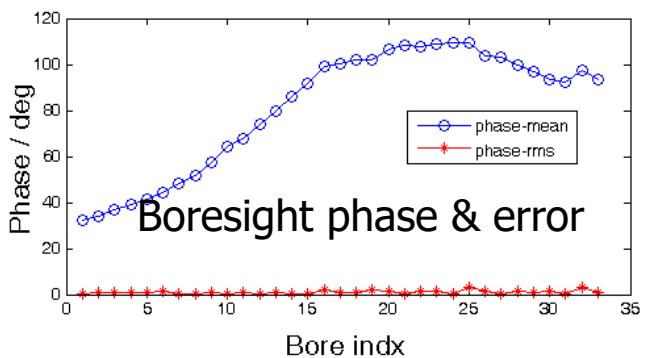
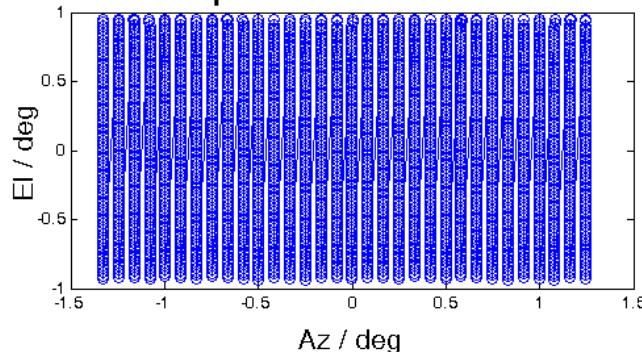


# SKA-P holography data calibration

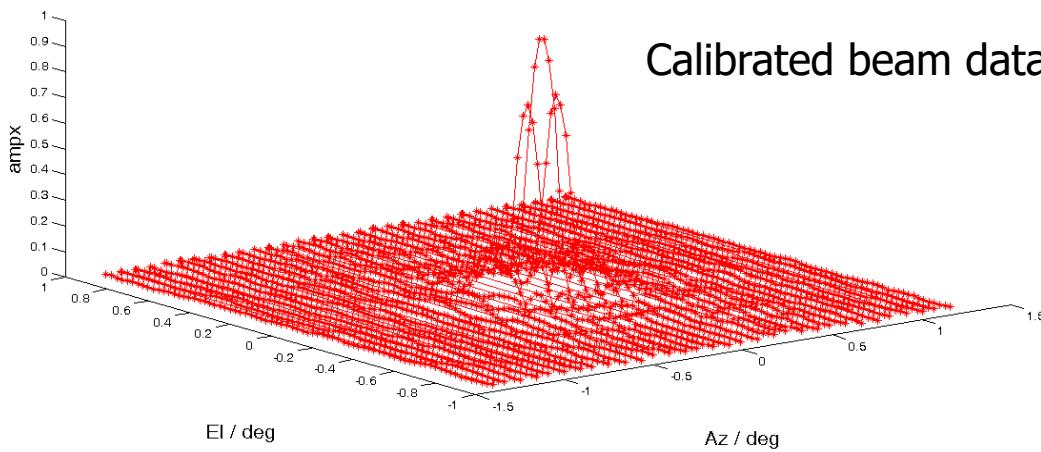
Scans amplitude and state



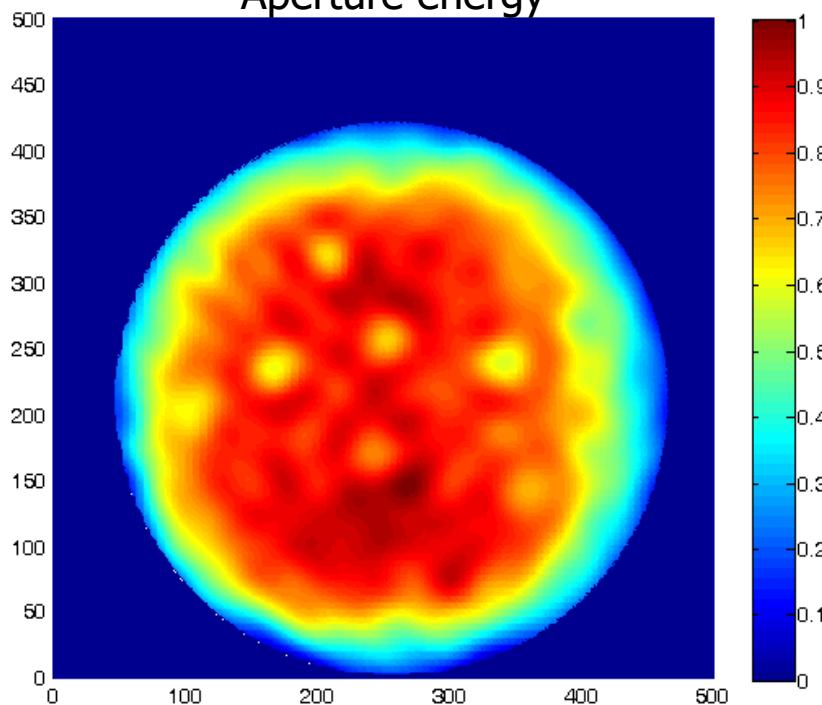
Scans position az & el



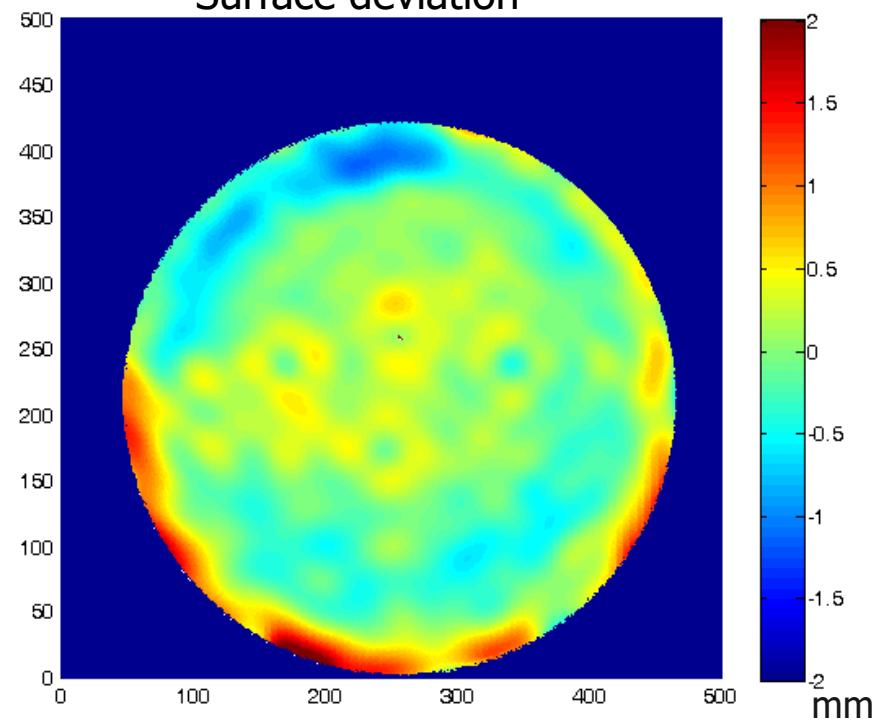
Calibrated beam data



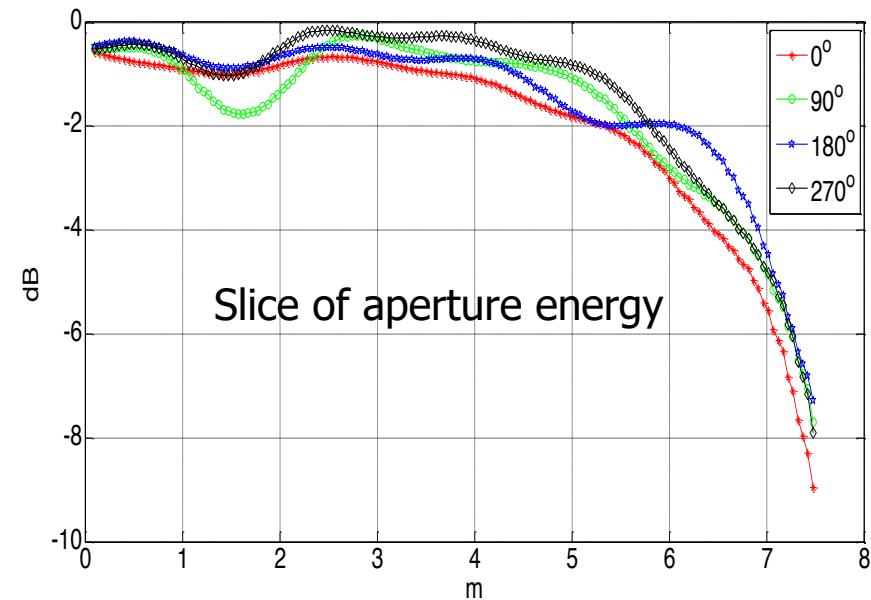
### Aperture energy



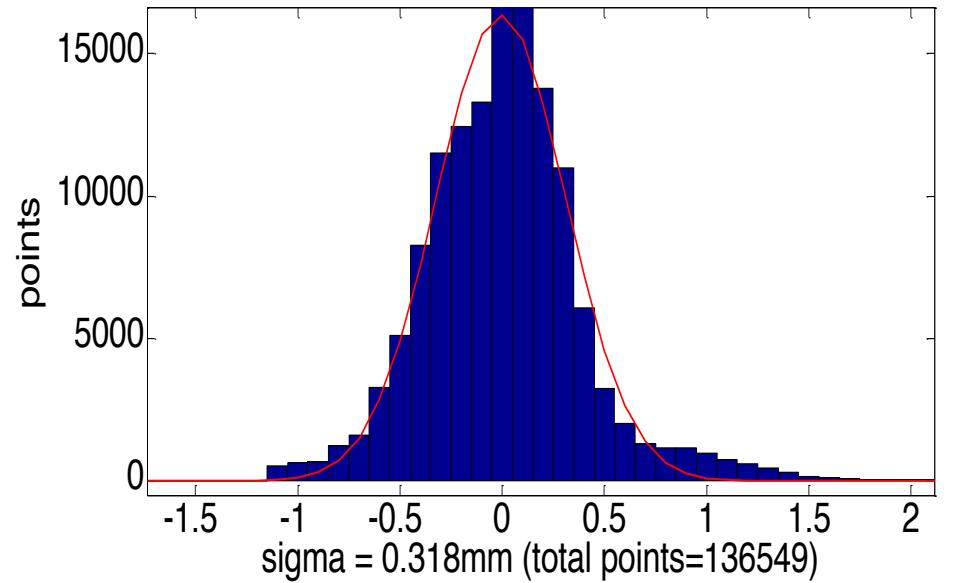
### Surface deviation



### Slice of aperture energy



points



# SKA holography and outputs information

## Holography steps:

- 1) Geostationary satellite holography at best elevation for panels setting better than 0.3mm rms (room temperature receiver, early time)
- 2) CE4 Ralay star (Earth moon 2<sup>nd</sup> Lagrange point) holography for entire elevation gravity deformantion, the star will be on service more than 10 years (room temperature receiver, early time)
- 3) Strong radio source holography for entire elevation gravity deformantion (cooled receiver installed)

## Holography outputs:

- 1) Surface accuracy: **panel setting**
- 2) Gravity deformation model: design evaluation
- 3) Sub-reflector best position model: **sub-reflector position adjustment**
- 4) Elevation axis offset: design evaluation
- 5) Gain and efficiency estimate: design evaluation

# Summary

- ◆ Pointing model & separation:  
industrial metrology applied, such as PSD, temperature sensor, tiltmeter, etc.
- ◆ Sub\_reflector position model:  
based on amplitude detection method
- ◆ Antenna performance measurement:  
based on calibrated noise diode
- ◆ Surface measurement by holography:  
surface error, gravity deformation model, sub-reflector position model base on aperture phase

Kunming40m



Miyun50m



Sheshan25m



Tianma65m



Seshan13m



Tianma13m



SKA-P 15m





*Thanks for your attention!*