

OPTIMISATION & AI FOR IMAGE FORMATION IN THE SKA ERA

Professor Yves Wiaux, BASP research group Head, Heriot-Watt Edinburgh

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- ☛ THE IMAGE FORMATION CHALLENGE
- ☛ THE HYBRID OPTIMISATION & AI ALGORITHMS
- ☛ ALGORITHM VARIATIONS AND REAL DATA

THE IMAGE FORMATION CHALLENGE

Aperture synthesis by radio interferometry provides access to high resolution but forming an image \mathbf{x} from visibility data \mathbf{y} is an **ill-posed inverse problem**.

- ▶ The combination of correlations between all antenna pairs across the observation time provides **an incomplete Fourier sampling of the sky**:
- ▶ Forward Model:

$$\mathbf{y} = \Phi \mathbf{x} + \mathbf{n}$$

- ▶ **Reconstruction algorithms are needed**, leveraging a prior image model to regularise and solve the problem:

$$\mathbf{y} \rightarrow \mathbf{x}$$

- ▶ Accurate models needed for **precision**
- ▶ Calibration functionalities needed for **robustness**

SKA will target new resolution and sensitivity regimes, leading to **EB data volumes** and **PB wideband image sizes**.

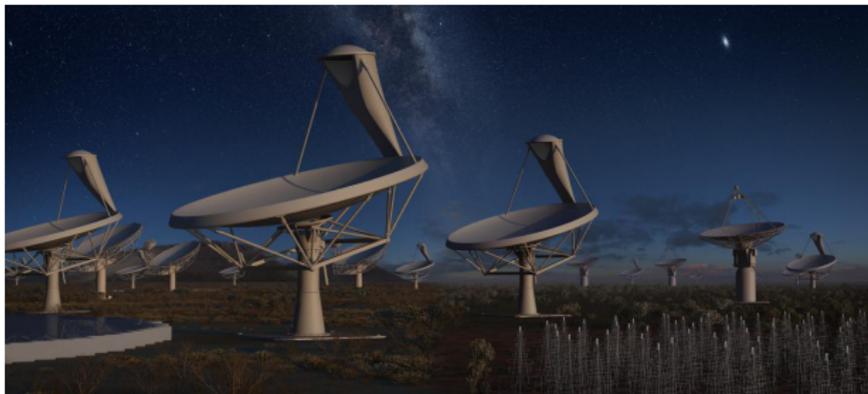


Image credit SKA organisation

- ▶ Reconstruction algorithms must be scalable!
- ▶ State-of-the-art CLEAN algorithm is scalable but offers sub-optimal precision and robustness

THE HYBRID OPTIMISATION & AI ALGORITHMS

Convex optimisation provides a powerful framework to solve inverse problems via highly iterative algorithms.

$$\mathbf{x}^* \in \operatorname{argmin}_{\mathbf{x}} \left\{ g(\mathbf{x}; \mathbf{y}) = f(\mathbf{x}; \mathbf{y}) + r(\mathbf{x}) \right\}$$

- ▶ $f(\mathbf{x}; \mathbf{y})$: convex data-fidelity term; $r(\mathbf{x})$: convex regularisation term

VERSATILE THEORY:

- ▶ Provides **convergence guarantees** for robustness
- ▶ Allows **advanced regularisation** for precision
- ▶ Provides **parallel algorithmic structures** for scalability
- ▶ **Generalizes to nonconvex optimisation** for robust calibration
- ▶ **Generalises to learned regularisation** for precision and scalability

The Forward-Backward (FB) algorithmic is a versatile and powerful optimisation structure for imaging.

- ▶ $f(\mathbf{x}; \mathbf{y})$, differentiable: e.g. $\|\mathbf{y} - \Phi\mathbf{x}\|_2^2$ (Gaussian noise)
- ▶ $r(\mathbf{x})$, differentiable or not: e.g. $\|\Psi\mathbf{x}\|_1$ (sparsity), $\ell_{\mathbb{R}_+^N}$ (positivity)
- ▶ Iteration structure (reminiscent of, but much more general than, CLEAN):

$$\mathbf{x}^{(t)} = \text{prox}_r \left(\mathbf{x}^{(t-1)} + \mu \Phi^\dagger (\mathbf{y} - \Phi \mathbf{x}^{(t-1)}) \right)$$

- ▶ Regularisation operator prox_r is an image denoiser

The Plug-and-Play Forward-Backward (PnP-FB) is an AI variant enabling to learn the regularisation model.

- ▶ $f(\mathbf{x}; \mathbf{y})$, differentiable: e.g. $\|\mathbf{y} - \Phi\mathbf{x}\|_2^2$ (Gaussian noise)
- ▶ The regularisation denoiser is learnt and embedded in a **DNN**, rather than handcrafted
- ▶ **Iteration structure:**

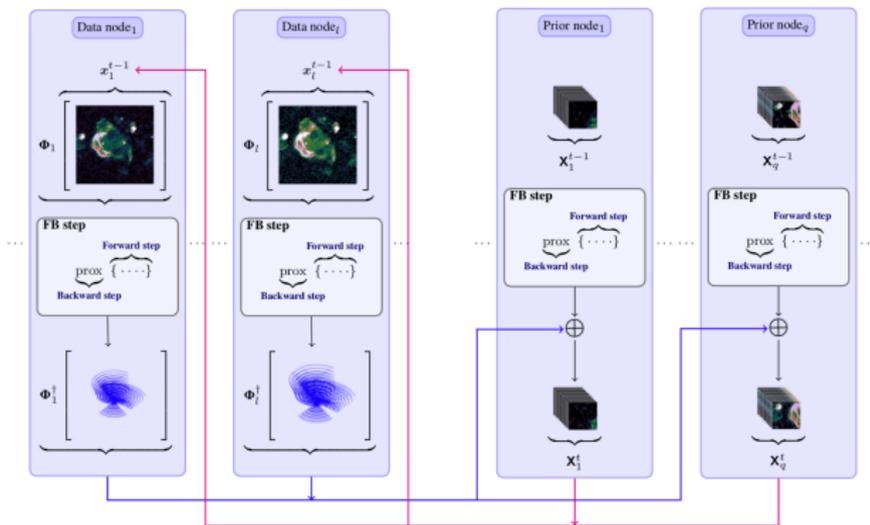
$$\mathbf{x}^{(t)} = \text{DNN} \left(\mathbf{x}^{(t-1)} + \mu \Phi^\dagger (\mathbf{y} - \Phi \mathbf{x}^{(t-1)}) \right)$$

- ▶ Learning enables more **physical regularisation** for precision
- ▶ The DNN is typically much **faster** than complicated prox_r operators

ALGORITHM VARIATIONS AND REAL DATA

Parallel FB deployed on an HPC system to jointly calibrate 7.4GB of VLA data and produce a **15GB wideband image of Cygnus A, with exquisite precision.**

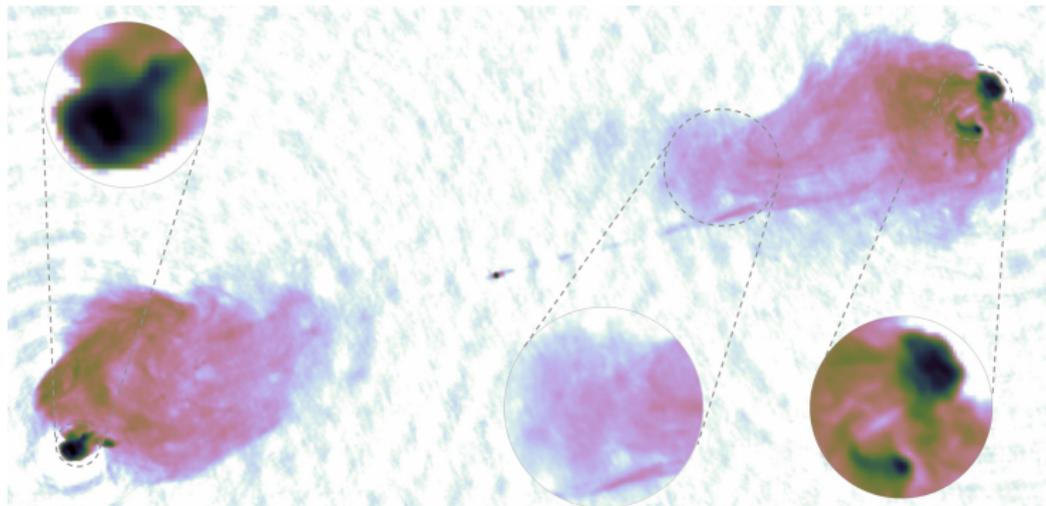
► Distributed implementation structure



Thouvenin et al., arXiv:2003.07358; Dabbech et al., arXiv:2102.00065

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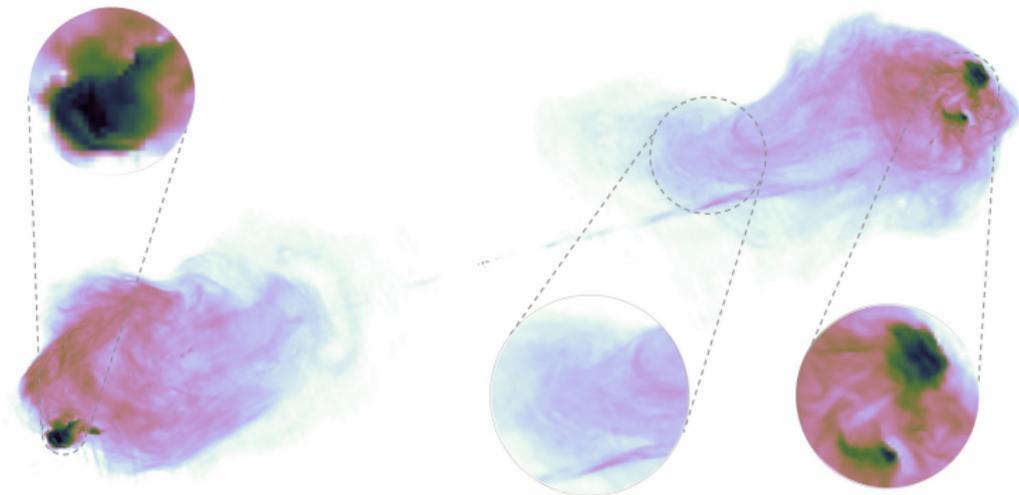
► CLEAN imaging



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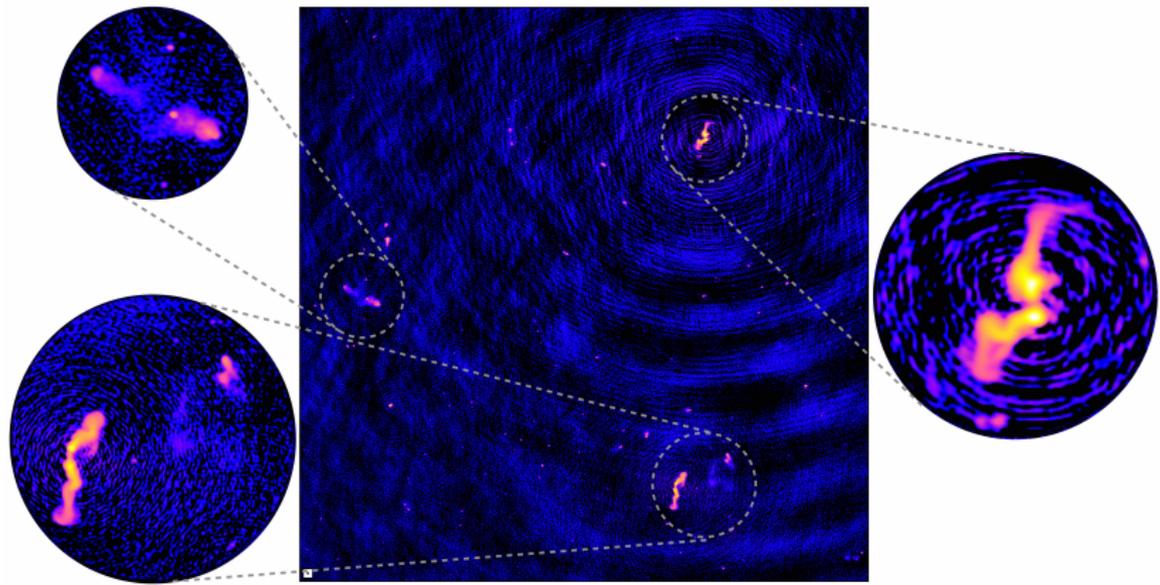
► FB imaging



Thouvenin et al., arXiv:2003.07358; Dabbech et al., arXiv:2102.00065

Parallel FB deployed to process widefield ASKAP data.

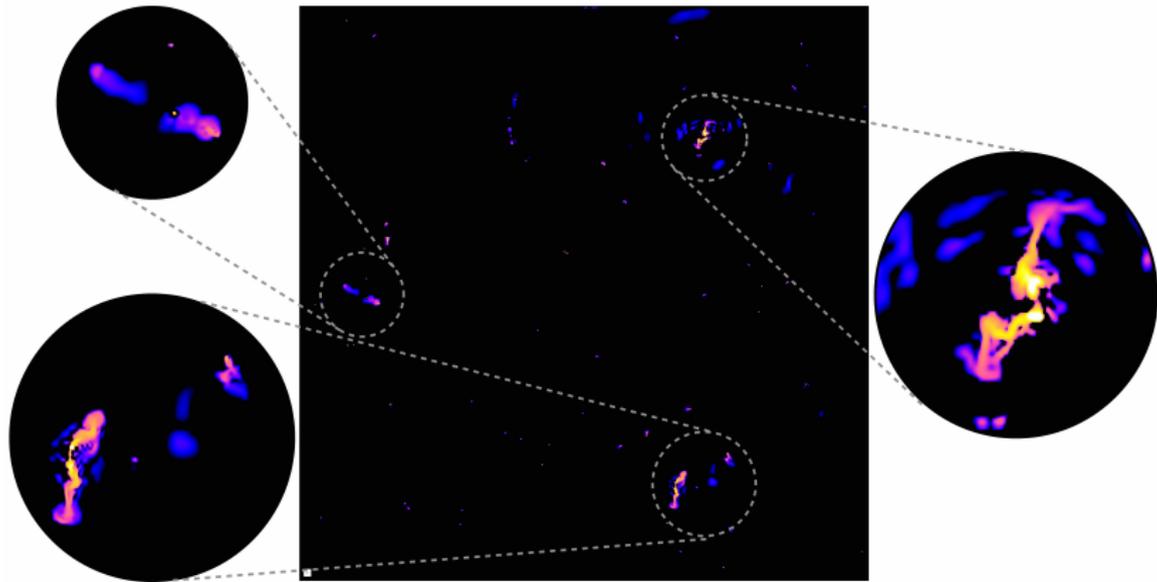
- ▶ Merging system Abell 3391/95: CLEAN imaging (0.3GB data)



Dabbech, Wilber et al., in prep.

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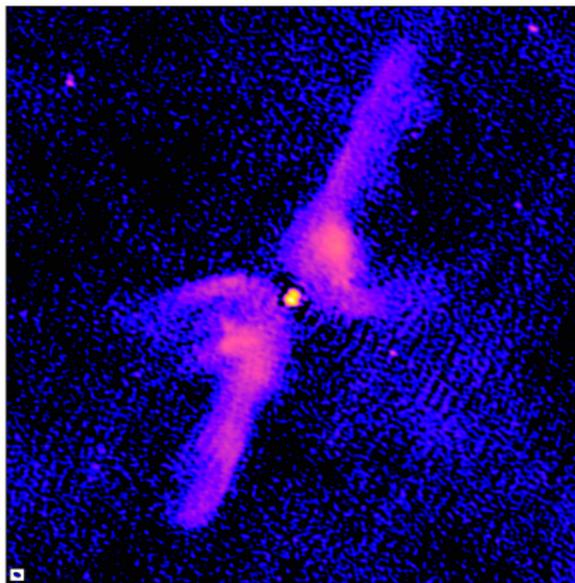
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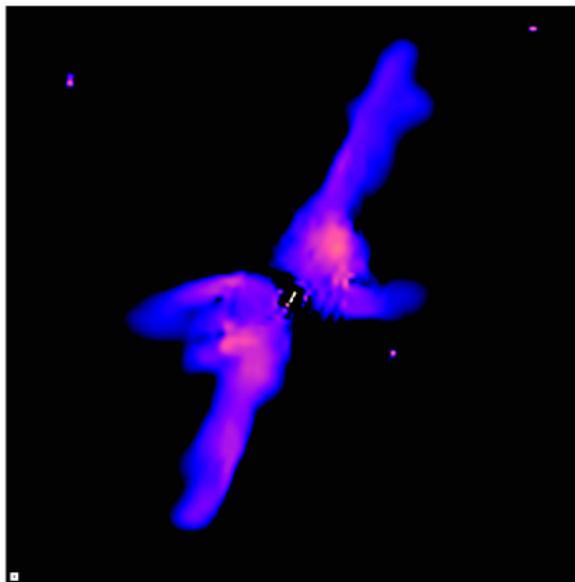
- ▶ X-shaped radio galaxy PKS 2014-55: CLEAN imaging (1GB data)



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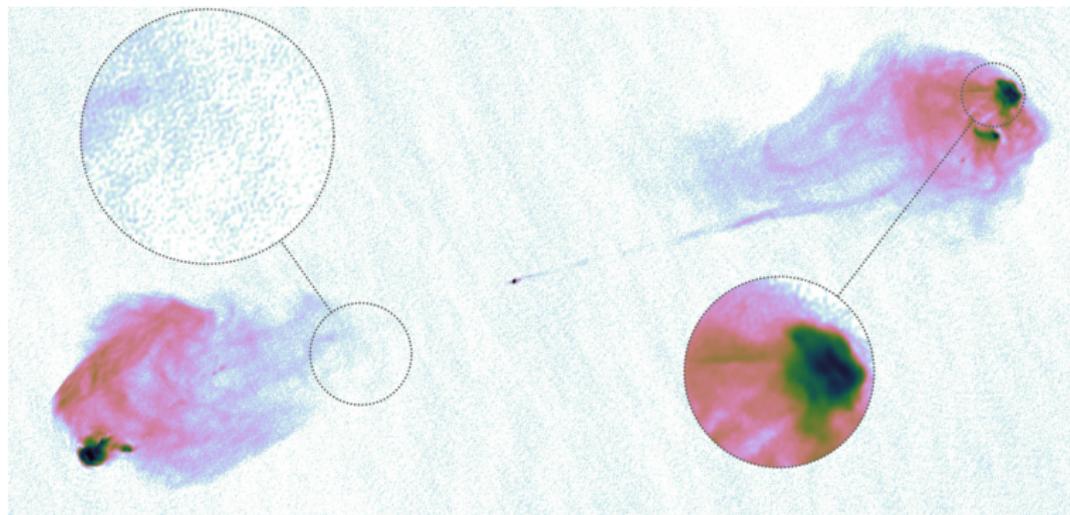
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DNN trained on high dynamic range dataset and PnP-FB deployed for Cygnus A imaging (simulation): **22-fold acceleration** vs. FB for similar precision.

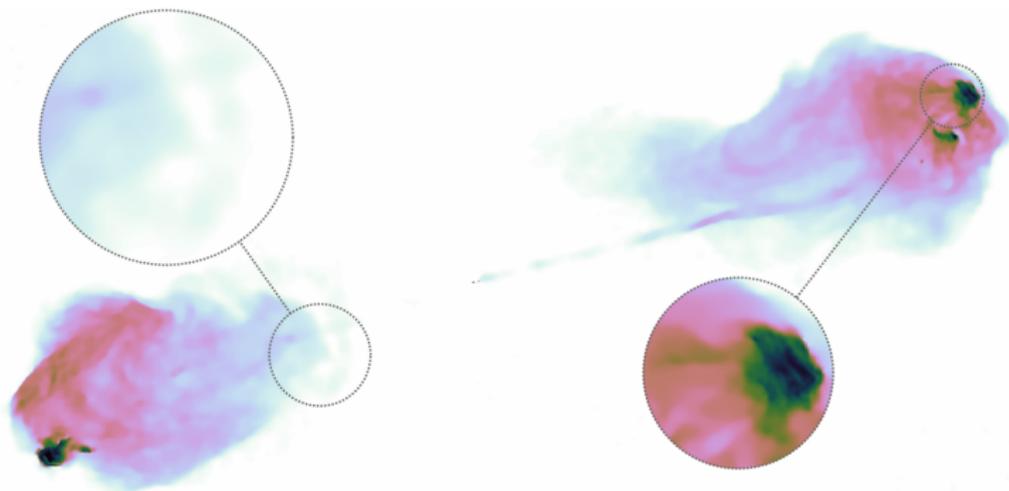
► CLEAN imaging



Terris et al., arXiv:2012.13247 (+ arXiv in prep.)

DNN trained on high dynamic range dataset and PnP-FB deployed for Cygnus A imaging (simulation): **22-fold acceleration** vs. FB for similar precision.

► PnP-FB imaging



Terris et al., arXiv:2012.13247 (+ arXiv in prep.)

WE ARE RECRUITING...