

Fast, Scalable and Accurate Wide-Field (De)Gridding via the 3D NUFFT

Swiss SKA Days 2022

Matthieu Simeoni, Joan Rue Queralt, Sepand Kashani

October 4, 2022

EPFL

Analysis and Synthesis for Imaging Purposes

Analysis (a.k.a. **gridding**) and **synthesis** (a.k.a. **degridding**) are used in radio interferometry to accurately predict **visibilities** (resp. **dirty images**) from a given **sky distribution** (resp. **visibility set**):

$$\left(V_i = \sum_{r \in \Theta_{\text{pix}}} I(r) e^{-j\langle r, p_i \rangle} \right)_{i=1, \dots, N_{\text{vis}}} \quad \& \quad \left(I_D(r) = \frac{1}{N_{\text{vis}}} \sum_{i=1}^{N_{\text{vis}}} V_i e^{j\langle r, p_i \rangle} \right)_{r \in \Theta_{\text{pix}}} .$$

Direct evaluation of the above expressions has **bi-linear complexity** $\mathcal{O}(N_{\text{vis}} N_{\text{pix}})$ which represents a **major bottleneck** for imaging purposes:

- **CLEAN** performs **one analysis and synthesis per major cycle**.
- **Proximal algorithms** typically perform **one analysis and synthesis per iteration**.

The (**numerous!**) analysis and synthesis steps tend to dominate the overall **computational complexity** of the imaging task.

We therefore need **fast, scalable** and yet **accurate** analysis and synthesis algorithms.

Fast Synthesis Algorithms

Let us focus on the synthesis step.¹

Assuming that the image is defined over a **regular grid** in **direction cosines coordinates** $(\ell, m) \in \mathbb{R}^2$, the latter can be expressed as:

$$\left(I_D(\ell, m) = \frac{1}{N_{\text{vis}}} \sum_{i=1}^{N_{\text{vis}}} V_i e^{j(\ell u_i + m v_i + n(\ell, m) w_i)} \right)_{(\ell, m) \in \Omega_{\text{pix}}}$$

where $n(\ell, m) := \sqrt{1 - \ell^2 - m^2} - 1$ and $(u_i, v_i, w_i) \in \mathbb{R}^3$ the (normalised) baselines' **uvw-coordinates**.

Resembles very much a **partial Fourier transform**, although with non-uniform frequencies $(u_i, v_i, w_i) \in \mathbb{R}^3$ and spatial coordinates evolving on a manifold. Can we leverage the **FFT** to achieve **log-linear complexity**?

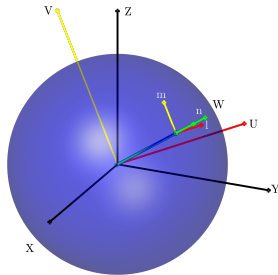


Figure: Direction cosines and uvw -coordinates.

¹Since analysis and synthesis are adjoint operations, any (linear) evaluation algorithm obtained for the synthesis step can be used for the analysis step by simply reversing the chain of operations involved.

Fast Synthesis Algorithms (continued)

Two cases:

Small FOV: $n(\ell, m) \approx 0 \Rightarrow$ we can neglect the w -term, yielding

$$I_D(\ell, m) = \frac{1}{N_{\text{vis}}} \sum_{i=1}^{N_{\text{vis}}} V_i e^{j(\ell u_i + m v_i)}.$$

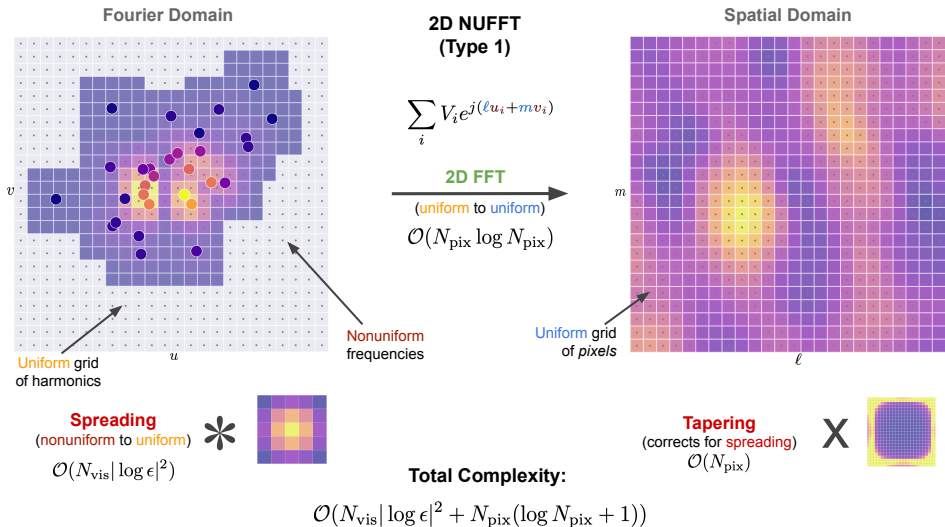
Since the direction cosine coordinates are uniformly chosen, we can then use a 2D **Non Uniform FFT (NUFFT) of Type 1** to evaluate the sum.

Large FOV: $n(\ell, m) \neq 0 \Rightarrow$ **much harder!** Many algorithms proposed: **image faceting, W-projection, W-snapshot, W-stacking, W-gridding, etc.**

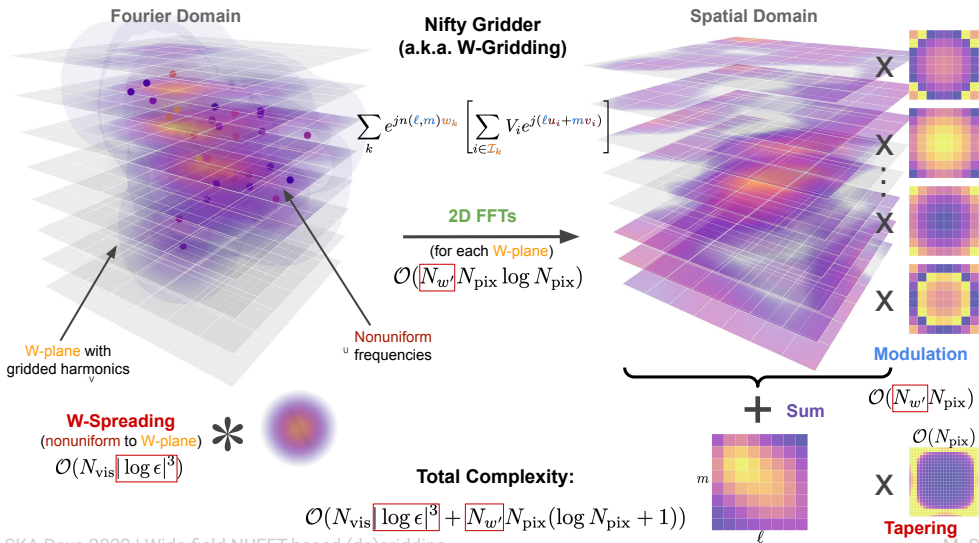
Most used is probably **w-stacking** which proposes to **cluster the baseline w coordinates** in N_w planes, each processed independently by a **2D NUFFT and a modulation before being summed:**

$$I_D(\ell, m) = \frac{1}{N_{\text{vis}}} \sum_{k=1}^{N_w} e^{j(n(\ell, m)w_k)} \left(\sum_{i \in P_k} V_i e^{j(\ell u_i + m v_i)} \right).$$

Standard Gridding



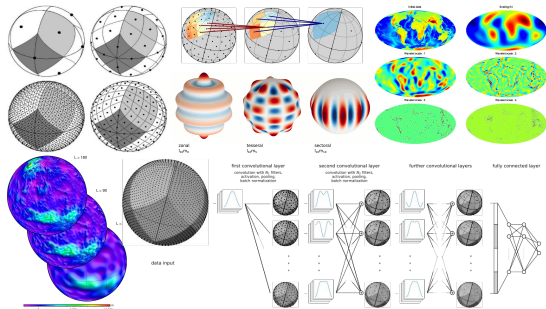
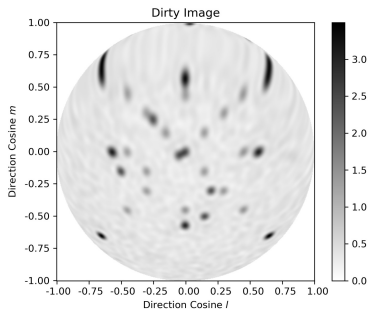
Nifty Gridder (a.k.a. W-gridding)



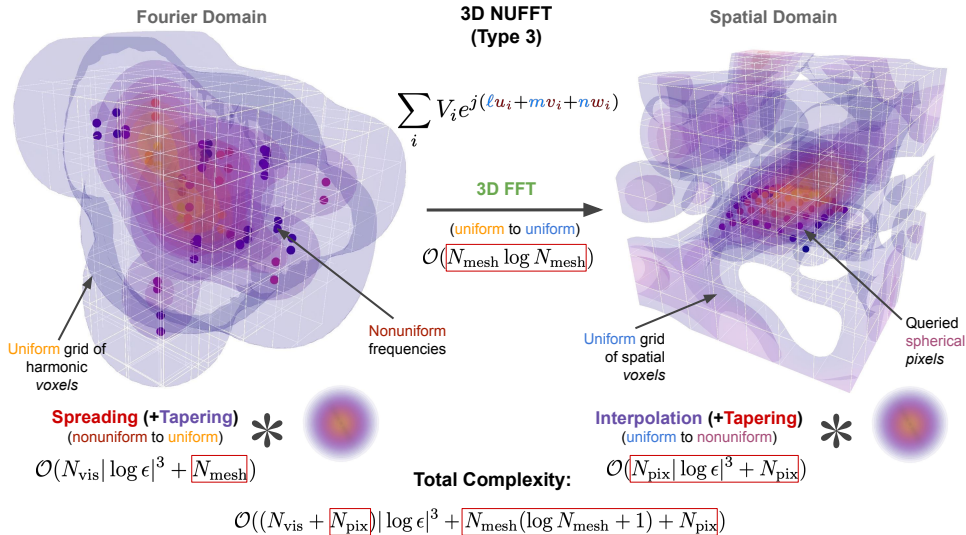
Limitations of Direction Cosine Grids

Current gridding techniques **achieve log-linear complexity**, but **only for direction cosine meshgrids**. The latter are **ill-suited for large FOVs** due to **heavily distorted** or **singular/non-feasible pixels** away from the center. This significantly **complicates** (if not *forbids*) the use of traditional **image processing** and **image analysis** tools.

In contrast the **HEALPix mesh** is tailored to spherical images, and **readily supports Fourier and wavelet analysis, filtering, CNNs for inference/classification, pattern recognition, noise analysis** and more.



Gridding via the 3D NUFFT of Type 3



Scaling up via Chunked NUFFT Gridding

The NUFFT of Type 3 performs a **single 3D FFT with critical size**:

$$N_{\text{mesh}} \propto (u_{\text{max}} v_{\text{max}} w_{\text{max}}) \times (\ell_{\text{max}} m_{\text{max}} n_{\text{max}})$$

To help reduce down the FFT sizes, we propose **partitioning** the ***uvw*** and **image domains** in **chunks**:

$$\sum_{C \in \mathcal{P}} \sum_{i \in C} V_i e^{j(\ell u_i + m v_i + n w_i)}$$

In the ***uvw*** domain, the partitioning is performed via a **quadtree** to ensure similar workloads in each chunk.

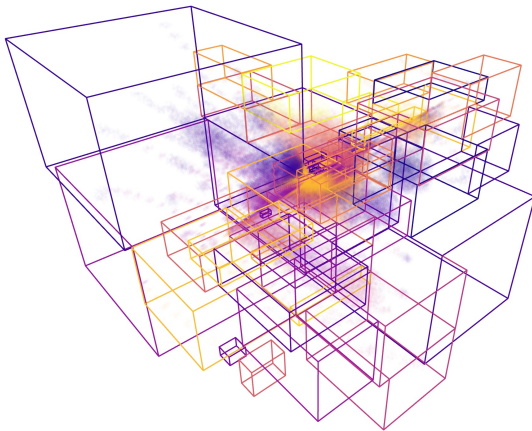
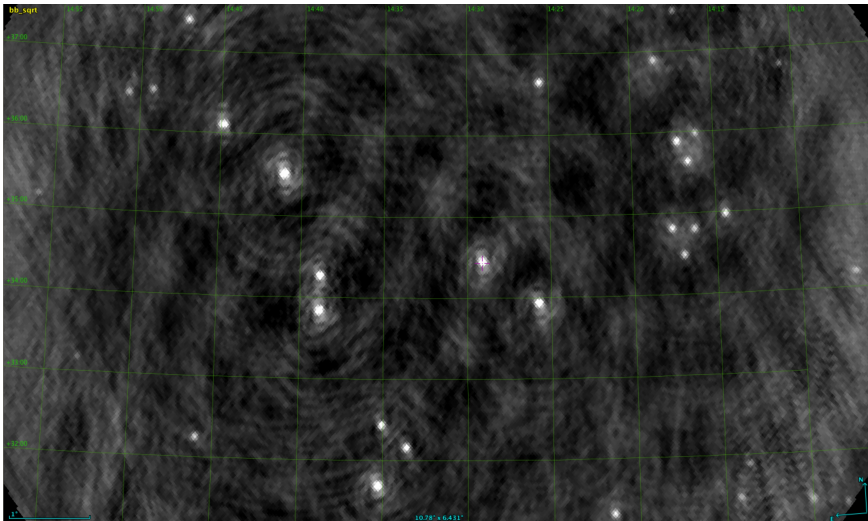
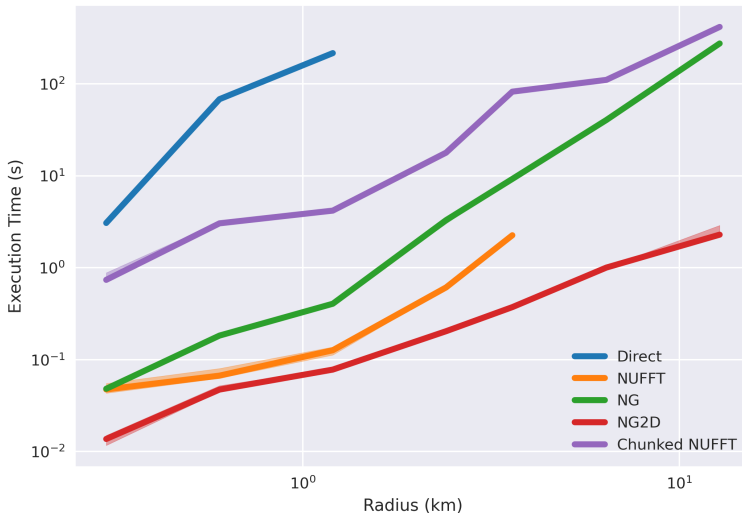


Figure: Quadtree partitioning in the *uvw* domain.

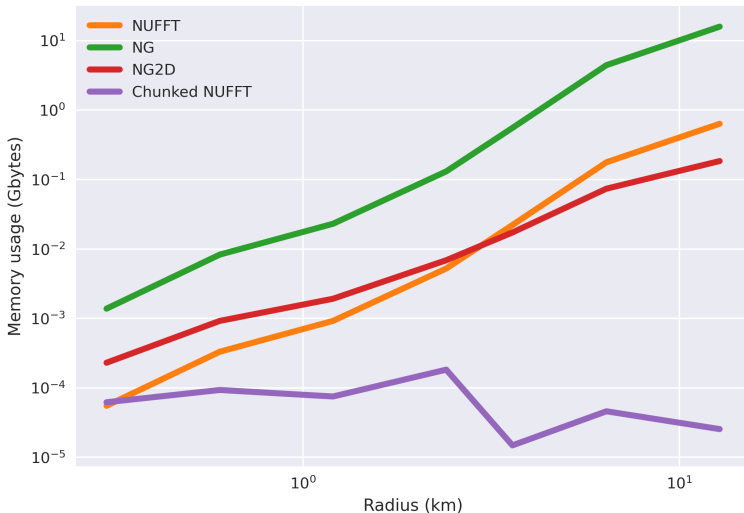
HEALPix Synthesis via the 3D NUFFT of Type 3



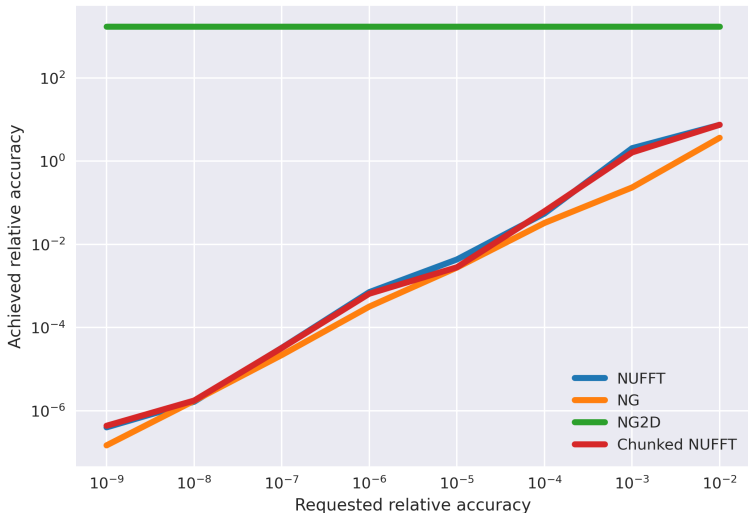
Benchmarking: Execution Time (SKA-LOW, 30°)



Benchmarking: Memory Usage (SKA-LOW, 30°)



Benchmarking: Relative Accuracy (SKA-LOW, 30° , $r_{\max} = 600m$)



Conclusion

We have proposed the **NUFFT gridder**, a new wide-field (de)gridding algorithm for radio interferometry with:

- support for **arbitrary spherical meshes** (including **HEALPix**),
- **similar accuracy** but **faster** than the **Nifty gridder** (s.o.a),
- **good scaling behaviour** thanks to a chunking strategy (opens up the way to **stochastic optimisation** too...).

Next steps:

- **release** the NUFFT gridder as an **extension to RASCIL**,
- fix issues related to **unmanaged memory** encountered in very large setups,
- submit paper (**on the way**),
- **deploy and test** in a production environment,
- extend the algorithm to support **A-terms** and compare to **Image Domain Gridding (IDG)**.