FIRST AI FOR DEEP SUPER-RESOLUTION WIDE-FIELD IMAGING IN RADIO ASTRONOMY:

unveiling structure in ESO 137-006

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# RI IMAGING CHALLENGE IN THE SKA ERA





Aperture synthesis by radio interferometry provides access to high resolution high dynamic range. But forming an image x from visibility data y is an ill-posed inverse problem.

Data model: incomplete Fourier sampling of the sky:

$$y = \Phi x + n$$

Reconstruction algorithms are needed, leveraging a prior image model to regularise and solve the problem:

$$m{y} 
ightarrow m{x}$$

Accurate models needed for precision





# The Square Kilometre Array

SKA will target unprecedented resolution and sensitivity regimes, leading to EB data volumes and PB wideband image sizes.



Image credit SKA organisation

- Reconstruction algorithms must be scalable
- CLEAN is scalable but sub-optimal and requires manual intervention





# PROPOSED AI FRAMEWORK FOR DEEP SUPER-RESOLUTION WIDE-FIELD RI IMAGING

Terris et al., MNRAS accepted, arXiv:2202.12959 Dabbech et al., ApJL submitted, arXiv:2207.11336





Convex optimisation provides a powerful framework to solve inverse problems via highly iterative algorithms.

$$\mathbf{x}^{\star} \in \operatorname*{argmin}_{\mathbf{x}} \Big\{ g(\mathbf{x}; \mathbf{y}) = f(\mathbf{x}; \mathbf{y}) + r(\mathbf{x}) \Big\}$$

•  $f(\mathbf{x}; \mathbf{y})$ : data-fidelity term;  $r(\mathbf{x})$ : regularisation term

VERSATILE THEORY:

- Provides iterative algorithms with convergence guarantees
- Allows advanced regularisation for precision
- Provides parallel algorithmic structures for scalability





The Forward-Backward (FB) algorithm is a simple and flexible optimisation structure.

$$\mathbf{x}^{\star} \in \operatorname*{argmin}_{\mathbf{x}} \Big\{ g(\mathbf{x}; \mathbf{y}) = f(\mathbf{x}; \mathbf{y}) + r(\mathbf{x}) \Big\}$$

• f(x; y): differentiable; r(x): differentiable or not

Iteration structure: (reminiscent of, but more general than, CLEAN)

$$\boldsymbol{x}^{(i)} = \operatorname{prox}_{r} \left( \boldsymbol{x}^{(i-1)} - \gamma \nabla f \left( \boldsymbol{x}^{(i-1)} \right) \right)$$

- $\checkmark\,$  forward gradient descent data-fidelity step
- $\checkmark$  backward regularisation step involving  $\mathrm{prox}_r$
- $\checkmark$  the proximal operator  $\mathrm{prox}_r$  is an image denoiser





Unconstrained SARA leverages FB with handcrafted regularisation for monochromatic intensity imaging.

- Data fidelity term:  $f(\mathbf{x}, \mathbf{y}) = ||\mathbf{y} \mathbf{\Phi}\mathbf{x}||_2^2$  (Gaussian noise)
- Regularisation term: log-sum prior (generalising l<sub>1</sub>) promoting average sparsity in a redundant wavelet dictionary

$$\mathbf{r}(\mathbf{x}) = \eta \sum_{n=1}^{B} \rho \log \left( 1 + \rho^{-1} \left| \left( \mathbf{\Psi}^{\dagger} \mathbf{x} \right)_{n} \right| \right) + \iota_{\mathbb{R}^{N}_{+}}(\mathbf{x})$$

Iteration structure:

$$\boldsymbol{x}^{(i)} = \operatorname{prox}_{\boldsymbol{r}} \left( \boldsymbol{x}^{(i-1)} + \gamma \boldsymbol{\Phi}^{\dagger} \left( \boldsymbol{y} - \boldsymbol{\Phi} \boldsymbol{x}^{(i-1)} \right) \right)$$

SARA's proximal operator is sub-iterative





# AI for Regularisation in Imaging (AIRI)

AIRI leverages FB, plugging a learned DNN denoiser in lieu of a proximal operator for monochromatic intensity imaging (plug-and-play approach).

- ► Data fidelity term:  $f(\mathbf{x}, \mathbf{y}) = ||\mathbf{y} \mathbf{\Phi}\mathbf{x}||_2^2$  (Gaussian noise)
- Regularisation term: implicitly defined by a learned DNN denoiser
- Requires tailored training approach to ensure algorithm convergence
- Iteration structure:

$$\mathbf{x}^{(i)} = \mathsf{DNN}\left(\mathbf{x}^{(i-1)} + \gamma \mathbf{\Phi}^{\dagger} \left(\mathbf{y} - \mathbf{\Phi}\mathbf{x}^{(i-1)}\right)\right)$$

Learning opens the door to powerful physical regularisation

DNNs provide acceleration over sub-iterative proximal operators





# Fully parallesised and scalable AI framework for RI

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The algorithmic framework is parallelised both in its forward and backward steps, to run on high performance computing hardware.



- Parallel denoising via image faceting
- Parallel gradient step via decomposition of Φ<sup>†</sup>Φ into sparse and low-dimensional blocks
- Parallelisation degree automated depending on hardware





# REVISITING ESO137-006 FROM MEERKAT DATA

Dabbech et al., ApJL submitted, arXiv:2207.11336





Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

WSClean (1.4GHz; 4k x 4k image; 11GB data; compute cost: 236 CoreH; precision: instrument resolution)







Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

uSARA (1.4GHz; 4k x 4k image; 11GB data; compute cost: 2377 CoreH; precision: super-resolved)







Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

AIRI (1.4GHz; 4k × 4k image; 11GB data; compute cost: 1028 CoreH; precision: further super-resolved, improved dynamic range)







#### Conclusion

Al opens the door to further precision and scalability in RI imaging

Ongoing evolutions beyond first uSARA & AIRI incarnations

- $\checkmark\,$  Investigate advanced denoisers: architectures, databases, losses
- $\checkmark$  Add wideband, polarisation, calibration functionalities
- ✓ Translate current Matlab code into C++ (Puri-Psi)
- ✓ Application to ASKAP data (2 articles in prep.)
- $\checkmark\,$  Application to EHT VLBI data

[We are hiring at PhD, postdoc., and Assist. Prof. level]





Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

WSClean (1.05GHz; 4k × 4k image; 8.2GB data; compute cost: 132 CoreH; precision: instrument resolution)







Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

uSARA (1.05GHz; 4k x 4k image; 8.2GB data; compute cost: 1120 CoreH; precision: super-resolved)







Wide-field imaging of ESO137-006 with MeerKAT data (Collab. SARAO).

AIRI (1.05GHz; 4k × 4k image; 8.2GB data; compute cost: 480 CoreH; precision: further super-resolved, improved dynamic range)





